# PL IWOLUTONS ON LPMS SPACES AND ONHER 3-MANHOLDS 

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# PL INVOLUTIONS ON <br> LENS SPACES AND OTHER 3-MANIFOLDS 

By<br>Paik Kee Kim

AN ABSTRACT OF A DISSERTATION

Submitted to
Michigan State University
in partial fulfillment of the requirements for the degree of

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# ABSTRACT <br> PL INVOLUTIONS ON <br> LENS SPACES AND OTHER 3-MANIFOLDS 

By

Paik Kee Kim

This thesis is to complete the classification problem for sense preserving PL involutions with non-empty fixed point sets on 3-dimensional lens spaces $L=L(p, q)$. The classification problem for PL involutions on the projective 3-space $P^{3}$ as well as that for $P L$ involutions on $P^{3} \# P^{3}$ will be settled. The principal results are the following theorems.

Theorem l: If $h$ is an orientation preserving PL involution on $L(p, q)$, $p$ even, which preserves sense and has non-empty fixed point set $F$, then $F$ is a disjoint union of two simple closed curves.

Theorem 2: Up to PL equivalences, there is exactly one orientation preserving PL involution on $L(p, q), p$ even, which preserves sense and has non-empty fixed point set.

Corollary 3: Up to PL equivalences, there is exactly one orientation preserving $P L$ involution on $P^{3}$ with nonempty fixed point set and there is exactly one free involution on $p^{3}$.

## Paik Kee Kim

Theorem 4: Let $h$ be an orientation preserving PL involution on a lens space $L=L(p, q)$, $p$ even, which preserves sense and has non-empty fixed point set. Then there exists a PL equivariant homeomorphism $t$ on $L$ such that $t$ interchanges the two components of Fix (h) if and only if $L$ is symmetric.

Corollary 5: Let $h$ be an orientation preserving PL involution on $P^{3} \# P^{3}$. If $F i x(h)=\varnothing$ or Fix (h) is connected, $h$ is the obvious involution which interchanges the two $P^{3}$. If Fix (h) is not connected, Fix (h) is a disjoint union of three simple closed curves and there is exactly one such $h$, up to $P L$ equivalences.

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To my mother and Myung

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## INTRODUCTION

An involution $h$ of a lens space $L=L(p, q)$ is called sense preserving if $h$ induces the identity of $H_{1}(L)$. The purpose of this thesis is to classify the orientation preserving PL involutions of $L$ which preserve sense and have non-empty fixed point sets for $p$ even. As results, this thesis will lead a complete classification of the $P L$ involutions on the projective 3 -space $P^{3}$ as well as that of the $P L$ involutions on $P^{3} \# P^{3}$.

We work in the piecewise linear (PL) category. All PL involutions are known on $S^{3}$ (see Livesay [5,6] and Waldhausen [20]) and on $s^{1} \times s^{2}$ (see Fremon [3]. Kwun [8], Tao [18], and Tollefson [19]). Therefore, in this thesis we will not consider $S^{3}$ and $S^{1} \times S^{2}$ as lens spaces. Kwun [9,10] classified all orientation reversing PL involutions of $L$ and all orientation preserving $P L$ involutions of $L(p, q)$, $p$ odd, which preserve sense and have non-empty fixed point sets. The classification problem of the (sense preserving) free involutions on $L(p, q), p>2)$, is still open, but the problem on $P^{3}$ will be solved by using Rice's work [15]. It will be shown that, up to PL equivalences, there are exactly three PL involutions on $\mathrm{P}^{3}$.

Let $M_{i}(i=1,2)$ be oriented 3-manifolds and $h_{i}$ be involutions on $M_{i}$. If there is a suitable invariant 3-cell
in each $M_{i}$, by taking the connected sum $M_{1} \# M_{2}$, along the 3-cells, one can define an involution, denoted by $h_{1} \# h_{2}$, on $M_{1} \# M_{2}$ induced by $h_{1}$ and $h_{2}$. The connected sum $M_{1} \# M_{2}$ is obtained by removing the interior of a nice invariant 3 -cell from each, and then matching the resulting boundaries using an orientation reversing equivariant homeomorphism. Notice that $h_{1} \# h_{2}$ depends on the choice of the invariant 3-cells along whose boundaries the connected sum is constructed. All orientation reversing involutions on $L(p, q)$ \# $L(\bar{p}, \bar{q})$ are known ([7]. [13], [16]). We will also investigate some orientation preserving PL involutions on $L(p, q) \# L(\bar{p}, \bar{q})$. As a consequence, up to $P L$ equivalences, there are exactly seven $P L$ involutions on $P^{3} \# P^{3}$.

## CHAPTER I

FIXED POINT SETS

In this chapter we shall study the fixed point set of an orientation preserving involution on a lens space $L=L(p, q)$ which preserves sense and has non-empty fixed point set.

Lemma 1.1: Let $X$ be a m-manifold which has a contractible universal covering space. If $H_{l}(X)$ is of rank $\geq n$ and there is a short exact sequence $0 \rightarrow A \stackrel{f}{\rightarrow} \Pi_{1}(X) \underset{p}{G} Z_{p} \rightarrow 0$ where $A$ is a free abelian group of rank $n$, then $\Pi_{1}(X)$ is a free abelian group of rank $n$.

Proof: Let $\left\{a_{i}\right\}_{i}=1,2, \ldots, n$ be a basis for $A$. Since $f$ is a monomorphism, we simply identify $A$ with the image $f(A)$. Let $t$ be an element of $\Pi_{1}(X)$ such that $g(t)$ genenates $Z_{p}$. Then $\Pi_{1}(x)$ is generated by the $a_{i}$ and $t$. Denote the image of an element $e$ of $\Pi_{1}(x)$ by $\bar{e}$ under the natural homomorphism of $\Pi_{1}$ to $H_{1}$. Let $Q$ be the rationais. $H_{1}(X ; Q)=H_{1}(X) \otimes Q$ is generated by the $\overline{\mathrm{a}}_{i} \otimes 1$ and $\bar{t} \otimes 1$. Since $g\left(t^{p}\right)=0, \quad t^{p} \in A$, and $\overline{t^{p}}=p \bar{t}$ is generate by the $\bar{a}_{i}$ (notice that we shift from the multiplicatimon notation $t^{p}$ to the additive notation $p \bar{t}$ as $H_{1}(X)$ is abelian). Hence $p \bar{t} \otimes l \in\left\langle\left\{\bar{a}_{i} \otimes 1\right\}\right\rangle$ which is Q-submodale of $H_{1}(X) \otimes Q$ generated by the $\bar{a}_{i} \otimes 1$. Hence, $\bar{t} \otimes l \in\left\langle\left\{\bar{a}_{i} \otimes 1\right\}\right\rangle$, and $\left\langle\left\{\bar{a}_{i} \otimes 1\right\}\right\rangle=H_{1}(X) \otimes Q$. Since
$H_{l}(X) \otimes Q$ is a vector space over $Q$ of rank $\geq n, \quad\left\{\bar{a}_{i} \otimes l\right\}$ is a basis for $H_{1}(X) \otimes Q$. Since $A$ is a normal subgroup of $\Pi_{1}(x), t^{-1} a_{i} t=\prod_{j=1}^{n} a_{j}{ }_{j}$ for some $k_{j} s^{\prime}$. Abelianizing
 $k_{i}=1$ and $k_{j}=0$ if $j \neq i$. Therefore, $\Pi_{l}(X)$ is abelian. Since $O \rightarrow A \rightarrow \Pi_{1}(X) \rightarrow Z_{p} \rightarrow 0$ is exact and $Q$ is torsion free, $A \otimes Q=\Pi_{1}(X) \otimes Q$. Since $\Pi_{1}(X)$ is a finite$l y$ generated abelian group, $\Pi_{1}(X)$ is of rank $n$. But no non-trivial finite group can act freely on a finite dimensional contractible space (due to P.A. Smith [4]. 287). Therefore, $\Pi_{1}(X)$ has no torsion subgroup. This completes the lemma.

Definition 1.2: Let $M_{1}$ and $M_{2}$ be PL manifolds. Two PL homeomorphisms $h_{i}$ on $M_{i}(i=1,2)$ are called PL equivalent if there is a PL homeomorphism $t$ of $M_{1}$ onto $M_{2}$ such that $h_{2} t=t h_{1}$. In this case $t$ is called $P L$ equivariant with respect to $h_{1}$ and $h_{2}$. We sometimes denote the fact by $h_{1} \sim h_{2}$.

When $h_{i}(i=1,2)$ happen to be involutions on $M_{i}$, obviously any equivariant map $t$ sends the fixed point set of $h_{1}$ onto the fixed point set of $h_{2}$.

Definition 1.3: Let $h$ be an involution on a space $M$. The quotient space $M / Z_{2}$ of $M$ generated by $h$ is called the orbit space of $h$ and the projection $g: M \rightarrow M / Z_{2}$ is called the orbit map of $h$. We denote the fixed point set of $h$ by Fix (h).

The following theorem is due to Stallings [17].
Theorem (Stallings): If $M$ is a compact irreducible connected 3-manifold, and if $\Pi_{1}(M)$ has a finitely generated normal subgroup $K$ different from $Z_{2}$, whose quotient group is $Z$, then $M$ is the total space of a fiber space with base space a circle and with fiber a connected 2-manifold $T$ embedded in $M$ whose fundamental group is $K$.

Let $D^{2}$ be the unit disk in the Gaussian plane of complex numbers and $S^{1}$ its boundary. $D^{2} \times S^{1}$ is a solid torus whose points can be denoted by $\left(\rho z_{1}, z_{2}\right)$ where $z_{1}, z_{2} \in S^{1}$ and $0 \leq \rho \leq 1$.

Lemma 1.4: The orbit space of a free PL involution $h$ on $D^{2} \times s^{1}$ is homeomorphic to a disk bundle over $S^{1}$, and $h$ is PL equivalent to an involution $h_{1}$ given by either $h_{1}\left(\rho z_{1}, z_{2}\right)=\left(\rho z_{1},-z_{2}\right)$ or $h_{1}\left(\rho z_{1}, z_{2}\right)=\left(\rho \bar{z}_{1},-z_{2}\right)$.

Proof: Since $h$ is free, the orbit space $D^{2} \times S^{1} / Z_{2}$ is a connected orientable compact 3-manifold with boundary. Hence the Betti numbers of $D^{2} \times s^{1} / Z_{2} \quad \rho_{3}=0$ and $\rho_{0}=1$. since $D^{2} \times S^{1} / Z_{2}$ is covered by $D^{2} \times S^{1}$, we have a short exact sequence $0 \rightarrow Z \rightarrow \Pi_{1}\left(D^{2} \times s^{1} / Z_{2}\right) \rightarrow Z_{2} \rightarrow 0$. since $x\left(D^{2} \times s^{1}\right)=2 \cdot x\left(D^{2} \times s^{1} / Z_{2}\right), x\left(D^{2} \times s^{1} / Z_{2}\right)=0$. Hence $\rho_{1} \geq 1$. By Lemma 1.1, $\Pi_{1}\left(D^{2} \times s^{1} / Z_{2}\right)=Z$. On the other hand, $\mathrm{D}^{2} \times \mathrm{s}^{1} / \mathrm{Z}_{2}$ is irreducible as it is covered by $\mathrm{D}^{2} \times \mathrm{s}^{1}$. Therefore by Stallings' theorem, $D^{2} \times S^{1} / Z_{2}$ is homeomorphic to a disk bundle over $S^{l}$. That is, $D^{2} \times S^{1} / Z_{2}$ is a solid torus or a non-orientable disk bundle over $S^{1}$, according
to $h$ preserving or reversing the orientation. Let $h$ and $h^{\prime}$ be any two orientation preserving (or reversing) free PL involutions of $D^{2} \times S^{1}$. Let $t^{\prime}$ be a PL homeomorphism between the two orbit spaces of $h$ and $h^{\prime}$.

Consider the following diagram.

where $g$ and $g^{\prime}$ are the orbit maps of $h$ and $h^{\prime}$ respectively.

Since

$$
g_{\#}\left[\Pi_{1}\left(D^{2} \times s^{1}\right)\right]=2 z \subset \Pi_{1}\left(D^{2} \times s^{1} / Z_{2}\right)=z
$$ by the lifting theorem, we have a PL homeomorphism $t$ of $\mathrm{D}^{2} \times \mathrm{s}^{1}$ which makes the above diagram commutes. It follows that $t h=h^{\prime} t$. This completes the Lemma.

Remark 1.5: Let $h$ be a PL involution of a finite triangulated $n$-manifold $M_{1}$. It can be shown that $h$ becomes simplicial after a suitable subdivision such that the fixed point set of $h$ is a subcomplex of the subdivision $M_{2}$. Let $M$ be the second barycentric subdivision of $M_{2}$. Then it is easy to check the following properties: (1) $F$ is full subcomplex of $M$ (2) the orbit map $g$ of $h$ and the orbit space of $h$ are simplicial and $g$ maps each simplex homeomorphically.

The following result seems to be well-known and freely used by various authors ([10], [19]). For the sake of completeness, we give a proof.

Lemma 1.6: Up to PL equivalences, there exists exactly one $P L$ involution $h$ of $D^{2} \times S^{1}$ with the center circle as the fixed point set.

Proof: We first show that the orbit space of $h$ is a solid torus. Let $M$ be a triangulation of $D^{2} \times s^{1}$ as in Remark 1.5 and $U$ be the simplicial neighborhood of the center circle $F$ in $M$. Then $U \approx D^{2} \times S^{l}$ is an invariant neighborhood and $U^{\prime}=g(U)$ is a simplicial neighborhood of $F^{\prime}=g(F)$ where $g$ is the orbit map of $h$. Since $h$ is orientation preserving, the orbit space $M^{\prime}$ of $h$ is an orientable manifold. Since $U^{\prime}$ is orientable, ( $U^{\prime}, F^{\prime}$ ) $\approx$ $\left(D^{2} \times S^{l}, 0 \times S^{1}\right)$. We want $\Pi_{1}\left(M^{\prime}-U^{\prime}\right)=Z \oplus Z$. since $M-U \approx S^{1} \times S^{1} \times I, \quad X(M-U)=0$, and $X\left(M^{\prime}-U^{\prime}\right)=0$. But $H_{2}\left(M^{\prime}-U^{\prime} ; Q\right) \cong H_{2}(M-U ; Q)^{Z_{2}}$ which is $Z_{2}$-invariant homology with rational coefficient $Q$ (for the proof, see Floyd [2]). By the definition of $Z_{2}$-invariant homology, $H_{2}(M-U ; Q)^{Z_{2}}=\left\{\alpha \mid h_{*}(\alpha)=\alpha, \alpha \in H_{2}(M-U ; Q)\right\} \cong\left\{\alpha \mid h_{*}(\alpha)=\alpha_{0}\right.$, $\left.\alpha \in H_{2}\left(S^{l} \times S^{l} ; Q\right)\right\}$ where $S^{l} \times S^{l}$ is the boundary of $M-U$ and $h^{\prime}=h \mid S^{l} \times s^{l}$. Since $h^{\prime}$ preserves the orientation, the induced isomorphism $h_{*}^{\prime}$ is the identity, and $H_{2}\left(M^{\prime}-U^{\prime} ; Q\right)=Q$. Hence the Betti number of $H_{2}\left(M^{\prime}-U^{\prime}\right)$ is $\rho_{2}=1$. since $X\left(M^{\prime}-U^{\prime}\right)=0, H_{1}\left(M^{\prime}-U^{\prime}\right)$ is of rank 2. Since $M^{\prime}-U^{\prime}$ is covered by $M-U$, by Lemma 1.1,
$\Pi_{1}\left(M^{\prime}-U^{\prime}\right)=Z \oplus Z$. Therefore, by Stallings' theorem, $L^{\prime}-U^{\prime}$ is fibered over a circle with fiber $T$ and $\Pi_{1}(T)=Z$. Since $T$ is a connected 2-manifold, $T$ would be $S^{1} \times I$ or möbius band. But since $L^{\prime}-U^{\prime}$ is orientable, $T$ is orientable, and $T$ must be $S^{l} \times I$. Thus $L^{\prime}-U^{\prime}$ may be obtained from $S^{1} \times I \times I$ by identifying each $(x, 0)\left(x \in S^{1} \times I\right)$ with $(f(x), 1)$ where $f$ is a homeomorphism of $S^{1} x$. Since the number of components of $M^{\prime}-U^{\prime}$ is two, $f$ carries $S^{1} \times i$ onto $S^{1} x i(i=0,1)$. Hence, since $M^{\prime}-U^{\prime}$ is orientable, $f$ must preserve the orientation, and it can be shown that $f$ is isotopic to the identity. Hence $M^{\prime}-U^{\prime} \approx$ $S^{1} \times S^{1} \times I$. Since $U^{\prime}$ is a solid torus, $M^{\prime}$ must be a solid torus. Let $\tilde{h}$ be the $P L$ involution of $D^{2} \times S^{1}$ given by $\tilde{h}\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$. Let $\tilde{M}$ be a triangulation of $D^{2} \times S^{1}$ with respect to $\tilde{h}$ as in Remark 1.5, $\tilde{U}$ the simplicial neighborhood of the center circle $\tilde{F}$ in $\tilde{M}, \tilde{M}^{\prime}$ the orbit space of $\tilde{h}$ and $\tilde{g}$ the orbit map of $\tilde{h}$. By the above argument, $M^{\prime}=D^{2} \times S^{1} \cup S^{1} \times S^{1} \times I=\tilde{M}^{\prime}$ where $g(U)=D^{2} \times S^{1}=\tilde{g}(\tilde{U})$ and $S^{1} \times S^{1}$ is the boundary of $D^{2} \times s^{1}$. since $U$ and $V$ are invariant simplicial neighborhoods of the fixed point sets, one can find invariant 2-cells $C$ and $D$ regularly embedded in $U$ and $V$ as subpolyhedra, respectively. Consider the following diagram.

where we will define a PL homeomorphism $\ell$ later. Let (1,0) be generators of $\Pi_{1}(M-F)$ and $\Pi_{1}(\mathbb{M}-\widetilde{F})$ represented by the path $\partial C$ and $\partial D$ in $M$ and $\tilde{M}_{\text {, respectively. For the }}$ sake of briefness, again ( 1,0 ) and ( 0,1 ) be the canonical generators of $\Pi_{1}\left(S^{1} \times S^{1}\right)$ which are the fundamental groups of $M^{\prime}-F^{\prime}$ and $\tilde{M}^{\prime}-\widetilde{F}^{\prime}$ where $\widetilde{F}^{\prime}=g(\widetilde{F})$ and $S^{1} \times S^{1}$ is the boundary of $U^{\prime}=D^{2} \times S^{1}=\tilde{U}^{\prime}$. Without loss of generality, we may assume that $(1,0)$ are generated by $g(\partial C)$ and $g(\partial D)$ of $g(\partial U)$ and $\tilde{g}(\partial \tilde{U})$, respectively. The induced homomorphism $g_{\#}$ sends $(1,0)$ to $(2,0)$, so that $g_{\#}(Z \oplus Z)=2 Z+\langle(d, e)\rangle$ where $g_{\#}[(0, l)]=(d, e)$ for some integers $d$ and $e$, and $\langle(d, e)\rangle$ is the subgroup of $\Pi_{1}\left(S^{1} \times S^{1}\right)$ generated by (d,e). Since $g$ is the double covering projection, $\langle(d, e)\rangle$ can not be contained in $\langle(1,0)\rangle$. Moreover, $\langle(1,0)\rangle \cap\langle(d, e)\rangle=\{0\}$ since otherwise $\langle(d, e)\rangle \subset\langle(1,0)\rangle$. Hence $\langle(1,0)\rangle+\langle(d, e)\rangle=\langle(1,0\rangle \oplus$ $\langle(d, e)\rangle$, and $g_{\#}(Z \oplus z)=2 Z \oplus\langle(d, e)\rangle$. since $\left[\Pi_{1}\left(S^{l} \times S^{l}\right)\right.$ : $2 Z \oplus\langle(d, e)\rangle]=2, \quad\left[\Pi_{1}\left(S^{l} \times s^{l}\right): Z \oplus\langle(d, e)\rangle\right]=1$, and $\Pi_{1}\left(S^{1} \times S^{l}\right)=Z \oplus\langle(d, e)\rangle$. since $g(C)$ and $\tilde{g}(D)$ are regularly embedded in $U^{\prime}$ and $\tilde{U}^{\prime}$ as subpolyhedra, there exists a PL homeomorphism $q^{\prime}$ of $U^{\prime}$ onto $V^{\prime}$ carrying $g(C)$ onto $\tilde{g}(D)$. Hence there exists an extended PL homeomorphism $q$ of $M^{\prime}$ onto $M^{\prime}$. Therefore, $q_{\#}$ sends ( 1,0 ) to ( 1,0 )
and $(d, e)$ to $(a, b)$, and $q_{\#}(Z \oplus\langle(d, e)\rangle)=z \oplus\langle(a, b)\rangle=$ $\Pi_{1}\left(S^{1} \times S^{1}\right)$. We may assume $b=1$. Define a PL homeomorphism $t^{\prime}$ of $\tilde{v}^{\prime}=D^{2} \times s^{1}$ by $t^{\prime}\left(\rho z_{1}, z_{2}\right)=\left(\rho z_{1}, z_{2}^{-a}, z_{2}\right)$. Since $\tilde{M}^{\prime}=D^{2} \times S^{1} \cup S^{1} \times S^{1} \times I$, there exists an externsion $t$ on $\widetilde{M}^{\prime}$. Now define $l=$ ta. Let $\varphi$ be the nice path generating $(0,1)$ of $\Pi_{1}\left(S^{1} \times S^{l}\right)=\Pi_{1}\left(\mathbb{M}^{\prime}-\tilde{F}^{\prime}\right)$. considering the action of $\tilde{h}$ and the fact that $V$ is the invariant simplicial neighborhood of $\tilde{F}, \tilde{g}^{-1}(\varphi)$ is a disjoint union of two simple closed curves. Denote one of them by $\varphi^{\prime}$. Let $\alpha$ be an element of $\Pi_{1}(\widetilde{M}-F)$ represented by the path $\varphi^{\prime}$. Then $\tilde{g}_{\#}[(1,0)]=(2,0)$ and $\tilde{g}_{\#}(\alpha)=(0,1)$, and $\langle(1,0)\rangle \cap\langle\alpha\rangle=\{0\}$. Suppose the contrary that $\langle(1,0)\rangle \oplus$ $\langle\alpha\rangle$ is a proper subgroup of $\Pi_{1}(\tilde{M}-\tilde{F})$. Then since $\tilde{g}_{\#}$ is monomorphism, $\langle(2,0)\rangle \oplus\langle(0,1)\rangle$ is a proper subgroup of $g_{\#}\left[\Pi_{1}(\mathbb{M}-\widetilde{F})\right]$. But $\left.\quad\left[\Pi_{1}(\widetilde{g}(\mathbb{M}-\widetilde{F})): \tilde{g}_{\#} \Pi_{1}(\mathbb{M}-\widetilde{F})\right)\right]=2$. Therefore $\left[\widetilde{g}_{\#} \Pi_{1}(\widetilde{M}-\widetilde{F}):\langle(2,0)\rangle \oplus\langle(0,1)\rangle\right]=1$. This is a contradiction. Let us look at the following diagram which is a concentration of the work done so far.


Since $t_{\#}=\left(\begin{array}{cc}1 & -a \\ 0 & 1\end{array}\right)$, one can check that $\ell_{\#} g_{\#}[(1,0)]=(2,0)$ and $\ell_{\#} g_{\#}(0,1)=(0,1)$. Hence by the lifting theorem, we have a PL homeomorphism $f$ which makes the following diagram commute

where $\left(D^{2}-0\right) \times s^{1}=g\left(\left(D^{2}-0\right) \times s^{1}\right), \tilde{g}\left(\left(D^{2}-0\right) \times s^{1}\right)$. Hence $\mathrm{fh}=\tilde{h}_{\mathrm{f}}$. One can extend f to $\mathrm{D}^{2} \times \mathrm{S}^{1}$ in an obvious way such that $f h=\tilde{\mathrm{h}} \mathrm{f}$ on $\mathrm{D}^{2} \times \mathrm{S}^{1}$. This completes the lemma.

Let $h$ be an orientation preserving PL involution on a lens space $L=L(p, q)$ which preserves sense and has nonempty fixed point set $F$. By the dimensional parity theorem, each component $F_{O}$ of $F$ is of l-dimension, and $F_{O}$ is a simple closed curve. Let $U$ be a regular neighborhood of $F_{O}$ such that $U \cap F=F_{O}$. Consider the usual covering projection $g: s^{3} \rightarrow$ L. By the lifting theorem, we have a PL involution $\tilde{\mathrm{h}}:\left(\mathrm{S}^{3}, y_{O}\right) \rightarrow\left(\mathrm{s}^{3}, \mathrm{y}_{\mathrm{O}}\right)$ where $\mathrm{g}\left(\mathrm{y}_{\mathrm{O}}\right) \in \mathrm{F}_{\mathrm{O}}$ Suppose $h$ is sense preserving. Then $g^{-1}\left(F_{0}\right)$ is connected, and $\tilde{F}=g^{-1}\left(F_{O}\right)$ is the fixed point set of $\tilde{h}$. By Waldhausen [20], $\widetilde{F}$ is an unknotted simple closed curve. Hence $\overline{\mathrm{s}^{3}-\mathrm{g}^{-1}(\mathrm{U})}$ is a solid torus, and $\overline{\mathrm{L}-\mathrm{U}}$ is a solid torus. An explicit argument of the above may be found in [10].

Theorem 1.7: If $h$ is an orientation preserving PL involution of $L=L(p, q), p$ even, which preserves sense and has non-empty fixed point set $F$, then $F$ is a disjoint union of two simple closed curves.

Proof: By the above discussion, $L=D^{2} \times S^{1} U_{k} S^{1} \times D^{2}$ such that $D^{2} \times S^{1}$ is an invariant regular neighborhood of a component of $F$ for an attaching map $k$ of $S^{1} \times S^{1}$. Denote $h \mid D^{2} \times s^{1}$ and $h \mid s^{1} \times D^{2}$ by $h_{1}^{\prime}$ and $h_{2}^{\prime}$, respectively. Suppose the contrary that Fix $\left(h_{2}^{\prime}\right)=\varnothing$. Define $h_{1}$ on $D^{2} \times S^{1}$ by $h_{1}\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$. By Lemma 1.6, there exists a PL homeomorphism $t^{\prime}$ on $D^{2} \times s^{1}$ such that $h_{1}=t^{\prime} h_{l}^{\prime} t^{\prime-1}$. Define $t$ of $D^{2} \times s^{1} U_{k} s^{1} \times D^{2}$ onto $D^{2} \times s^{1} U_{k t^{\prime}-1} s^{1} \times D^{2}$ by the following:

$$
\left\{\begin{array}{lll}
t=t^{\prime} & \text { on } & D^{2} \times s^{1} \\
t=\text { identity } & \text { on } & s^{1} \times D^{2}
\end{array}\right.
$$

It is a well defined PL homeomorphism. Define $\tilde{\mathrm{K}}$ on $D^{2} \times s^{1} U_{k t^{\prime}-1} S^{1} \times D^{2}$ by $\tilde{K}=t h t^{-1}$. since $h_{1}=t^{\prime} h_{1}^{\prime} t^{\prime-1}$. $\tilde{h} \mid D^{2} \times S^{1}=h_{1}$ and $\tilde{h} \mid S^{1} \times D^{2}=h_{2}^{\prime}$. It is checked that $\tilde{h}$ is a $P L$ involution, and $h$ and $\tilde{h}$ are $P L$ equivalent. Hence we may assume that $h\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$ on $D^{2} \times s^{1}$. By Lemma 1.4 and the similar argument as the above, we may furthen assume that $h\left(z_{1}, \rho z_{2}\right)=\left(-z_{1}, \rho z_{2}\right)$ on $S^{l} \times D^{2}$ since Fix $(h)=\varnothing$. That is, we may assume that $L=D^{2} \times S^{1} U_{f} S^{1} \times D^{2}$ for an appropriate attaching map $f$ of $S^{1} \times S^{1}$ and $h$ is given by $h\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$ on $D^{2} \times s^{l}$ and $h\left(z_{1}, \rho z_{2}\right)$ $=\left(-z_{1}, \rho z_{2}\right)$ on $S^{1} \times D^{2}$. Consider the following commutative diagram

where $\varphi_{1}$ and $\varphi_{2}$ are the inclusion maps.
Let $(1,0)$ and $(0,1)$ be the canonical generators of $\Pi_{1}\left(S^{1} \times S^{1}\right)$ such that $f_{\#}(1,0)=(a, b)$ and $f_{\#}(0,1)=(c, d)$, where $f_{\#}$ is the isomorphism induced by $f$ (we disregard the base point as $\Pi_{1}\left(S^{l} \times S^{l}, *\right)$ is abelian). We may assome that $\left|\begin{array}{ll}a & c \\ b & d\end{array}\right|=1$. One can show that by Van Kampen theorem, $\Pi_{1}(L)=\left\{\alpha, \beta \mid \beta^{c}=\alpha, \beta^{a}=1\right\}=\left\{\beta \mid \beta^{a}=1\right\}$ where $\alpha$ and $\beta$ are the canonical generators of $\Pi_{1}\left(D^{2} \times s^{1}\right)$ and $\Pi_{1}\left(S^{1} \times D^{2}\right)$, respectively. Since $\Pi_{1}(L(p, q))=Z_{p^{\prime}} a= \pm p$, and $a$ is even. Let $g$ and $\hat{g}$ be the orbit maps of $h!D^{2} \times S^{1}$ and $h / S^{1} \times D^{2}$, respectively. Then by Lemma 1.4 and the proof of Lemma 1.6, $g\left(D^{2} \times S^{1}\right)$ and $\hat{g}\left(S^{1} \times D^{2}\right)$ are solid tori. Consider the following diagram

$$
\begin{aligned}
& \mathrm{D}^{2} \times \mathrm{s}^{1} \supset \mathrm{~S}^{1} \times \mathrm{S}^{1} \xrightarrow{\mathrm{f}} \mathrm{~S}^{1} \times \mathrm{S}^{1} \subset \mathrm{~S}^{1} \times \mathrm{D}^{2}
\end{aligned}
$$

where $g^{\prime}$ and $\hat{g}^{\prime}$ are induced by $g$ and $\hat{g}$, respectiveMy and $f^{\prime}$ is the induced attaching map in the orbit space of $h$. Notice that $g_{\#}^{\prime}(r, s)=(2 r, s)$ and $\hat{g}_{\#}^{\prime}(r, s)=(2 r, s)$ for any element $(r, s) \in \Pi_{1}\left(S^{l} \times s^{1}\right)$. Let $f_{\#}^{\prime}[(1,0)]=\left(a^{\prime}, b\right)$
and $f_{\#}^{\prime}[(0,1)]=\left(c^{\prime}, d^{\prime}\right)$. By chasing the above commutative diagram, easy computation shows that $b=2 b^{\prime}$, and $b$ is even. Since $a$ is even, we have a contradiction to the fact $a d-b c=1$. Therefore, $F i x\left(h \mid s^{1} \times D^{2}\right.$ ) can not be empty. By Tollefson [19], Fix (hiS $\mathrm{S}^{1} \times \mathrm{D}^{2}$ ) is a simple closed curve. This completes the proof.

## PL INVOLUTIONS ON SOME 3-MANIFOLDS

In this chapter, we will investigate all orientation preserving PL involutions on $L(p, q)$, $p$ even, which preserve sense and have non-empty fixed point sets.

Kwun [9] considered all orientation reversing PL involutions on lens spaces, and proved that no lens space except the projective 3-space $P^{3}$ admits an orientation reversing PL involution and there exists exactly one orientation reversing $P L$ involution on $P^{3}$, up to $P L$ equivalences. In this case, the fixed point set is a projective plane $\mathrm{P}^{2}$ plus an isolated point. Using this result applied to Kim and Tollefson's work [7] and Showers' work [16], the orientation reversing $P L$ involutions on the connected sum of two lens spaces are easily classified. Myung [13] initiated this problem and gave a partial solution. We will also study all orientation preserving $P L$ involutions on $P^{3} \# P^{3}$ as well as those on $P^{3}$. Kwun [10] also showed that up to PL equivalences, there is exactly one orientation preserving PL involution $h$ on $L=L(p, q), p$ odd, which preserves sense and has non-empty fixed point set if $L$ is symmetric and there are exactly two such $h$ if $L$ is non-symmetric. In the latter case, the two different orbit spaces are $L\left(p, q^{\prime}\right)$ and $L\left(p, q^{\prime \prime}\right)$ where $2 q^{\prime} \equiv \pm q$ and $2 q^{\prime \prime} q \equiv \pm 1$ mod $p$. In either case, Fix(h) is a simple closed curve.

Let $(1,0)$ and ( 0,1 ) be the canonical generators of $I_{1}\left(S^{l} \times S^{l}\right)$ and $k$ be a PL homeomorphism on $S^{l} \times S^{l}$ such that $k_{\#}[(1,0)]=(a, b)$ and $k_{\#}[(0,1)]=(c, d)$. We may assume $\left|\begin{array}{ll}a & c \\ b & d\end{array}\right|=1$ and $a \geq 0$.

Definition 2.1: Define $L_{k}(a, c, b, d)=D^{2} \times s^{1} U_{k} s^{1} \times D^{2}$ where $\left|\begin{array}{ll}\mathrm{a} & \mathrm{c} \\ \mathrm{b} & \mathrm{d}\end{array}\right|=1$ and $\mathrm{a} \geq 0$. We sometimes denote $I_{k}(a, c, b, d)$ by $I_{k}$ if no confusion arises.

By Mangler [ll], the isotopy classes of homeomorphisms of $S^{l} \times S^{l}$ are precisely the automorphism classes of $\Pi_{1}\left(S^{1} \times S^{1}\right)$. Hence, the integers $a, b, c$ and $d$ completely determine the isotopy class of $k$ in Definition 2.1, and hence the homeomorphic type of $L_{k}(a, c, b, d)$. As Kwan [10] pointed out, if $a=0, L_{k}$ is homeomorphic to $s^{1} \times s^{2}$, if $a=1$, $\quad L_{k}$ is homeomorphic to $S^{3}$, and if $a>1$, $L_{k}$ is homeomorphic to $L(a, b)$ : Recall that $L(p, q)$ is homeomorphic to $L\left(p, q^{\prime}\right)$ if and only if $q \equiv \pm q^{\prime}$ or $q q^{\prime} \equiv \pm 1 \bmod p[12,14]$.

Lemma 2.2: Let $h$ be a PL involution of $L_{k}(a, c, b, d)$ such that $h\left(D^{2} \times S^{1}\right)=D^{2} \times S^{1}$ and $h$ is given by $h\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$ on $D^{2} \times s^{l}$ and $h\left(z_{1}, \rho z_{2}\right)=\left(z_{1},-\rho z_{2}\right)$ on $S^{1} \times D^{2}$. Then the orbit space of $h$ is homeomorphic to $I_{k^{\prime}}\left(\frac{a}{2}, c, b, 2 d\right)$, and $a$ is even, where $k^{\prime}$ is the attaching map induced by $k$.

Proof: By Lemma 1.6, the orbit space of $h \mid D^{2} \times s^{1}$ and $h \mid S^{1} \times D^{2}$ are solid tori. Hence the orbit space of
$h$ is homeomorphic to $L_{k},\left(p^{\prime}, c^{\prime}, b^{\prime}, d^{\prime}\right)$ for suitable $k^{\prime}$. $p^{\prime}, b^{\prime}, c^{\prime}$ and $d^{\prime}$. Consider the following diagram.

where $g$ and $g^{\prime}$ are induced by the orbit maps of $h \mid D^{2} \times S^{1}$ and $h \mid S^{1} \times D^{2}$, respectively. Notice that $g_{\#}[(1,0)]=$ $(2,0), \quad g_{\#}[(0,1)]=(0,1), \quad g_{\#}^{\prime}[(1,0)]=(1,0)$ and $g_{\#}^{\prime}[(0,1)]=$ $(0,2)$. Easy computation shows that $p=2 p^{\prime}, b=b^{\prime}, c=c^{\prime}$ and $2 d=d^{\prime}$. Hence the orbit space of $h$ is homeomorphic to $L_{k},\left(\frac{p}{2}, c, b, 2 d\right)$. This completes the lemma.

Definition 2.3: Let $p$ be even and a homeomorphism $f$ of $s^{l} \times s^{l}$ be given by $f\left(z_{1}, z_{2}\right)=\left(z_{1}^{p} z_{2}^{c}, z_{1}^{b} z_{2}^{d}\right)$. Define an involution of $L_{f}(p, c, b, d)$ by $h\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$ on $D^{2} \times s^{1}$ and $h\left(z_{1}, \rho z_{2}\right)=\left(z_{1},-\rho z_{2}\right)$ on $s^{1} \times D^{2}$. We denote the involution by $h(p, c, b, d)$.

In the above definition, since $p$ is even and $b$ is odd (recall that $\mathrm{pd}-\mathrm{bc}=1$ ), one can easily check that $h=h(p, c, b, d)$ is compatible with the attaching map, ie., $\mathrm{fh}=\mathrm{hf}$.

Lemma 2.4: Let $h_{i}(i=1,2)$ be PL involutions on $L_{i}=L_{f_{i}}(a, c, b, d)$ such that $h_{i}\left(D^{2} \times s^{1}\right)=D^{2} \times s^{1}$, and $h_{i}\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$ on $D^{2} \times s^{l}$ and $h_{i}\left(z_{1}, \rho z_{2}\right)=$ $\left(z_{1},-\rho z_{2}\right)$ on $S^{1} \times D^{2}$. Then $h_{1}$ and $h_{2}$ are PL equivalent.

Proof: By Lemma 2.2, the orbit spaces of $h_{i}$ are homeomorphic to $L_{f_{i}^{\prime}}\left(\frac{a}{2}, c, b, 2 d\right)$ for some attaching maps $f_{i}^{\prime}$. Hence $f_{1}^{\prime}$ and $f_{2}^{\prime}$ are isotopic, and there exists a level preserving $P L$ homeomorphism $H$ of $S^{1} \times S^{1} \times I$ such that $H_{1} f_{1}^{\prime}=f_{2}^{\prime}$ and $H_{0}=$ identity. since $S^{1} \times S^{l} \times I$ is a boundary collar of $S^{1} \times D^{2}$, there exists a PL homeomorphism $t^{\prime}$ of $s^{1} \times D^{2} \subset L_{f_{1}^{\prime}}$ onto $s^{1} \times D^{2} \subset L_{f_{2}^{\prime}}$ such that $t^{\prime} f_{1}^{\prime}=$ $f_{2}^{\prime}$. Define a homeomorphism $t_{1}: L_{f_{1}^{\prime}} \rightarrow L_{f_{2}^{\prime}}$ by $t_{1}\left(\rho z_{1}, z_{2}\right)=$ $\left(\rho z_{1}, z_{2}\right)$ on $D^{2} \times S^{1}$ and $t_{1}\left(z_{1}, \rho z_{2}\right)=t^{\prime}\left(z_{1}, \rho z_{2}\right)$ on $S^{1} \times D^{2}$. One can check that $t_{1}$ is well defined. Consider the following diagram.
where $F_{i j}(j=1,2)$ are the components of the fixed point set $F_{i}$ of $h_{i}, g_{i}$ are the orbit maps of $h_{i}$ and $g_{i}\left(F_{i j}\right)=F_{i j}^{\prime}$
Since $S^{1} \times D^{2}$ is a regular neighborhood of $F_{i_{2}}$, $\Pi\left(L_{i}-F_{i_{1}}-F_{i_{2}}\right)=\Pi_{1}\left(D^{2} \times s^{1}-F_{i_{1}}\right)=\Pi_{1}\left(\left(D^{2}-0\right) \times s^{1}\right)$. Since $t_{1}$ is identity on $D^{2} \times s^{1}$, by the lifting theorem, we have a lifting $t$ such that the above diagram computes. One can extend $t$ to whole $L_{1}$ in an obvious way such that $t h_{1}=h_{2} t$ on $L_{1}$. This completes the proof.

Remark 2.5: Let $h$ be an orientation preserving PL involution $h$ of $L=L(p, q)$, $p$ even, which preserves sense and has non-empty fixed point set. By Tollefson [19], any orientation preserving $P L$ involution on $S^{1} \times D^{2}$ with non-empty fixed point set is PL equivalent to the involution $h^{\prime}$ given by $h^{\prime}\left(z_{1}, \rho z_{2}\right)=\left(z_{1},-\rho z_{2}\right)$. Therefore, by using same technique as in the proof of Theorem 1.7, we may assume that $L=D^{2} \times S^{l} U_{f} S^{l} \times D^{2}$ for an appropriate attaching map $f$ and $h$ is given by $h\left(\rho z_{1}, z_{2}\right)=\left(-\rho z_{1}, z_{2}\right)$ on $D^{2} \times S^{1}$ and $h\left(z_{1}, \rho z_{2}\right)=\left(z_{1},-\rho z_{2}\right)$ on $S^{l} \times D^{2}$. Hence, by Lemma 2.4, we may assume $h=h(p, c, b, d)$ on $L_{f}(p, c, b, d)$ where $f$ is given by $f\left(z_{1}, z_{2}\right)=\left(z_{1}^{p} z_{2}^{c}, z_{1}^{b} z_{2}^{d}\right)$. Since $L_{f}(p, c, b, d) \approx$ $\mathrm{L}(\mathrm{p}, \mathrm{b}), \mathrm{b} \equiv \pm \mathrm{q}$ or $\mathrm{bq} \equiv \pm 1 \bmod \mathrm{p}$. By Lemma 2.2, the orbit space of $h$ is homeomorphic to $L\left(\frac{p}{2}, b\right)$ where $b \equiv \pm q$ or $\mathrm{bq} \equiv \pm 1$ mod $p$.

Proposition 2.6: $h=h(p, c, b, d)$ can be extended to an effective circle action.

Proof: For each $Z \in S^{1}$, define $S^{1}$-action by $z \cdot\left(\rho z_{1}, z_{2}\right)=\left(\rho z_{1} z_{,} z_{2}\right)$ on $D^{2} \times S^{1}$ and $z \cdot\left(z_{1}, \rho z_{2}\right)=$ $\left(z_{1} z^{p}, \rho z_{2} z^{b}\right)$ on $S^{1} \times D^{2}$.

Remark 2.7: If an involution $h$ of $L(p, q)$ can be extended to an effective circle action, $h$ must be clearly sense preserving. By Proposition 2.6, $h(p, c, b, d)$ is sense preserving. Therefore, by Remark 2.5, the classification problem of orientation preserving $P L$ involutions of $L(p, q)$,
p even, which preserve sense and have non-empty fixed point sets is the same problem as the classification of those $h(p, c, b, d)$ for various possible $c, b, d$ with $p d-c b=1$. The information that we have is that $b q \equiv \pm 1$ or $b \equiv \pm q$ $\bmod p$.

Now we analyze the involution $h(p, c, b, d)$. If $h(p, c, b, d)$ is equivalent to $h\left(p, c^{\prime}, b^{\prime}, d^{\prime}\right)$, we denote the fact by $h(p, c, b, d) \sim h\left(p, c^{\prime}, b^{\prime}, d^{\prime}\right)$.

Lemma 2.8: For any integers $c, b, d$ with $p d-c b=1$,
(1) $h(p, b, c, d) \sim h\left(p, c^{\prime}, b, d^{\prime}\right)$ for any integers $c^{\prime}$ and $d^{\prime}$ with $p d^{\prime}-c^{\prime} b=1$.
(2) $h(p, c, b, d) \sim h(p, c, b+m p, d+m c)$
(3) $h(p, c, b, d) \sim h(p,-c,-b, d)$
(4) $h(p, c, b, d) \sim h(p,-b,-c, d)$

Proof: We will define a homeomorphism $t: L_{f} \rightarrow L_{f}$, where $L_{f}=L_{f}(p, c, b, d)$ and $L_{f}$, is the space corresponding to the equivalent involution claimed in (i), $i=1,2,3,4$. In (1), since $p d^{-b c}=1=p d^{\prime}-b c^{\prime}, c^{\prime}=c+m p, d^{\prime}=d+m b$ for some integer $m$. Define $t: L_{f} \rightarrow L_{f}$, by $t\left(\rho z_{1}, z_{2}\right)=$ $\left(\rho z_{1} z_{2}{ }^{-m}, z_{2}\right)$ on $D^{2} \times s^{1}$ and $t\left(z_{1}, \rho z_{2}\right)=\left(z_{1}, \rho z_{2}\right)$ on $S^{1} \times D^{2}$. For (2), define $t: L_{f} \rightarrow L_{f}$, by $t\left(\rho z_{1}, z_{2}\right)=$ $\left(\rho z_{1}, z_{2}\right)$ on $D^{2} \times S^{1}$ and $t\left(z_{1}, \rho z_{2}\right)=\left(z_{1}, \rho z_{2} z_{1}^{m}\right)$ on $s^{1} \times D^{2}$. For (3), define $t: L_{f} \rightarrow L_{f}$, by $t\left(\rho z_{1}, z_{2}\right)=$ $\left(\rho z_{1}, z_{2}^{-1}\right)$ on $D^{2} \times S^{1}$ and $t\left(z_{1}, \rho z_{2}\right)=\left(z_{1}, \rho z_{2}^{-1}\right)$ on $s^{1} \times D^{2}$.
For (4), define $t: L_{f} \rightarrow L_{f}$, by $t\left(\rho z_{1}, z_{2}\right)=\left(z_{2}, \rho z_{1}\right)$ on $D^{2} \times s^{1}$ and $t\left(z_{1}, \rho z_{2}\right)=\left(\rho z_{2}, z_{1}\right)$ on $s^{1} \times D^{2}$ such that
$t\left(D^{2} \times s^{1}\right)=s^{1} \times D^{2}$. It is checked that those $t$ are well defined and equivariant homeomorphisms. This completes the proof.

Now we are in a position to state our main theorem.

Theorem 2.9: Up to PL equivalences, there is exactly one orientation preserving $P L$ involution on $L(p, q), \quad P$ even, which preserves sense and has non-empty fixed point set.

Proof: By Remark 2.7, we will consider two involutions $h_{1}=h(p, c, b, d)$ and $h_{2}=h\left(p, c^{\prime}, b^{\prime}, d^{\prime}\right)$. Let $L_{1}=$ $L_{f}(p, c, b, d)$ and $L_{2}=L_{f},\left(p, c^{\prime}, b^{\prime}, d^{\prime}\right)$ corresponding to $h_{1}$ and $h_{2}$, respectively. Since $L_{1} \approx L(p, b)$ and $L_{2} \approx$ $L\left(p, b^{\prime}\right), b \equiv \pm b^{\prime}$ or $b b^{\prime} \equiv \pm 1 \bmod p$. If $b \equiv \pm b^{\prime} \bmod p$, $b= \pm b^{\prime}+m p$ for some integer $m$. By (1), (2), and (3) $h_{1} \sim h_{2}$. Suppose $b b^{\prime} \equiv \pm 1 \bmod p . \quad$ Since $p d-b c=1$, $b^{\prime}= \pm c+m p$ for some $m$. BY (1), (2), (3), and (4), again $h_{1} \sim h_{2}$. This completes the theorem.

Now consider free $Z_{2}$-action $h$ on $p^{3}$. The orbit space $M$ of $h$ is a closed 3-manifold. Since we have a universal covering projection $S^{3} \rightarrow P^{3} \rightarrow M$, the order of $\Pi_{1}(M)$ is 4, and $\Pi_{1}(M)=Z_{2} \oplus Z_{2}$ on $Z_{4}$. Epstein [1] completely determined all possible abelian groups which can be fundamental groups of closed 3-manifolds; $Z, Z \oplus Z \oplus Z$, $Z \oplus Z_{2}$, and $Z_{r}$. Hence $\Pi_{1}(M)$ should be $Z_{4}$. Hence $S^{3} / Z_{4}=M$. Rice [15] discussed free $Z_{4}$-action on $S^{3}$. As a consequence of the discussion, $M=L(4,1)$. Since every
involution on $P^{3}$ is sense preserving, by Theorem 2.9 and the above discussion, we have the following corollary.

Corollary 2.10: Up to PL equivalences, there is exactly one orientation preserving $P L$ involution $h$ on $P^{3}$ with Fix (h) $\neq \varnothing$ and there is exactly one free involution on $\mathrm{p}^{3}$ 。

Definition 2.11: $L(p, q)$ is called symmetric if $q^{2} \equiv \pm 1 \bmod p$.

Since $L(p, q)$ and $L\left(p, q^{\prime}\right)$ are homeomorphic if and only if $q^{\prime} \equiv \pm q$ or $q^{\prime} \equiv \pm 1 \bmod p, L$ being symmetric is a topological property.

Let $h$ be an orientation preserving $P L$ involution on a lens space $L(p, q)$, $p$ even, which preserves sense and non-empty fixed point set. By Theorem 1.7. Fix (h) is a disjoint union of two simple closed curves $F_{1}$ and $F_{2}$. We ask that under what condition there exists a PL equivalent homeomorphism $t$ with respect to $h$ such that $t\left(F_{1}\right)=F_{2}$. Indeed, there exists such a $t$ if $L(p, q)$ is symmetric. Furthermore, the converse is true. By Theorem 2.9, we may assume $h=h(p, c, b, d)$ on $L_{f}(p, c, b, d)$. If $L(p, q)$ is symmetric, $b^{2} \equiv \pm 1$ mod $p$. Since $p d-c b=1, c= \pm b+m p$ for some integer $m$. By Lemma 2.8, we have the following equivariant maps $t_{i} . \quad h(p, c, b, d)=h(p, \pm b+m p, b, d) \stackrel{t_{1}}{\sim}$
 $h(p, \pm b+m p, b, d)=h(p, c, b, d)$. Recall that $t_{1}\left(D^{2} \times s^{1}\right)=$ $S^{1} \times D^{2}$ and $t_{i}\left(D^{2} \times S^{1}\right)=D^{2} \times S^{1}$. Let $t=t_{4} t_{3} t_{2} t_{1}$.

Then $t$ is a PL equivariant homeomorphism on $L_{f}(p, c, b, d)$ such that $t\left(0 \times s^{l}\right)=s^{1} \times 0$. Conversely, suppose that there exists a PL equivariant homeomorphism $t$ on $L(p, q)$ such that $t\left(F_{1}\right)=F_{2}$. By the proof of Theorem 1.7, $\Pi_{1}(L)=$ $\left\{\alpha, \beta \mid \beta^{C}=\alpha, \beta^{p}=1\right\}$ where $\alpha$ and $\beta$ are represented by the loops $F_{1}$ and $F_{2}$, respectively. Let $t_{\#}$ be the automorphism induced by $t$. Then $t_{\#}(\alpha)=\beta^{\varepsilon}$ and $t_{\#}(\beta)=\alpha^{\delta}$ where $\epsilon= \pm 1$ and $\delta= \pm 1$. since $t_{\#}\left(\beta^{c}\right)=\alpha^{\delta c}=\beta^{\delta C^{2}}$ and $t_{\#}(\alpha)=\beta^{\varepsilon}, \beta^{\varepsilon}=\beta^{\delta c^{2}}$, and $c^{2} \equiv \pm 1 \bmod p$. Since $p d-b c=1, \quad b^{2} \equiv \pm 1$ mod $p$, which implies $L(p, q)$ is symmetric. Thus, we have the following theorem.

Theorem 2.11: Let $h$ be an orientation preserving PL involution on a lens space $L=L(p, q)$, $p$ even, which preserves sense and has non-empty fixed point set. Then there exists a PL equivariant homeomorphism $t$ such that $t$ interchanges the two components of Fix(h) if and only if L is symmetric.

Let $M_{i}(i=1,2)$ be oriented, connected, closed, irreducible 3-manifolds. It is known [7] that a PL involution $h$ on $M_{1} \# M_{2}$ is either the obvious involution which interchanges $M_{1}$ and $M_{2}$ or of the form $h_{1} \# h_{2}$ where each $h_{i}$ is a $P L$ involution on $M_{i}$. In the latter case, Fix (h) is not empty, and if $\operatorname{dim} F i x(h)=1$, the 2 -sphere along which the $M_{1}$ and $M_{2}$ are joined meets $F$ in general position. When each $M_{i}$ happens to be a lens space and $h$ is of the form $h_{1} \# h_{2}$, it will be convenient to
call decomposed sense preserving if $h$ induces the identity of $H_{1}(M)=H_{1}\left(M_{1}\right) \oplus H_{1}\left(M_{2}\right)$. Obviously, if $h$ is decomposed sense preserving, each $h_{i}$ is sense preserving. In this case, if $h$ is orientation preserving involution with Fix $(h) \neq \varnothing$ and $M_{1}$ is symmetric, by Theorem 2.11, $h$ does not depend on how an invariant 3-cell of $M_{1}$ is chosen to construct $h_{1} \# h_{2}$. Therefore, the following corollary is obtained by using Kwun's result [10] and Theorem 2.9.

Corollary 2.12: Up to PL equivalences, there exists exactly one decomposed sense preserving PL involution $h$ on $L(p, q) \# L(\bar{p}, \bar{q})$, which preserves the orientation if $L(p, q)$ and $L(\bar{p}, \bar{q})$ are symmetric ( $p, \bar{p}$ are any integers). There exist exactly two such $h$ if $L(p, q)$ is symmetric and $L(\bar{p}, \bar{q})$ is non-symmetric lens space with $\bar{p}$ odd ( $p$ is any integer).

Since any involution $h$ on $p^{3} \# p^{3}$ of the form $h_{1} * h_{2}$ is decomposed sense preserving, we have the following corollary.

Corollary 2.13: Let $h$ be an orientation preserving PL involution on $P^{3} \# P^{3}$. If Fix $(h)=\varnothing$ or Fix $(h)$ is connected, $h$ is the obvious involution which interchanges the two $p^{3}$. If Fix (h) is not connected, Fix (h) is a disjoint union of three simple closed curves and there is exactly one such $h$, up to PL equivalences.

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