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TRANSIENT REFLECTION OF PLANE WAVES FROM A LORENTZ-MEDIUM HALF-SPACE

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TRANSIENT REFLECTION OF PLANE WAVES FROM A LORENTZ-MEDIUM HALF-SPACE

By

Steven Michael Cossmann

A THESIS

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ABSTRACT

TRANSIENT REFLECTION OF PLANE WAVES FROM A LORENTZ-MEDIUM HALF-SPACE

By

Steven Michael Cossmann

For materials that exhibit resonances, or have parameters that vary rapidly with frequency, the Lorentz model is becoming increasingly more popular, especially when dealing with signals with content at optical frequencies. The propagation and reflection of transient pulses by these media is of particular interest.

It has been shown previously that the transient plane-wave field reflected from a Lorentz-medium half-space can be represented as an infinite sum of fractional-order Bessel functions. In order to gain more physical insight into the physical behavior of the problem, in this thesis a closed form solution is formulated which has no infinite sums. The solution is obtained by taking an inverse Laplace transform of the frequency-domain reflection coefficient. This is accomplished by rearranging the frequency-domain reflection coefficient into separate terms which have inverse Laplace transforms which are found in standard tables.

The results obtained using the closed-form solutions are verified through comparison with an inverse fast Fourier transform of the frequency-domain reflection coefficient. For My Parents

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CHAPTER 1

INTRODUCTION AND BACKGROUND

Simple electromagnetic materials are often modeled as having constitutive parameters that are constant with frequency. More complicated materials with frequencydependent parameters are often represented using the Debye model, which is valid for many liquids at moderate frequency. For materials that exhibit resonances, or have parameters that vary rapidly with frequency, the Lorentz model is becoming increasingly more popular, especially when dealing with signals with content at optical frequencies [1].

The propagation and reflection of short duration transient pulses in these dispersive materials has generated much interest, and the effects of dispersion on the shape of the propagating wave, particularly in the Sommerfeld and Brillouin precursors, has been extensively studied [2]-[5]. Recently, the use of short pulses to probe materials has prompted the investigation of the reflection of transient waves from material half spaces of various types [6]-[9].

The transient field reflection of a plane wave from a Lorentz-medium half-space has been calculated previously for both TE polarization [10] and TM polarization [11] by expanding the frequency-domain reflection coefficient using a simple expansion method and taking the inverse Laplace transform of each term in the infinite series. This produces a result which is given as an infinite sum of Bessel functions of fractional-order. While this method produces a convenient solution for numerical techniques, it provides little insight into the behavior of the reflected field.

This thesis proposes a method for formulating the transient reflection coefficient by rearranging the frequency-domain reflection coefficient into a form which enables the inverse Laplace transform to be taken without making an expansion as done previously. This leads to a solution containing a finite number of convolutions of Bessel functions and exponentials, which gives a clearer picture of the behavior of the reflection coefficient. Material parameter and incidence angle choices determine whether the convolution terms contain ordinary or modified Bessel functions. In order to obtain a complete solution to the problem, different sets of parameters are chosen which are representative of all the possible combinations of standard Bessel functions and modified Bessel functions. The various combinations of standard Bessel functions and modified Bessel functions allow for the general behavior of the reflected wave to be predicted from the material choices. A more oscillatory reflection would be expected from a solution containing only standard Bessel functions, while a less oscillatory reflection would be expected from a solution containing only modified Bessel functions.

With certain material parameters, there are some angles of incidence in which the final transient expression for a TM-polarized wave contains a non-causal term. For a TE-polarized wave this is not the case as long as the material is not highly magnetic. Explanation for these non-causal terms are examined in more detail as they arise in formulation.

Once the result is formulated, the transient reflection coefficient is computed numerically and then compared to the inverse fast Fourier transform (FFT).

CHAPTER 2

FREQUENCY DOMAIN REFLECTION COEFFICIENTS

In order to derive the time-domain reflection coefficient for a Lorentz-medium halfspace, the frequency domain reflection coefficient must first be formulated. The most general way to accomplish this is to enforce tangential field continuity across the boundary of the half-space. In this chapter the frequency domain reflection coefficient of an obliquely incident plane wave from a material half-space is derived. This solution is valid for any homogeneous, isotropic material.

2.1 The Frequency Domain Wave Equation

Maxwell's equations for a source-free region of linear, isotropic, homogeneous material for a time-harmonic field are given in point form in terms of $\mathbf{E}(\mathbf{r},\omega)$ and $\mathbf{H}(\mathbf{r},\omega)$ as [12]

$$\nabla \times \mathbf{E} = -j\omega\mu\mathbf{H},\tag{2.1}$$

$$\nabla \times \mathbf{H} = j\omega\epsilon \mathbf{E},\tag{2.2}$$

$$\nabla \cdot \mathbf{E} = 0, \tag{2.3}$$

$$\nabla \cdot \mathbf{H} = 0, \tag{2.4}$$

where ϵ is the frequency dependant complex permittivity. Taking the curl of (2.1) produces

$$\nabla \times \nabla \times \mathbf{E} = -j\omega\mu \left(\nabla \times \mathbf{H}\right)$$
$$= \omega^2 \mu \epsilon \mathbf{E}, \qquad (2.5)$$

where (2.2) has be substituted for $\nabla \times \mathbf{H}$. Utilizing both (2.3) and the vector identity $\nabla \times \nabla \times \mathbf{E} = \nabla (\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E}$, allows (2.5) to be rewritten as

$$\nabla^2 \mathbf{E} + k^2 \mathbf{E} = 0, \tag{2.6}$$

where the wave number in the medium is given as $k = \sqrt{\mu\epsilon}$. This is the homogeneous vector Helmholtz equation for the electric field. By a similar process, the homogeneous vector Helmholtz equation for the magnetic field can be written as

$$\nabla^2 \mathbf{H} + k^2 \mathbf{H} = 0. \tag{2.7}$$

In cartesian coordinates, each component of \mathbf{E} and \mathbf{H} must satisfy the scalar Helmholtz equation

$$\nabla^2 \psi + k^2 \psi = 0. \tag{2.8}$$

The expression for the electric field of a plane wave can be written as

$$\mathbf{E} = \mathbf{E}_0 e^{-j\mathbf{k}\cdot\mathbf{r}},\tag{2.9}$$

where ${\bf k}$ is the wave vector defined as

$$\mathbf{k} = \hat{\mathbf{x}}k_x + \hat{\mathbf{y}}k_y + \hat{\mathbf{z}}k_z, \qquad (2.10)$$

with $|\mathbf{k}| = k$ and \mathbf{r} is the position vector defined as

$$\mathbf{r} = \hat{\mathbf{x}}x + \hat{\mathbf{y}}y + \hat{\mathbf{z}}z. \tag{2.11}$$

The magnetic field for a uniform plane wave is related to the electric field by

$$\mathbf{H} = \frac{\mathbf{k} \times \mathbf{E}}{\omega \mu}.$$
 (2.12)

2.2 Reflection from a Half-Space

The problem of interest is a plane wave in free space (region 1) incident on a material half-space. A portion of the wave is reflected and a portion is transmitted into the material half-space (region 2). The problem geometry can be seen in Figure 2.1. Examining the geometry, it can be seen that since the wave is propagating in the x-z plane, the field is invariant in the y-direction which means $k_y = 0$. It can also be seen from examining the geometry that the wavenumber for the incident wave is given as

$$k_{x0} = k_0 \sin \theta_i, \tag{2.13a}$$

$$k_{z0} = k_0 \cos \theta_i, \tag{2.13b}$$

and the wavenumber for the transmitted wave is given as

$$k_x = k \sin \theta_t, \tag{2.14a}$$

$$k_z = k \cos \theta_t. \tag{2.14b}$$

Any uniform plane wave incident on a planar surface may be decomposed into two orthogonal polarization components, one perpendicular and one parallel to the plane of incidence. The perpendicular polarization is also known as TE polarization, and the parallel polarization is also known as TM polarization. Each of these polarizations can be solved for separately and their solutions can be added together to form a complete solution for the total field.

2.2.1 TE Polarization

The fields for a TE-polarized plane wave incident on a material half-space can be seen in Figure 2.2. The fields for the incident plane wave in free space can be given as

$$\mathbf{E}_{\perp}^{i} = \hat{\mathbf{y}} E_{0}^{i} e^{-jk_{0}(x\sin\theta_{i}+z\cos\theta_{i})}, \qquad (2.15)$$

$$\mathbf{H}_{\perp}^{i} = \frac{E_{0}^{i}}{\eta_{0}} \left(-\hat{\mathbf{x}} \cos \theta_{i} + \hat{\mathbf{z}} \sin \theta_{i} \right) e^{-jk_{0}(x \sin \theta_{i} + z \cos \theta_{i})}.$$
 (2.16)

were $\eta_0 = \sqrt{\mu_0/\epsilon_0}$ and $k_0 = \omega \sqrt{\mu_0 \epsilon_0}$. The total field in region 1 can be expressed as the incident plane wave plus a reflected plane wave. The reflected field is given as

$$\mathbf{E}_{\perp}^{r} = \hat{\mathbf{y}} E_{0}^{r} e^{-jk_{0}(x\sin\theta_{r} - z\cos\theta_{r})}, \qquad (2.17)$$

$$\mathbf{H}_{\perp}^{r} = \frac{E_{0}^{r}}{\eta_{0}} \left(\hat{\mathbf{x}} \cos \theta_{r} + \hat{\mathbf{z}} \sin \theta_{r} \right) e^{-jk_{0}(x \sin \theta_{r} - z \cos \theta_{r})}.$$
 (2.18)

In region 2, the area to the right of the interface, the transmitted field can be represented as a plane wave given as

$$\mathbf{E}_{\perp}^{t} = \hat{\mathbf{y}} E_{0}^{t} e^{-jk(x\sin\theta_{t} + z\cos\theta_{t})}, \qquad (2.19)$$

$$\mathbf{H}_{\perp}^{t} = \frac{E_{0}^{t}}{\eta} \left(-\hat{\mathbf{x}} \cos \theta_{t} + \hat{\mathbf{z}} \sin \theta_{t} \right) e^{-jk(x \sin \theta_{t} + z \cos \theta_{t})}, \tag{2.20}$$

were $\eta = \sqrt{\mu/\epsilon}$. In order to have phase continuity across the interface for all values of x, the exponential terms must be equal at the interface, z = 0. This implies that

$$k_0 \sin \theta_i = k_0 \sin \theta_r = k \sin \theta_t. \tag{2.21}$$

It can be easily deduced from this equation that

$$\theta_i = \theta_r$$
,

$$\frac{\sin \theta_t}{\sin \theta_i} = \frac{k_0}{k} = \sqrt{\frac{\epsilon_0 \mu_0}{\epsilon \mu}}.$$
(2.22)

The boundary conditions at the interface requires the tangential electric fields to be continuous across the interface. This requires

$$\hat{\mathbf{z}} \times \left(\mathbf{E}_{\perp}^{i} + \mathbf{E}_{\perp}^{r} \right) \Big|_{z=0} = \hat{\mathbf{z}} \times \mathbf{E}_{\perp}^{t} \Big|_{z=0}.$$
 (2.23)

Using (2.23) and the fact that the phase is continuous across the interface, and using the expressions for the electric fields it can be seen that

$$E_0^i + E_0^r = E_0^t. (2.24)$$

Dividing this by the incident field amplitude leads to

$$1 + \frac{E_0^r}{E_0^i} = \frac{E_0^t}{E_0^i},$$

$$1 + \Gamma_\perp = T_\perp,$$
(2.25)

where Γ_{\perp} is the reflection coefficient and T_{\perp} is the transmission coefficient.

The boundary conditions also require that the magnetic field be continuous across the interface. This requires

$$\hat{\mathbf{z}} \times \left(\mathbf{H}_{\perp}^{i} + \mathbf{H}_{\perp}^{r}\right)\Big|_{z=0} = \hat{\mathbf{z}} \times \mathbf{H}_{\perp}^{t}\Big|_{z=0}.$$
 (2.26)

Using (2.26) and the fact that the phase is continuous across the interface, and using the expressions for the magnetic field it can be seen that

$$-\frac{E_0^i}{\eta_0}\cos\theta_i + \frac{E_0^r}{\eta_0}\cos\theta_r = -\frac{E_0^t}{\eta}\cos\theta_t.$$
 (2.27)

Dividing by the incident wave amplitude again yields

$$-\frac{1}{\eta_0}\cos\theta_i + \frac{E_0^r}{E_0^i\eta_0}\cos\theta_r = -\frac{E_0^t}{E_0^i\eta}\cos\theta_t, -\frac{1}{\eta_0}\cos\theta_i + \frac{\Gamma_\perp}{\eta_0}\cos\theta_r = -\frac{T_\perp}{\eta}\cos\theta_t.$$
(2.28)

Combining (2.25) and (2.28) allows both Γ_{\perp} and T_{\perp} to be solved for as

$$T_{\perp} = \frac{2Z_{\perp}}{Z_{\perp} + Z_0},\tag{2.29}$$

$$\Gamma_{\perp} = \frac{Z_{\perp} - Z_0}{Z_{\perp} + Z_0},\tag{2.30}$$

with the definitions

$$Z_0 = \frac{\eta_0}{\cos \theta_i},\tag{2.31}$$

$$Z_{\perp} = \frac{\eta}{\cos \theta_t} = \frac{k\eta}{\sqrt{k^2 - k_0^2 \sin^2 \theta_i}}.$$
 (2.32)

In the above expression, using (2.22) $\cos \theta_t$ is given as

$$\cos\theta_t = \frac{\sqrt{k^2 - k_0^2 \sin^2\theta_i}}{k}.$$
(2.33)

2.2.2 TM Polarization

For a TM-polarized plane wave, the method to formulate the reflection and transmission coefficients is similar to the method for the TE case. The fields for a TM-polarized plane wave incident on a material half-space can be seen in Figure 2.3. The fields for the incident plane wave in free-space can be given as

$$\mathbf{E}_{\parallel}^{i} = E_{0}^{i} \left(\hat{\mathbf{x}} \cos \theta_{i} - \hat{\mathbf{z}} \sin \theta_{i} \right) e^{-jk_{0}(x \sin \theta_{i} + z \cos \theta_{i})}, \qquad (2.34)$$

$$\mathbf{H}_{\parallel}^{i} = \hat{\mathbf{y}} \frac{E_{0}^{i}}{\eta_{0}} e^{-jk_{0}(x\sin\theta_{i}+z\cos\theta_{i})}.$$
(2.35)

The reflected and transmitted fields are given as

$$\mathbf{E}_{\parallel}^{r} = E_{0}^{r} \left(\hat{\mathbf{x}} \cos \theta_{r} - \hat{\mathbf{z}} \sin \theta_{r} \right) e^{-jk_{0} \left(x \sin \theta_{r} - z \cos \theta_{r} \right)}, \tag{2.36}$$

$$\mathbf{H}_{\parallel}^{r} = -\hat{\mathbf{y}} \frac{E_{0}^{r}}{\eta_{0}} e^{-jk_{0}(x\sin\theta_{r}-z\cos\theta_{r})}, \qquad (2.37)$$

and

$$\mathbf{E}_{\parallel}^{t} = E_{0}^{t} \left(\hat{\mathbf{x}} \cos \theta_{t} - \hat{\mathbf{z}} \sin \theta_{t} \right) e^{-jk(x \sin \theta_{t} + z \cos \theta_{t})}, \qquad (2.38)$$

$$\mathbf{H}_{\parallel}^{t} = \hat{\mathbf{y}} \frac{E_{0}^{t}}{\eta} e^{-jk(x\sin\theta_{t} + z\cos\theta_{t})}, \qquad (2.39)$$

respectively. Just as in the TE case, enforcing phase continuity across the boundary leads to

$$\theta_i = \theta_r,$$

$$\frac{\sin \theta_t}{\sin \theta_i} = \frac{k_0}{k} = \sqrt{\frac{\epsilon_0 \mu_0}{\epsilon^c \mu}}.$$
(2.40)

Using

$$\hat{\mathbf{z}} \times \left(\mathbf{E}_{\parallel}^{i} + \mathbf{E}_{\parallel}^{r} \right) \Big|_{z=0} = \hat{\mathbf{z}} \times \mathbf{E}_{\parallel}^{t} \Big|_{z=0},$$
(2.41)

yields

$$E_0^i \cos \theta_i + E_0^r \cos \theta_r = E_0^t \cos \theta_t.$$
(2.42)

Dividing by the incident wave amplitude leads to

$$\cos \theta_i + \frac{E_0^r}{E_0^i} \cos \theta_r = \frac{E_0^t}{E_0^i} \cos \theta_t,$$

$$\cos \theta_i + \Gamma_{\parallel} \cos \theta_r = T_{\parallel} \cos \theta_t.$$
 (2.43)

Enforcing tangential field continuity for the magnetic field across the interface requires

$$\hat{\mathbf{z}} \times \left(\mathbf{H}_{\parallel}^{i} + \mathbf{H}_{\parallel}^{r}\right)\Big|_{z=0} = \hat{\mathbf{z}} \times \mathbf{H}_{\parallel}^{t}\Big|_{z=0}, \qquad (2.44)$$

which leads to

$$\frac{E_0^i}{\eta_0} + \frac{E_0^r}{\eta_0} = \frac{E_0^t}{\eta}.$$
 (2.45)

Dividing by the incident wave amplitude leads to

$$\frac{1}{\eta_0} + \frac{E_0^r}{E_0^i} \frac{1}{\eta_0} = \frac{E_0^t}{E_0^i} \frac{1}{\eta},$$

$$\frac{1}{\eta_0} + \frac{\Gamma_{\parallel}}{\eta_0} = \frac{T_{\parallel}}{\eta}.$$
 (2.46)

Combining (2.43) and (2.46) allows Γ_{\parallel} and T_{\parallel} to be solved for as

$$T_{\parallel} = \frac{2Z_{\parallel}}{Z_{\parallel} + Z_0},$$
(2.47)

$$\Gamma_{\parallel} = \frac{Z_{\parallel} - Z_0}{Z_{\parallel} + Z_0},\tag{2.48}$$

with the definitions

$$Z_0 = \eta_0 \cos \theta_i, \tag{2.49}$$

$$Z_{\parallel} = \eta \cos \theta_t = \frac{\eta}{k} \sqrt{k^2 - k_0^2 \sin^2 \theta_i}.$$
 (2.50)



Figure 2.1. Geometry for an incident wave at a discontinuity between two material regions



Figure 2.2. Fields for a TE-polarized plane wave incident on a material half-space.



Figure 2.3. Fields for a TM-polarized plane wave incident on a material half-space.

CHAPTER 3

TE PLANE WAVE REFLECTION FOR THE OPTICAL CASE

The transient reflection from a Lorentz-medium half-space for a plane wave can be found analytically using an inverse Laplace transform technique. The simplest case to examine is that of a TE-polarized plane wave. A steady-state TE-polarized plane wave of frequency ω is obliquely incident on an interface separating free space (region 1) from a homogeneous Lorentz medium (region 2). The angle of incidence θ is measured from the normal to the interface. This geometry can be seen in Figure 2.2. As shown in Chapter 2, the reflection coefficient for a plane wave from a material half-space can be expressed as

$$\Gamma_{\perp}(\omega) = \frac{Z_{\perp}(\omega) - Z_0}{Z_{\perp}(\omega) + Z_0}.$$
(3.1)

For a TE-polarized plane wave, the impedance of the incident wave is $Z_0 = \eta_0 / \cos \theta$ and the wave impedance of the transmitted wave is given by

$$Z_{\perp}(\omega) = \frac{k(\omega)\eta(\omega)}{k_z(\omega)}.$$
(3.2)

where

$$\eta_0 = \sqrt{\mu_0/\epsilon_0},\tag{3.3a}$$

$$\eta = \sqrt{\mu/\epsilon},\tag{3.3b}$$

$$k_z = \sqrt{k^2 - k_0^2 \sin^2 \theta},$$
 (3.3c)

$$k_0 = \omega \sqrt{\mu_0 \epsilon_0},\tag{3.3d}$$

$$k = \omega \sqrt{\mu \epsilon}, \tag{3.3e}$$

$$\epsilon = \epsilon_0 \epsilon_r(\omega). \tag{3.3f}$$

The relative permittivity of a single-resonance Lorentz medium is given by [1]

$$\epsilon_r(\omega) = \epsilon_\infty - \frac{\omega_0^2(\epsilon_s - \epsilon_\infty)}{\omega^2 - 2j\omega\delta - \omega_0^2},\tag{3.4}$$

where ω_0 is the resonance frequency and δ is the damping coefficient. ϵ_s is the static permittivity which is the value of ϵ_r when $\omega = 0$, and ϵ_{∞} is the optical permittivity which is the value of ϵ_r as $\omega \to \infty$. In optical problems, the case when $\epsilon_{\infty} = 1$ and the relative permeability $\mu_r = 1$ is of the most interest. In this case, (3.4) can be rewritten as [4]

$$\epsilon_r(\omega) = 1 + \frac{b^2}{\omega_0^2 - \omega^2 + 2j\omega\delta},\tag{3.5}$$

where b is the plasma frequency of the medium.

3.1 Laplace Domain Representation

A frequency domain quantity can be generalized to the Laplace domain using $s = j\omega$. Using this, (3.5) can be represented in the Laplace domain as

$$\epsilon_r(s) = 1 + \frac{b^2}{s^2 + 2\delta s + \omega_0^2}.$$
(3.6)

The wave number in the Lorentz medium can then be calculated as

$$k(s) = -js\sqrt{\mu\epsilon}$$

= $-js\sqrt{\mu_0\epsilon_0}\sqrt{1 + \frac{b^2}{s^2 + 2\delta s + \omega_0^2}}$
= $-js\sqrt{\mu_0\epsilon_0}\sqrt{\frac{s^2 + 2\delta s + \omega_0^2 + b^2}{s^2 + 2\delta s + \omega_0^2}}.$ (3.7)

It is then convenient to make the substitution

$$s^{2} + 2\delta s + \omega_{0}^{2} = (s - s_{1})(s - s_{2}), \qquad (3.8)$$

where

$$s_{1,2} = -\delta \pm \sqrt{\delta^2 - \omega_0^2},$$
 (3.9)

and also the substitution

$$s^{2} + 2\delta s + \omega_{0}^{2} + b^{2} = (s - s_{3})(s - s_{4}), \qquad (3.10)$$

where

$$s_{3,4} = -\delta \pm \sqrt{\delta^2 - \omega_0^2 - b^2}.$$
 (3.11)

The Laplace domain reflection coefficient can then be written as

$$\Gamma(s) = \frac{k_{z0} - k_z}{k_{z0} + k_z}$$

$$= \frac{\cos\theta - \sqrt{(k/k_0)^2 - \sin^2\theta}}{\cos\theta + \sqrt{(k/k_0)^2 - \sin^2\theta}}$$

$$= \frac{\cos\theta - \sqrt{[(s - s_3)(s - s_4)]/[(s - s_1)(s - s_2)] - \sin^2\theta}}{\cos\theta + \sqrt{[(s - s_3)(s - s_4)]/[(s - s_1)(s - s_2)] - \sin^2\theta}}$$

$$= \frac{\cos\theta\sqrt{s - s_1}\sqrt{s - s_2} - \sqrt{(s - s_3)(s - s_4) - \sin^2\theta(s - s_1)(s - s_2)}}{\cos\theta\sqrt{s - s_1}\sqrt{s - s_2} + \sqrt{(s - s_3)(s - s_4) - \sin^2\theta(s - s_1)(s - s_2)}}.$$
 (3.12)

Expanding $(s - s_1)(s - s_2)$ and $(s - s_3)(s - s_4)$ using (3.8) and (3.10) respectively allows the reflection coefficient to be written as

$$\Gamma(s) = \left[\cos\theta\sqrt{s-s_1}\sqrt{s-s_2} - [s^2(1-\sin^2\theta) + 2\delta s(1-\sin^2\theta) + (\omega_0^2 + b^2 - \omega_0^2\sin^2\theta)]^{1/2} \right] / \left[\cos\theta\sqrt{s-s_1}\sqrt{s-s_2} + [s^2(1-\sin^2\theta) + 2\delta s(1-\sin^2\theta) + (\omega_0^2 + b^2 - \omega_0^2\sin^2\theta)]^{1/2} \right]$$

$$=\frac{\sqrt{s-s_1}\sqrt{s-s_2}-\sqrt{s^2+2\delta s+\omega_0^2+b^2/\cos^2\theta}}{\sqrt{s-s_1}\sqrt{s-s_2}+\sqrt{s^2+2\delta s+\omega_0^2+b^2/\cos^2\theta}}.$$
(3.13)

It is then convenient to make another substitution with the definition

$$s^{2} + 2\delta s + \omega_{0}^{2} + b^{2}/\cos^{2}\theta = (s - s_{5})(s - s_{6}), \qquad (3.14)$$

where

$$s_{5,6} = -\delta \pm \sqrt{\delta^2 - \omega_0^2 - b^2 / \cos^2 \theta}.$$
 (3.15)

Substituting (3.14) into (3.13) allows the reflection coefficient in the Laplace domain to be rewritten as

$$\Gamma(s) = \frac{\sqrt{s - s_1}\sqrt{s - s_2} - \sqrt{s - s_5}\sqrt{s - s_6}}{\sqrt{s - s_1}\sqrt{s - s_2} + \sqrt{s - s_5}\sqrt{s - s_6}}.$$
(3.16)

3.2 Time-Domain Reflection Coefficient

Using the frequency-domain reflection coefficient found in Section 3.1, the timedomain reflection coefficient can be found using an inverse Laplace transform [13]. In order to perform the inverse Laplace transform, the frequency-domain reflection coefficient may be rearranged into a more manageable form. Rationalizing the denominator in (3.16) leads to

$$\Gamma(s) = \frac{(\sqrt{s-s_1}\sqrt{s-s_2} - \sqrt{s-s_5}\sqrt{s-s_6})^2}{(s-s_1)(s-s_2) - (s-s_5)(s-s_6)} = \frac{N}{D}.$$
(3.17)

Examining the denominator term in more detail it can be seen that

$$D = (s - s_1)(s - s_2) - (s - s_5)(s - s_6)$$
$$= (s^2 + 2\delta s + \omega_0^2) - (s^2 + 2\delta s + \omega_0^2 + \frac{b^2}{\cos^2 \theta})$$

$$= -b^2/\cos^2\theta$$
$$= -B^2.$$
(3.18)

The numerator can then be expanded to

$$N = (s - s_1)(s - s_2) - 2\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} + (s - s_5)(s - s_6),$$

$$= [(s - s_1)(s - s_2) - \sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6}] + [(s - s_5)(s - s_6) - \sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6}],$$

$$= g_1(s) + g_2(s).$$
(3.19)

This last separation is taken in order to make the inverse Laplace transform easier to perform.

The invertible form of the reflection coefficient is then given by

$$-B^2\Gamma(s) = g_1(s) + g_2(s), \qquad (3.20)$$

where each term, $g_1(s)$ and $g_2(s)$, can then be inverted separately.

3.2.1 Inversion of the $g_1(s)$ and $g_2(s)$ Terms

When inverting the term $g_1(s)$, it is convenient to make the substitutions

$$s_{1,2} = -\delta \pm \lambda_1, \tag{3.21}$$

$$s_{5,6} = -\delta \pm \lambda_5, \tag{3.22}$$

where

$$\lambda_1 = \sqrt{\delta^2 - \omega_0^2},\tag{3.23a}$$

$$\lambda_5 = \sqrt{\delta^2 - \omega_0^2 - B^2},\tag{3.23b}$$

and B^2 is as defined in (3.18). In order to perform the inverse Laplace transform, $g_1(s)$ may be rearranged into

$$g_1(s) = (s - s_1)(s - s_2)(s - s_5)(s - s_6) \times \left[\frac{1}{(s - s_5)(s - s_6)} - \frac{1}{\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6}}\right].$$
 (3.24)

Using partial fraction expansion, the first term in the brackets can be rewritten in the form

$$\frac{1}{(s-s_5)(s-s_6)} = \frac{K_1}{s-s_5} + \frac{K_2}{s-s_6},$$
(3.25)

where K_1 and K_2 are given by

$$K_1 = \frac{1}{s_5 - s_6} = \frac{1}{2\lambda_5},\tag{3.26a}$$

$$K_2 = \frac{1}{s_6 - s_5} = -\frac{1}{2\lambda_5}.$$
 (3.26b)

Since ω_0^2 and B^2 are both positive numbers, $Re\{s_{5,6}\} < 0$ always. This means the standard inverse Laplace transform [14]

$$\frac{1}{s+\beta} \longleftrightarrow e^{-\beta t} \mathbf{u}(t), \tag{3.27}$$

can be used, where u(t) is a unit step function which is zero for t < 0 and has unit amplitude for $t \ge 0$. Using this identity, (3.25) can be transformed into

$$\frac{1}{(s-s_5)(s-s_6)} \longleftrightarrow \frac{1}{2\lambda_5} \left[e^{s_5 t} - e^{s_6 t} \right] \mathbf{u}(t)$$

$$= \frac{e^{-\delta t}}{2\lambda_5} \left[e^{\lambda_5 t} - e^{-\lambda_5 t} \right] \mathbf{u}(t)$$

$$= \frac{e^{-\delta t}}{\lambda_5} \sinh(\lambda_5 t) \mathbf{u}(t).$$
(3.28)

The second term in the bracket in (3.24) can be transformed into a convolution between two terms if the following inverse Laplace transform is used [14]:

$$\frac{1}{\sqrt{s+\rho}\sqrt{s+\sigma}} \longleftrightarrow e^{-\frac{1}{2}(\rho+\sigma)t} I_0 \left[\frac{1}{2}(\rho-\sigma)t\right] u(t),$$
(3.29)

where $I_n(x)$ is the modified Bessel function of the first kind of order n. Using this, the second term can be transformed into

$$\frac{1}{\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6}} \longleftrightarrow e^{-\delta t} \left[\left\{ \mathbf{I}_0(\lambda_1 t)\mathbf{u}(t) \right\} * \left\{ \mathbf{I}_0(\lambda_5 t)\mathbf{u}(t) \right\} \right].$$
(3.30)

Using (3.8), (3.14), (3.28) and (3.30), and using the differentiation theorem, it is possible to write $g_1(t)$ as

$$g_{1}(t) = \left(\frac{d^{2}}{dt^{2}} + 2\delta \frac{d}{dt} + \omega_{0}^{2}\right) \left(\frac{d^{2}}{dt^{2}} + 2\delta \frac{d}{dt} + \omega_{0}^{2} + B^{2}\right) \times e^{-\delta t} \left[\frac{1}{\lambda_{5}}\sinh(\lambda_{5}t)u(t) - \{I_{0}(\lambda_{1}t)u(t)\} * \{I_{0}(\lambda_{5}t)u(t)\}\right].$$
(3.31)

The next step is to carry out the derivatives. It is important to note at this point that when taking a derivative in time of two signals convolved with respect to time, the derivative only needs to be taken over one of the signals in the convolution. This can be expressed mathematically as

$$\frac{\mathrm{d}}{\mathrm{d}t}(f * g) = \frac{\mathrm{d}f}{\mathrm{d}t} * g = f * \frac{\mathrm{d}g}{\mathrm{d}t}.$$
(3.32)

Defining

$$\overline{g}_1(t) = e^{-\delta t} \left[\frac{1}{\lambda_5} \sinh(\lambda_5 t) \mathbf{u}(t) - \{ \mathbf{I}_0(\lambda_1 t) \mathbf{u}(t) \} * \{ \mathbf{I}_0(\lambda_5 t) \mathbf{u}(t) \} \right],$$
(3.33)

makes the solution easier to compute. The first derivative of $\overline{g}_1(t)$ computed using the product rule is given by

$$\frac{\mathrm{d}}{\mathrm{d}t}\overline{g}_1(t) = -\delta\overline{g}_1(t) + \overline{g}_1'(t), \qquad (3.34)$$

where $\overline{g}'_1(t)$ is the exponential term multiplied by the derivative of the term in the brackets in (3.31). Using the bessel function identity [15]

$$I_0'(x) = I_1(x), (3.35)$$

and the identity

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathbf{u}(t) = \delta(t), \tag{3.36}$$

allows $\overline{g}'_1(t)$ to be written as

$$\overline{g}_{1}'(t) = e^{-\delta t} \left[\cosh(\lambda_{5}t) \mathbf{u}(t) - \lambda_{5} \left\{ \mathbf{I}_{0}(\lambda_{1}t) \mathbf{u}(t) \right\} * \left\{ \mathbf{I}_{1}(\lambda_{5}t) \mathbf{u}(t) \right\} - \mathbf{I}_{0}(\lambda_{1}t) \mathbf{u}(t) \right].$$
(3.37)

In the convolution term, the derivative was taken on the second modified Bessel function containing the argument $\lambda_5 t$. The modified Bessel function of order zero came from the fact that $\{I_0(\lambda_1 t)u(t)\} * \{I_0(\lambda_5 t)\delta(t)\} = I_0(\lambda_1 t)u(t)$. The second derivative is given by

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2}\overline{g}_1(t) = -\delta\left(\frac{\mathrm{d}}{\mathrm{d}t}\overline{g}_1(t)\right) + \frac{\mathrm{d}}{\mathrm{d}t}\overline{g}_1'(t)$$

$$= -\delta\left(-\delta\overline{g}_1(t) + \overline{g}_1'(t)\right) - \delta\overline{g}_1'(t) + \overline{g}_1''(t)$$

$$= \delta^2\overline{g}_1(t) - 2\delta\overline{g}_1(t)' + \overline{g}_1''(t),$$
(3.38)

where $\overline{g}_1''(t)$ is defined as the exponential term multiplied by the derivative of the term in the brackets in (3.37). Using the Bessel function identity [15]

$$\mathbf{I}'_{n}(x) = \frac{1}{2} \left[\mathbf{I}_{n-1}(x) + \mathbf{I}_{n+1}(x) \right], \qquad (3.39)$$

and again takin the derivative on the second modified Bessel function in the convolution term allows $\overline{g}_1''(t)$ to be solved for as

$$\overline{g}_{1}^{\prime\prime}(t) = e^{-\delta t} \left[\lambda_{5} \sinh(\lambda_{5}t) \mathbf{u}(t) - \frac{\lambda_{5}^{2}}{2} \left\{ \mathbf{I}_{0}(\lambda_{1}t) \mathbf{u}(t) \right\} * \left\{ \mathbf{I}_{0}(\lambda_{5}t) \mathbf{u}(t) \right\} - \frac{\lambda_{5}^{2}}{2} \left\{ \mathbf{I}_{0}(\lambda_{1}t) \mathbf{u}(t) \right\} * \left\{ \mathbf{I}_{2}(\lambda_{5}t) \mathbf{u}(t) \right\} - \lambda_{1} \mathbf{I}_{1}(\lambda_{1}t) \mathbf{u}(t) \right].$$
(3.40)

Combining (3.33), (3.34) and (3.38), it can be seen that

$$\left(\frac{\mathrm{d}^2}{\mathrm{d}t^2} + 2\delta\frac{\mathrm{d}}{\mathrm{d}t} + \omega_0^2 + B^2\right) \overline{g}_1(t) = \delta^2 \overline{g}_1(t) - 2\delta \overline{g}_1'(t) + \overline{g}_1''(t) - 2\delta^2 \overline{g}_1(t) + 2\delta \overline{g}_1'(t) + (\omega_0^2 + B^2) \overline{g}_1(t)$$

$$= \overline{g}_1''(t) - (\delta^2 - \omega_0^2 - B^2) \overline{g}_1(t).$$

$$(3.41)$$

Using the definition for λ_5 given in (3.23), (3.41) can be rewritten as

$$\left(\frac{\mathrm{d}^2}{\mathrm{d}t^2} + 2\delta\frac{\mathrm{d}}{\mathrm{d}t} + \omega_0^2 + B^2\right)\overline{g}_1(t) = \overline{g}_1''(t) - \lambda_5^2\overline{g}_1(t)$$

$$= e^{-\delta t} \left[\frac{\lambda_5^2}{2} \left\{ \mathrm{I}_0(\lambda_1 t)\mathrm{u}(t) \right\} * \left\{ \mathrm{I}_0(\lambda_5 t)\mathrm{u}(t) - \mathrm{I}_2(\lambda_5 t)\mathrm{u}(t) \right\} - \lambda_1\mathrm{I}_1(\lambda_1 t)\mathrm{u}(t) \right]$$

$$= e^{-\delta t} \left[\lambda_5 \left\{ \mathrm{I}_0(\lambda_1 t)\mathrm{u}(t) \right\} * \left\{ \frac{\mathrm{I}_1(\lambda_5 t)\mathrm{u}(t)}{t} \right\} - \lambda_1\mathrm{I}_1(\lambda_1 t)\mathrm{u}(t) \right]$$

$$= \overline{h}_1(t), \qquad (3.42)$$

which takes advantage of the identity [15]

$$\frac{2n}{x}\mathbf{I}_n(x) = \mathbf{I}_{n-1}(x) - \mathbf{I}_{n+1}(x).$$
(3.43)

It is then possible to find

$$\frac{\mathrm{d}}{\mathrm{d}t}\overline{h}_1(t) = -\delta\overline{h}_1(t) + \overline{h}_1'(t), \qquad (3.44)$$

where $\overline{h}'_1(t)$ is the exponential term multiplied by the derivative of the term in the brackets in (3.42). Performing the derivative on the first modified Bessel function in the convolution allows $\overline{h}'_1(t)$ to be written as

$$\overline{h}_{1}'(t) = e^{-\delta t} \left[\lambda_{1}\lambda_{5} \left\{ I_{1}(\lambda_{1}t)u(t) \right\} * \left\{ \frac{I_{1}(\lambda_{5}t)u(t)}{t} \right\} + \frac{\lambda_{5}^{2}}{2} [I_{0}(\lambda_{5}t) - I_{2}(\lambda_{5}t)]u(t) - \frac{\lambda_{1}^{2}}{2} [I_{0}(\lambda_{1}t) + I_{2}(\lambda_{1}t)]u(t) \right].$$
(3.45)

The second derivative is then found to be

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2}\overline{h}_1(t) = -\delta \left[\frac{\mathrm{d}}{\mathrm{d}t}\overline{h}_1(t)\right] + \frac{\mathrm{d}}{\mathrm{d}t}\overline{h}_1'(t)
= -\delta \left[-\delta\overline{h}_1(t) + \overline{h}_1'(t)\right] - \delta\overline{h}_1'(t) + \overline{h}_1''(t)
= \delta^2\overline{h}_1(t) - 2\delta\overline{h}_1'(t) + \overline{h}_1''(t),$$
(3.46)

where $\overline{h}_{1}^{\prime\prime}(t)$ is the exponential term multiplied by the derivative of the term in the brackets in (3.45). When taking the derivative of the convolution term, the derivative is taken on the first modified Bessel function. This leads to

$$\overline{h}_1''(t) = e^{-\delta t} \left[\frac{\lambda_1^2 \lambda_5}{2} \left\{ \left[\mathbf{I}_0(\lambda_1 t) + \mathbf{I}_2(\lambda_1 t) \right] \mathbf{u}(t) \right\} * \left\{ \frac{\mathbf{I}_1(\lambda_5 t) \mathbf{u}(t)}{t} \right\} + \frac{1}{2} \left\{ \mathbf{I}_1(\lambda_5 t) \mathbf{u}(t) \mathbf{u}(t) \mathbf{u}(t) \right\} + \frac{1}{2} \left\{ \mathbf{I}_1(\lambda_5 t) \mathbf$$

$$\frac{\lambda_5^3}{4} [\mathbf{I}_1(\lambda_5 t) - \mathbf{I}_3(\lambda_5 t)] \mathbf{u}(t) - \frac{\lambda_1^3}{4} [3\mathbf{I}_1(\lambda_1 t) + \mathbf{I}_3(\lambda_1 t)] \mathbf{u}(t) \Bigg] + \frac{\lambda_5^2 - \lambda_1^2}{2} \delta(t).$$
(3.47)

Combining (3.42),(3.44) and (3.46) it can be seen that

$$\left(\frac{\mathrm{d}^2}{\mathrm{d}t^2} + 2\delta\frac{\mathrm{d}}{\mathrm{d}t} + \omega_0^2\right)\overline{h}_1(t) = \delta^2\overline{h}_1(t) - 2\delta\overline{h}_1'(t) + \overline{h}_1''(t) - 2\delta^2\overline{h}_1(t) + 2\delta\overline{h}_1'(t) + \omega_0^2\overline{h}_1(t) = \overline{h}_1''(t) - \left(\delta^2 - \omega_0^2\right)\overline{h}_1(t).$$
(3.48)

Using the definition for λ_1 given in (3.23), (3.48) can be rewritten as

$$\left(\frac{\mathrm{d}^2}{\mathrm{d}t^2} + 2\delta \frac{\mathrm{d}}{\mathrm{d}t} + \omega_0^2\right)\overline{h}_1(t) = \overline{h}_1''(t) - \lambda_1^2\overline{h}_1(t)$$
$$= g_1(t), \qquad (3.49)$$

which leads to

$$g_1(t) = e^{-\delta t} \left[-\lambda_1^2 \lambda_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{I}}_1(\lambda_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \lambda_5^3 \hat{\mathbf{I}}_2(\lambda_5 t) \right] + \frac{\lambda_5^2 - \lambda_1^2}{2} \delta(t), \quad (3.50)$$

where

$$\hat{\mathbf{I}}_n(x) = \frac{\mathbf{I}_n(x)}{x} \mathbf{u}(x). \tag{3.51}$$

The same approach can be taken to find

$$g_2(t) = e^{-\delta t} \left[-\lambda_1^2 \lambda_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{I}}_1(\lambda_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \lambda_5^3 \hat{\mathbf{I}}_2(\lambda_5 t) \right] - \frac{\lambda_5^2 - \lambda_1^2}{2} \delta(t).$$
(3.52)

3.2.2 Final Expression for $\Gamma(t)$

Substituting $g_1(t)$ from (3.50) and $g_2(t)$ from (3.52) into (3.20) yields the final expression for the reflection coefficient

$$\Gamma(t) = \frac{2}{B^2} e^{-\delta t} \left[\lambda_1^2 \lambda_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{I}}_1(\lambda_5 t) - \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) - \lambda_5^3 \hat{\mathbf{I}}_2(\lambda_5 t) \right].$$
(3.53)

The solution (3.53) is generally valid for all cases, but when λ_1 or λ_5 is imaginary, the modified Bessel functions can be replaced with ordinary Bessel functions according to three possible cases. Case 1 occurs when $\omega_0^2 > \delta^2$. In this case both λ_1 and λ_5 are purely imaginary and defined as

$$-j\lambda_1 = \overline{\lambda}_1 = \sqrt{\omega_0^2 - \delta^2}, \qquad -j\lambda_5 = \overline{\lambda}_5 = \sqrt{\omega_0^2 + B^2 - \delta^2}. \tag{3.54}$$

Then, using the property [15]

$$\mathbf{I}_n(jx) = j^n \mathbf{J}_n(x), \tag{3.55}$$

allows the reflection coefficient to be rewritten as

$$\Gamma(t) = \frac{2}{B^2} e^{-\delta t} \left[\overline{\lambda}_1^2 \overline{\lambda}_5^2 \hat{\mathbf{J}}_1(\overline{\lambda}_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) - \overline{\lambda}_1^3 \hat{\mathbf{J}}_2(\overline{\lambda}_1 t) - \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) \right],$$
(3.56)

where, similar to (3.51),

$$\hat{\mathbf{J}}_n(x) = \frac{\mathbf{J}_n(x)}{x} \mathbf{u}(x).$$
(3.57)

Case 2 occurs when $\omega_0^2 + B^2 < \delta^2$. In this case, both λ_1 and λ_5 are purely real and the same expression from (3.53) can be used. Case 3 occurs when $-B^2 < \omega_0^2 - \delta^2 < 0$. In this case, λ_1 is purely real and λ_5 is purely imaginary. $\overline{\lambda}_5$ is defined as it was in
(3.54) and the expression for the reflection coefficient can be written as

$$\Gamma(t) = -\frac{2}{B^2} e^{-\delta t} \left[\lambda_1^2 \overline{\lambda}_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) \right].$$
(3.58)

3.3 Numerical Results

In order to validate the expressions derived in the previous section, the time-domain reflection coefficient is evaluated numerically in Fortran, and then compared to the inverse FFT of the frequency domain reflection coefficient given in (3.16). The Fortran code is included in Appendix A. The inverse FFT was done using WaveCalc. The frequency-domain data was zero-padded up to the maximum limit allowed by WaveCalc, 32,768, before the inverse FFT was taken. Since the signal had already decayed to zero by this point, no windowing was necessary. A set of parameters corresponding to each of the three possible cases is used. The number of points and step size for the results varied between the different cases.

The first set of parameters is the same as those chosen by Brillouin [16]: $\omega_0 = 4.0 \times 10^{16} \ s^{-1}$, $b^2 = 20.0 \times 10^{32} \ s^{-2}$, $\delta = 0.28 \times 10^{16} \ s^{-1}$. This choice of parameters corresponds to case 1. When computing the numerical results, for the frequency-domain data 16,384 frequency points were calculated with a step size of 8,000 GHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-9} ns. Using $\theta = 30^{\circ}$, (3.56) has been plotted in Figure 3.1 and compared to the inverse FFT. The results show excellent agreement. Since this function includes only standard Bessel functions, which are highly oscillatory, and no modified Bessel functions, which are not oscillatory, the waveform is highly oscillatory and only lightly damped.

The next choice of parameters is: $\omega_0 = 2.0 \times 10^{15} \ s^{-1}$, $b^2 = 20.0 \times 10^{29} \ s^{-2}$, $\delta = 0.28 \times 10^{16} \ s^{-1}$, which corresponds to case 2, (3.53). When computing the numerical results, for the frequency-domain data 4,096 frequency points were calculated with a step size of 400 GHz. In the time-domain, 4,096 points were calculated with a step size

of 1×10^{-8} ns. The results are shown in Figure 3.2. Again, the closed-form expression and the inverse FFT compare well. For this choice of parameters $\delta^2 > \omega_0^2 + B^2$, and the resulting waveform is overdamped, showing no oscillatory behavior and only a single negative peak. Since the expression for case 2 only involves modified Bessel functions, which do not have the oscillatory behavior of ordinary Bessel functions, this observed behavior is easily predicted from the mathematical form of the expression.

The final choice of parameters, which corresponds to case 3, is: $\omega_0 = 2.0 \times 10^{15} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$, which corresponds to case 3, (3.58). When computing the numerical results, for the frequency-domain data 16,384 frequency points were calculated with a step size of 8,000 GHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-9} ns. The analytic expression again matches the inverse FFT, as seen in Figure 3.3. As expected, since $\delta > \omega_0$, but $\delta^2 < \omega_0^2 + B^2$, there is more damping and less oscillation than with case 1, but more oscillation than with case 2. Here the expression for the reflection coefficient has a combination of ordinary and modified Bessel functions.



Figure 3.1. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{16} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 1, Eq. (3.56).



Figure 3.2. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 2.0 \times 10^{15} s^{-1}$, $b^2 = 20.0 \times 10^{29} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 2, Eq. (3.53).



Figure 3.3. Time-domain reflection coefficient with at an angle of $\theta = 30^{\circ}$ with parameter choices of $\omega_0 = 2.0 \times 10^{15} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 3, Eq. (3.58).

CHAPTER 4

TM PLANE WAVE REFLECTION FOR THE OPTICAL CASE

The reflection of a TM plane wave from a Lorentz medium half-space can be found with a similar method as for the TE case. The problem is defined as in Chapter 3 with a plane wave from free space obliquely incident on a homogeneous Lorentz medium at an angle θ measured normal to the interface. This geometry can be seen in Figure 2.3. As shown in Chapter 2, the reflection coefficient for a plane wave from a material half-space can be expressed as

$$\Gamma_{\parallel}(\omega) = \frac{Z_{\parallel}(\omega) - Z_0}{Z_{\parallel}(\omega) + Z_0}.$$
(4.1)

For a TM-polarized plane wave, the impedance of the incident wave is $Z_0 = \eta_0 \cos \theta$ and the wave impedance of the transmitted wave is given by

$$Z_{\parallel}(\omega) = \frac{k_z(\omega)\eta(\omega)}{k(\omega)},\tag{4.2}$$

where the terms k_z, η , and k are defined in (3.3). The relative permittivity is the same as given in (3.5).

4.1 Laplace-Domain Representation

For a TM-polarized plane wave, the Laplace domain reflection coefficient can be written as

$$\Gamma(s) = \frac{k_z - \epsilon_r k_{z0}}{k_z + \epsilon_r k_{z0}}$$
$$= \frac{\sqrt{(k/k_0)^2 - \sin^2 \theta} - \epsilon_r \cos \theta}{\sqrt{(k/k_0)^2 - \sin^2 \theta} + \epsilon_r \cos \theta}$$

$$=\frac{\sqrt{\epsilon_r - \sin^2\theta} - \epsilon_r \cos\theta}{\sqrt{\epsilon_r - \sin^2\theta} + \epsilon_r \cos\theta}.$$
(4.3)

Combining the relative permittivity ϵ_r into one fraction, it can be substituted into (4.3) to give

$$\Gamma(s) = \left[\sqrt{(s^2 + 2\delta s + \omega_0^2 + b^2)/(s^2 + 2\delta s + \omega_0^2) - \sin^2 \theta} - \left[(s^2 + 2\delta s + \omega_0^2 + b^2)/(s^2 + 2\delta s + \omega_0^2 + b^2)/(s^2 + 2\delta s + \omega_0^2) - \sin^2 \theta + \left[(s^2 + 2\delta s + \omega_0^2 + b^2)/(s^2 + 2\delta s + \omega_0^2) \right] \cos \theta \right]$$

$$= \left[\sqrt{s - s_1} \sqrt{s - s_2} \left[s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2) \sin^2 \theta \right]^{1/2} - \left[(s - s_3)(s - s_4) \cos \theta \right] / \left[\sqrt{s - s_1} \sqrt{s - s_2} \left[s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2 + b^2 - (s^2 + 2\delta s + \omega_0^2$$

where $s_{1,2}$ are defined as in (3.9) and $s_{3,4}$ are defined as in (3.11). Using the substitution defined in (3.14), allows (4.4) to be rewritten into the final frequency-domain reflection coefficient

$$\Gamma(s) = \frac{\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6} - (s-s_3)(s-s_4)}{\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6} + (s-s_3)(s-s_4)}.$$
(4.5)

4.2 Time-Domain Reflection Coefficient

Using the frequency-domain reflection coefficient found in Section 4.1, the timedomain reflection coefficient can be found using an inverse Laplace transform. In order to perform the inverse Laplace transform, the frequency-domain reflection coefficient may be rearranged into a more manageable form. Rationalizing the denominator in (4.5) leads to

$$\Gamma(s) = \frac{\left[\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6} - (s-s_3)(s-s_4)\right]^2}{(s-s_1)(s-s_2)(s-s_5)(s-s_6) - (s-s_3)^2(s-s_4)^2} = \frac{N}{D}.$$
 (4.6)

Noting that

$$(s - s_3)(s - s_4) = (s - s_1)(s - s_2) + \frac{b^2}{\cos^2 \theta},$$
(4.7)

allows the denominator to be expanded into

$$D = (s - s_1)(s - s_2) \left[(s - s_1)(s - s_2) + \frac{b^2}{\cos^2 \theta} \right] - \left[(s - s_1)(s - s_2) + b^2 \right]^2$$

= $b^2 \left(\frac{1}{\cos^2 \theta} - 2 \right) (s - s_1)(s - s_2) - b^4$
= $b^2 (\tan^2 \theta - 1)(s^2 + 2\delta s + \omega_0^2) - b^4$
= $b^2 (\tan^2 \theta - 1) \left(s^2 + 2\delta s + \omega_0^2 - \frac{b^2}{\tan^2 \theta - 1} \right)$
= $b^2 (\tan^2 \theta - 1)(s - s_A)(s - s_B),$ (4.8)

where

$$s_{A,B} = -\delta \pm \sqrt{\delta^2 - \omega_0^2 + \frac{b^2}{\tan^2 \theta - 1}}$$
$$= -\delta \pm \lambda_A. \tag{4.9}$$

Using this, (4.6) can be rewritten as

$$b^{2}(\tan^{2}\theta - 1)\Gamma(s) = \frac{\left[\sqrt{s - s_{1}}\sqrt{s - s_{2}}\sqrt{s - s_{5}}\sqrt{s - s_{6}} - (s - s_{3})(s - s_{4})\right]^{2}}{(s - s_{A})(s - s_{B})}.$$
 (4.10)

Using (4.7), the numerator can be expanded into

 $N = (s - s_1)(s - s_2)(s - s_5)(s - s_6) -$

$$2(s - s_3)(s - s_4)\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} + (s - s_3)^2(s - s_4)^2$$

= $(s - s_1)(s - s_2)(s - s_5)(s - s_6) -$
 $2(s - s_1)(s - s_2)\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} -$
 $2b^2\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} + (s - s_1)^2(s - s_2)^2 +$
 $2b^2(s - s_1)(s - s_2) + b^4.$ (4.11)

At this point, factoring out $(s - s_1)(s - s_2)$ allows the numerator to be rewritten in a form that includes both $g_1(s)$ and $g_2(s)$ which are defined and inverted previously in Section 3.2.

$$N = (s - s_1)(s - s_2) \left[(s - s_1)(s - s_2) + (s - s_5)(s - s_6) - 2\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} - 2b^2 \frac{(s - s_5)(s - s_6)}{\sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6}} + \frac{b^2}{(s - s_1)(s - s_2)} + 2b^2 \right]$$

= $(s - s_1)(s - s_2) \left[g_1(s) + g_2(s) - 2b^2 g_3(s) + b^4 g_4(s) + 2b^2 \right].$ (4.12)

In the above equation, the $g_n(s)$ terms are defined as

$$g_1(s) = (s - s_1)(s - s_2) - \sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6},$$
 (4.13a)

$$g_2(s) = (s - s_5)(s - s_6) - \sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6},$$
 (4.13b)

$$g_3(s) = \frac{(s-s_5)(s-s_6)}{\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6}},$$
(4.13c)

$$g_4(s) = \frac{1}{(s-s_1)(s-s_2)}.$$
 (4.13d)

By defining

$$C(s) = \frac{(s - s_1)(s - s_2)}{(s - s_A)(s - s_B)},$$
(4.14)

the reflection coefficient can be rewritten substituting (4.8), (4.12) and (4.14) into (4.6) as

$$b^{2}(\tan^{2}\theta - 1)\Gamma(s) = C(s)\left[g_{1}(s) + g_{2}(s) - 2b^{2}g_{3}(s) + b^{4}g_{4}(s) + 2b^{2}\right]$$

= $C(s)G(s).$ (4.15)

Each term in this expression can be inverted separately to give a final transient reflection coefficient.

4.2.1 Inversion of the $g_n(s)$ Terms

Inversion of the $g_1(s)$ and $g_2(s)$ terms are solved for previously in Section 3.2.1 and are given as

$$g_{1}(t) = e^{-\delta t} \left[-\lambda_{1}^{2}\lambda_{5}^{2}\hat{\mathbf{I}}_{1}(\lambda_{1}t) * \hat{\mathbf{I}}_{1}(\lambda_{5}t) + \lambda_{1}^{3}\hat{\mathbf{I}}_{2}(\lambda_{1}t) + \lambda_{5}^{3}\hat{\mathbf{I}}_{2}(\lambda_{5}t) \right] - \frac{\lambda_{1}^{2} - \lambda_{5}^{2}}{2}\delta(t),$$

$$(4.16)$$

$$g_{2}(t) = e^{-\delta t} \left[-\lambda_{1}^{2}\lambda_{5}^{2}\hat{\mathbf{I}}_{1}(\lambda_{1}t) * \hat{\mathbf{I}}_{1}(\lambda_{5}t) + \lambda_{1}^{3}\hat{\mathbf{I}}_{2}(\lambda_{1}t) + \lambda_{5}^{3}\hat{\mathbf{I}}_{2}(\lambda_{5}t) \right] + \frac{\lambda_{1}^{2} - \lambda_{5}^{2}}{2}\delta(t).$$

$$(4.17)$$

In these equations, λ_1 and λ_5 are defined in (3.23) and $\hat{I}_n(x)$ is defined in (3.51).

The identity from (3.29), redefined below, can be used to perform the inversion on $g_3(s)$ to find $g_3(t)$.

$$\frac{1}{\sqrt{s+\rho}\sqrt{s+\sigma}} \longleftrightarrow e^{-\frac{1}{2}(\rho+\sigma)t} I_0 \left[\frac{1}{2}(\rho-\sigma)t\right] u(t).$$
(4.18)

Using this, it is possible to write

$$g_3(t) = \left(\frac{\mathrm{d}^2}{\mathrm{d}t^2} + 2\delta\frac{\mathrm{d}}{\mathrm{d}t} + \omega_0^2 + \frac{b^2}{\cos^2\theta}\right)e^{-\delta t}\left[\left\{\mathrm{I}_0(\lambda_1 t)\mathrm{u}(t)\right\} * \left\{\mathrm{I}_0(\lambda_5 t)\mathrm{u}(t)\right\}\right]$$

$$= \left(\frac{\mathrm{d}^2}{\mathrm{d}t^2} + 2\delta\frac{\mathrm{d}}{\mathrm{d}t} + \omega_0^2 + \frac{b^2}{\cos^2\theta}\right)\overline{g}_3(t).$$
(4.19)

Taking the first derivative of $\overline{g}_3(t)$ using the product rule yields

$$\frac{\mathrm{d}}{\mathrm{d}t}\overline{g}_{3}(t) = -\delta\overline{g}_{3}(t) + \overline{g}_{3}'(t), \qquad (4.20)$$

where $\overline{g}'_{3}(t)$ is the exponential term multiplied by the derivative of the term in the brackets in (4.19). Taking the derivative on the second term in the convolution allows $\overline{g}'_{3}(t)$ to be written as

$$\overline{g}_{3}'(t) = e^{-\delta t} \left[\lambda_{5} \left\{ I_{0}(\lambda_{1}t)u(t) \right\} * \left\{ I_{1}(\lambda_{5}t)u(t) \right\} + I_{0}(\lambda_{1}t)u(t) \right].$$
(4.21)

From this, the second derivative can be written as

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2}\overline{g}_3(t) = -\delta \left[\frac{\mathrm{d}}{\mathrm{d}t}\overline{g}_3(t)\right] + \frac{\mathrm{d}}{\mathrm{d}t}\overline{g}_3'(t)
= -\delta \left[-\delta\overline{g}_3(t) + \overline{g}_3'(t)\right] - \delta\overline{g}_3'(t) + \overline{g}_3''(t)
= \delta^2\overline{g}_3(t) - 2\delta\overline{g}_3'(t) + \overline{g}_3''(t),$$
(4.22)

where $\overline{g}_{3}''(t)$ is the exponential term multiplied by the derivative of the term in the brackets in (4.21). Using the identity given in (3.39), it can then be shown that

$$\overline{g}_{3}''(t), = e^{-\delta t} \left[\frac{\lambda_{5}^{2}}{2} \left\{ I_{0}(\lambda_{1}t)u(t) \right\} * \left\{ \left[I_{0}(\lambda_{5}t) + I_{2}(\lambda_{5}t) \right]u(t) \right\} + \lambda_{1}I_{1}(\lambda_{1}t)u(t) + \delta(t) \right],$$
(4.23)

where the derivative was again taken on the second term in the convolution. Combining (4.19), (4.20) and (4.22) allows $g_3(t)$ to be written as

$$g_3(t) = \delta^2 \overline{g}_3(t) - 2\delta \overline{g}'_3(t) + \overline{g}''_3(t) - 2\delta^2 \overline{g}_3(t) + 2\delta \overline{g}'_3(t) + (\omega_0^2 + B^2)\overline{g}_3(t)$$

$$=\overline{g}_{3}''(t) - (\delta^{2} - \omega_{0}^{2} - B^{2})\overline{g}_{3}(t).$$
(4.24)

Using the definition for λ_5 given in (3.23), the final expression for $g_3(t)$ is found to be

$$g_{3}(t) = \bar{g}_{3}''(t) - \lambda_{5}^{2} \bar{g}_{3}(t)$$

$$= e^{-\delta t} \left[\frac{\lambda_{5}^{2}}{2} \left\{ I_{0}(\lambda_{1}t)u(t) \right\} * \left\{ [I_{2}(\lambda_{5}t) - I_{0}(\lambda_{5}t)]u(t) \right\} + \lambda_{1}I_{1}(\lambda_{1}t)u(t) \right] + \delta(t)$$

$$= e^{-\delta t} \left[-\lambda_{5}^{2} \left\{ I_{0}(\lambda_{1}t)u(t) \right\} * \hat{I}_{1}(\lambda_{5}t) + \lambda_{1}I_{1}(\lambda_{1}t)u(t) \right] + \delta(t).$$
(4.25)

This took advantage of the Bessel identity defined in (3.43).

The final g-term to invert, $g_4(s)$, is given by (4.12) as

$$\frac{1}{(s-s_1)(s-s_2)}.$$
 (4.26)

Using partial fraction expansion, this term can be rewritten as

$$g_4(s) = \frac{1}{(s-s_1)(s-s_2)}$$

= $\frac{K_1}{s-s_1} + \frac{K_2}{s-s_2},$ (4.27)

where

$$K_1 = \frac{1}{2\lambda_1},\tag{4.28a}$$

$$K_2 = -\frac{1}{2\lambda_1} = -K_1. \tag{4.28b}$$

This allows (4.27) to be rewritten as

$$g_4(s) = \frac{1}{2\lambda_1} \left(\frac{1}{s - s_1} - \frac{1}{s - s_2} \right).$$
(4.29)

Using the identity as defined in (3.27), $g_4(t)$ is found to be

$$g_{4}(t) \longleftrightarrow g_{4}(t) = \frac{1}{2\lambda_{1}} \left[e^{s_{1}t} - e^{s_{2}t} \right] \mathbf{u}(t)$$
$$= \frac{e^{-\delta t}}{2\lambda_{1}} \left[e^{\lambda_{1}t} - e^{-\lambda_{1}t} \right] \mathbf{u}(t)$$
$$= \frac{e^{-\delta t}}{\lambda_{1}} \sinh(\lambda_{1}t)\mathbf{u}(t).$$
(4.30)

Using (4.16), (4.17), (4.25) and (4.30), G(t) from (4.15) can be written as

$$G(t) = 2e^{-\delta t} \left[-\lambda_1^2 \lambda_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{I}}_1(\lambda_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \lambda_5^3 \hat{\mathbf{I}}_2(\lambda_5 t) + b^2 \lambda_5^2 \left\{ \mathbf{I}_0(\lambda_1 t) \mathbf{u}(t) \right\} * \hat{\mathbf{I}}_1(\lambda_5 t) - b^2 \lambda_1 \mathbf{I}_1(\lambda_1 t) \mathbf{u}(t) + \frac{b^4}{2\lambda_1} \sinh(\lambda_1 t) \mathbf{u}(t) \right].$$
(4.31)

4.2.2 Final expression for G(t)

Just as in the TE case in Chapter 3, there are cases where λ_1 or λ_5 can be found to be imaginary and the modified Bessel functions in (4.31) can be replaced with ordinary Bessel functions. These cases occur for the same material properties as in the TE case. Case 1 occurs when $\omega_0^2 > \delta^2$. In this case both λ_1 and λ_5 are purely imaginary and defined as in (3.54). Then, using the property defined in (3.55) to replace modified Bessel functions with standard Bessel functions and noting that

$$\sinh(jx) = j\sin(x),\tag{4.32}$$

it can be seen that

$$G(t) = 2e^{-\delta t} \left[-\overline{\lambda}_1^2 \overline{\lambda}_5^2 \hat{\mathbf{J}}_1(\overline{\lambda}_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) + \overline{\lambda}_1^3 \hat{\mathbf{J}}_2(\overline{\lambda}_1 t) + \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) - b^2 \overline{\lambda}_5^2 \left\{ \mathbf{J}_0(\overline{\lambda}_1 t) \mathbf{u}(t) \right\} * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) + b^2 \overline{\lambda}_1 \mathbf{J}_1(\overline{\lambda}_1 t) \mathbf{u}(t) + \frac{b^4}{2\overline{\lambda}_1} \sin(\overline{\lambda}_1 t) \mathbf{u}(t) \right], \quad (4.33)$$

where $\hat{J}_n(x)$ is defined in (3.57).

Case 2 occurs when $\omega_0^2 + B^2 < \delta^2$. In this case, both λ_1 and λ_5 are purely real and the same expression from (4.31) can be used. Case 3 occurs when $-B^2 < \omega_0^2 - \delta^2 < 0$. In this case, λ_1 is purely real and λ_5 is purely imaginary. $\overline{\lambda}_5$ is defined as it was in (3.54) and the expression for G(t) can be written as

$$G(t) = 2e^{-\delta t} \left[\lambda_1^2 \overline{\lambda}_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) - b^2 \overline{\lambda}_5^2 \left\{ \mathbf{I}_0(\lambda_1 t) \mathbf{u}(t) \right\} * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) - b^2 \lambda_1 \mathbf{I}_1(\lambda_1 t) \mathbf{u}(t) + \frac{b^4}{2\lambda_1} \sinh(\lambda_1 t) \mathbf{u}(t) \right].$$
(4.34)

4.2.3 Inversion of the C(s) Term

The C(s) term is defined in (4.14) as

$$C(s) = \frac{(s-s_1)(s-s_2)}{(s-s_A)(s-s_B)}.$$
(4.35)

Through algebraic manipulation and partial fraction expansion, it can be rewritten into an invertible form as

$$C(s) = 1 + \frac{(s - s_1)(s - s_2) - (s - s_A)(s - s_B)}{(s - s_A)(s - s_B)}$$

= $1 + \frac{(s^2 + 2\delta s + \omega_0^2) - (s^2 + 2\delta s + \omega_0^2 - \frac{b^2}{\tan^2 \theta - 1})}{(s - s_A)(s - s_B)}$
= $1 + \frac{b^2}{(\tan^2 \theta - 1)(s - s_A)(s - s_B)}$
= $1 + \frac{b^2}{2\lambda_A(\tan^2 \theta - 1)} \left[\frac{1}{s - s_A} - \frac{1}{s - s_B}\right].$ (4.36)

The inversion of C(s) depends on the values of s_A and s_B . If $\omega_0^2 > b^2/(\tan^2 \theta - 1)$, C(s) can be inverted using the identity (3.27) into

$$C(s) \longleftrightarrow C(t) = \delta(t) + \frac{b^2}{2\lambda_A(\tan^2\theta - 1)}[e^{sAt} - e^{sBt}]\mathbf{u}(t)$$

$$= \delta(t) + \frac{b^2 e^{-\delta t}}{\lambda_A (\tan^2 \theta - 1)} \sinh(\lambda_A t) \mathbf{u}(t).$$
(4.37)

If $\omega_0^2 > \delta^2 + b^2/(\tan^2 \theta - 1)$, λ_A is purely imaginary and defined as

$$-j\lambda_A = \overline{\lambda}_A = \sqrt{\omega_0^2 - \delta^2 - \frac{b^2}{\tan^2 \theta - 1}}.$$
(4.38)

In this case, using (4.32) C(t) can be simplified into

$$C(t) = \delta(t) + \frac{b^2 e^{-\delta t}}{\overline{\lambda}_A (\tan^2 \theta - 1)} \sin(\overline{\lambda}_A t) \mathbf{u}(t).$$
(4.39)

If $\omega_0^2 > \delta^2 + b^2/(\tan^2 \theta - 1)$, λ_A is real and less than δ . In this case, (4.37) can be used directly. If $\omega_0^2 < b^2/(\tan^2 \theta - 1)$, λ_A is real and greater than δ . In this case $Re\{s_A\} > 0$, which requires the following inverse Laplace transform identity to be used [14]:

$$\frac{1}{s-\beta} \longleftrightarrow -e^{\beta t} \mathbf{u}(-t). \tag{4.40}$$

Using this identity and the identity defined previously in (3.27), C(t) can be written as

$$C(t) = \delta(t) + \frac{b^2 e^{-\delta t}}{2\lambda_A (\tan^2 \theta - 1)} \left[-e^{\lambda_A t} \mathbf{u}(-t) - e^{-\lambda_A t} \mathbf{u}(t) \right]$$

= $\delta(t) - \frac{b^2 e^{-\delta t}}{2\lambda_A (\tan^2 \theta - 1)} e^{-\lambda_A |t|}.$ (4.41)

The crucial issue to address with this decomposition is the fact that this term is non-causal (ie, has non-zero value for t < 0). Further examination of the terms in question show that this case can only occur at angles greater than 45° and between some upper angle limit determined by the material properties. It appears that this non-causality is due to a problem with the model for ϵ_r . A true plane wave is a non-physical construct that is convenient in many cases, but does not exist. When an infinite plane wave is obliquely incident on an infinite half-space, it can be seen that there is no point in time when the wave is not intersecting the half-space. This has the potential to cause problems with causality such as in this case. Ultimately, the non-causal term exists in this case solely due to this fact.

Using the final expressions for G(t) and C(t), the final expression for the reflection coefficient can be written as

$$\Gamma(t) = \frac{1}{b^2(\tan^2\theta - 1)}C(t) * G(t).$$
(4.42)

4.3 Numerical Results

In order to validate the expressions derived in the previous section, the time-domain reflection coefficient is evaluated numerically in Fortran, and then compared to the inverse FFT of the frequency domain reflection coefficient given in (4.5). The Fortran code is included in Appendix B. The inverse FFT was done using WaveCalc. The frequency-domain data was zero-padded up to the maximum limit allowed by Wave-Calc, 32,768, before the inverse FFT was taken. Since the signal had already decayed to zero by this point, no windowing was necessary. A set of parameters corresponding to each of the three possible cases for G(t) is used. The angle is then adjusted for the case 1 parameters to produce results that contain a non-causal contribution. The number of points and step size for the results varied between the different cases.

The first set of parameters is the same as those chosen by Brillouin: $\omega_0 = 4.0 \times 10^{16} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 1. When computing the numerical results, for the frequency-domain data 16,384 frequency points were calculated with a step size of 8,000 GHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-9} ns. Using $\theta = 30^{\circ}$, (4.33) has been plotted in Figure 4.1 and compared to the inverse FFT. The results show excellent agreement. Since this function includes only standard Bessel

functions, which are highly oscillatory, and no modified Bessel functions, which are not oscillatory, the waveform is highly oscillatory and only lightly damped.

The next choice of parameters is: $\omega_0 = 2.0 \times 10^{15} \ s^{-1}$, $b^2 = 20.0 \times 10^{29} \ s^{-2}$, $\delta = 0.28 \times 10^{16} \ s^{-1}$, which corresponds to case 2, (4.31). When computing the numerical results, for the frequency-domain data 32,768 frequency points were calculated with a step size of 400 GHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-9} ns. The results are shown in Figure 4.2. Again, the closed-form expression and the inverse FFT compare well. For this choice of parameters $\delta^2 > \omega_0^2 + B^2$, and the resulting waveform is overdamped, showing no oscillatory behavior and only a single negative peak. Since the expression for case 2 only involves modified Bessel functions, which do not have the oscillatory behavior of ordinary Bessel functions, this observed behavior is easily predicted from the mathematical form of the expression.

The next choice of parameters, which corresponds to case 3, is: $\omega_0 = 2.0 \times 10^{15} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$, which corresponds to case 3, (4.34). When computing the numerical results, for the frequency-domain data 32,768 frequency points were calculated with a step size of 6,000 GHz. In the time-domain, 16,384 points were calculated with a step size of 1×10^{-10} ns. The analytic expression again matches the inverse FFT, as seen in Figure 4.3. As expected, since $\delta > \omega_0$, but $\delta^2 < \omega_0^2 + B^2$, there is more damping and less oscillation than with case 1, but more oscillation than with case 2. Here the expression for the reflection coefficient has a combination of ordinary and modified Bessel functions.

To examine the non-causal result which is possible for the C(t) term, Brillouin's choice of parameters are used again, but at an angle of 50°. This causes the C(t) term to be non-causal as shown in (4.41). When computing the numerical results, for the frequency-domain data 16,384 frequency points were calculated with a step size of 8,000 GHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-9} ns with a starting time value of -4.096×10^{-6} ns. As seen in Figure 4.4, the

expression again matches well with the inverse FFT for t > 0. For t < 0, non-causal term in the analytic expression is extremely small. Unfortunately, the inverse FFT does not have the necessary resolution to capture the small non-causal portion of the reflection coefficient, so it cannot be compared to the analytic expression.

In order to have a better insight into the non-causal term, the delta function term was subtracted from the non-causal C-term and plotted in Figure 4.5. It can immediately be seen that this term is extremely small when compared to the final transient field. In order to examine the non-causality even further, this term is convolved with G(t), as it is in the final expression for the reflection coefficient, and plotted in Figure 4.6. Just as in Figure 4.4, the non-causal term is not even visible in this plot. Taking a closer view of this plot in Figure 4.7 it can be seen that the non-causal portion of the signal is around 3-orders of magnitude less than the causal portion.



Figure 4.1. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{16} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 1, Eq. (4.33).



Figure 4.2. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 2.0 \times 10^{15} s^{-1}$, $b^2 = 20.0 \times 10^{29} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 2, Eq. (4.31).



Figure 4.3. Time-domain reflection coefficient with at an angle of $\theta = 30^{\circ}$ with parameter choices of $\omega_0 = 2.0 \times 10^{15} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 3, Eq. (4.34).



Figure 4.4. Time-domain reflection coefficient with incidence angle $\theta = 50^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{16} s^{-1}$, $b^2 = 20.0 \times 10^{32} s^{-2}$, $\delta = 0.28 \times 10^{16} s^{-1}$. This choice of parameters corresponds to case 1, Eq. (4.33) with non-causal term from Eq. (4.41).



Figure 4.5. Non-causal $C(t) - \delta(t)$ for case 1 results.



Figure 4.6. Non-causal $[C(t) - \delta(t)] * G(t)$ for case 1 results.



Figure 4.7. Close-up of the non-causal $[C(t) - \delta(t)] * G(t)$ for case 1 results.

CHAPTER 5

TE PLANE WAVE REFLECTION FOR THE GENERAL CASE

In Chapter 3, the transient reflection of a TE plane-wave from the Lorentz-medium half-space is examined for a Lorentz-medium simplified to the optical case. In this chapter, the reflection coefficient will be examined for the most general case. As in the Chapter 3, a steady-state TE-polarized plane wave of frequency ω is obliquely incident on an interface separating free space (region 1) from a homogeneous Lorentz medium (region 2). The angle of incidence θ is measured from the normal to the interface. This geometry can be seen in Figure 2.2. As shown in Chapter 2, the reflection coefficient for a plane wave from a material half-space can be expressed as

$$\Gamma_{\perp}(\omega) = \frac{Z_{\perp}(\omega) - Z_0}{Z_{\perp}(\omega) + Z_0}.$$
(5.1)

For a TE-polarized plane wave, the impedance of the incident wave is $Z_0 = \eta_0 / \cos \theta$ and the wave impedance of the transmitted wave is given by

$$Z_{\perp}(\omega) = \frac{k(\omega)\eta(\omega)}{k_z(\omega)},$$
(5.2)

where the terms k_z , η , and k are defined in (3.3). The relative permittivity is the same as given in (3.4). For the general case, the simplifications made in Chapter 3 cannot be made, but the relative permittivity can be rewritten as

$$\epsilon_r(\omega) = \epsilon_\infty + \frac{b^2}{\omega_0^2 - \omega^2 + 2j\omega\delta},\tag{5.3}$$

where b is the plasma frequency of the medium.

5.1 Laplace Domain Representation

Equation (5.3) can be represented in the Laplace domain as

$$\epsilon_r(s) = \epsilon_\infty + \frac{b^2}{s^2 + 2\delta s + \omega_0^2}.$$
(5.4)

Using this, the wave number in the Lorentz medium can then be calculated as

$$k(s) = -js\sqrt{\mu\epsilon}$$

$$= -js\sqrt{\mu\epsilon_0}\sqrt{\epsilon_\infty + \frac{b^2}{s^2 + 2\delta s + \omega_0^2}}$$

$$= -js\sqrt{\mu\epsilon_0\epsilon_\infty}\sqrt{\frac{s^2 + 2\delta s + \omega_0^2 + b^2/\epsilon_\infty}{s^2 + 2\delta s + \omega_0^2}}.$$
(5.5)

For a TE-polarized plane wave, the Laplace domain reflection coefficient can then be written as

$$\Gamma(s) = \frac{\mu_r k_{z0} - k_z}{\mu_r k_{z0} + k_z} = \frac{\mu_r \cos\theta - \sqrt{(k/k_0)^2 - \sin^2\theta}}{\mu_r \cos\theta + \sqrt{(k/k_0)^2 - \sin^2\theta}} = \frac{\mu_r \cos\theta - \sqrt{\mu_r \epsilon_{\infty}(s - s_3)(s - s_4)/[(s - s_1)(s - s_2)] - \sin^2\theta}}{\mu_r \cos\theta + \sqrt{\mu_r \epsilon_{\infty}(s - s_3)(s - s_4)[(s - s_1)(s - s_2)] - \sin^2\theta}},$$
(5.6)

where $s_{1,2}$ are the same as defined in (3.9) and $s_{3,4}$ are defined as

$$s_{3,4} = -\delta \pm \sqrt{\delta^2 - \omega_0^2 - \frac{b^2}{\epsilon_\infty}},\tag{5.7}$$

which is derived from the fact that

$$s^{2} + 2\delta s + \omega_{0}^{2} + \frac{b^{2}}{\epsilon_{\infty}} = (s - s_{3})(s - s_{4}).$$
(5.8)

Multiplying the numerator and denominator in (5.6) by $\sqrt{(s-s_1)(s-s_2)}$ and expanding $(s-s_1)(s-s_2)$ and $(s-s_3)(s-s_4)$ leads to

$$\Gamma(s) = \frac{\mu_r \cos\theta \sqrt{(s-s_1)(s-s_2)} - \sqrt{\mu_r \epsilon_{\infty}(s-s_3)(s-s_4) - \sin^2\theta(s-s_1)(s-s_2)}}{\mu_r \cos\theta \sqrt{(s-s_1)(s-s_2)} + \sqrt{\mu_r \epsilon_{\infty}(s-s_3)(s-s_4) - \sin^2\theta(s-s_1)(s-s_2)}} \\ = \left[\mu_r \cos\theta \sqrt{(s-s_1)(s-s_2)} - \left(s^2(\mu_r \epsilon_{\infty} - \sin^2\theta) + 2\delta s(\mu_r \epsilon_{\infty} - \sin^2\theta) + 2\delta s(\mu_r \epsilon_{\infty} - \sin^2\theta) + \omega_0^2(\mu_r \epsilon_{\infty} - \sin^2\theta) + \mu_r b^2 \right)^{1/2} \right] / \left[\mu_r \cos\theta \sqrt{(s-s_1)(s-s_2)} + \left(s^2(\mu_r \epsilon_{\infty} - \sin^2\theta) + 2\delta s(\mu_r \epsilon_{\infty} - \sin^2\theta) + \omega_0^2(\mu_r \epsilon_{\infty} - \sin^2\theta) + \mu_r b^2 \right)^{1/2} \right].$$
(5.9)

For convenience, define

$$K^2 = \mu_r \epsilon_\infty - \sin^2 \theta. \tag{5.10}$$

This allows (5.9) to be written as

$$\Gamma(s) = \frac{\mu_r \cos\theta\sqrt{(s-s_1)(s-s_2)} - K\sqrt{s^2 + 2\delta s + \omega_0^2 + \mu_r b^2/K^2}}{\mu_r \cos\theta\sqrt{(s-s_1)(s-s_2)} + K\sqrt{s^2 + 2\delta s + \omega_0^2 + \mu_r b^2/K^2}}.$$
(5.11)

It is then convenient to make the substitution

$$s^{2} + 2\delta s + \omega_{0}^{2} + \mu_{r} \frac{b^{2}}{K^{2}} = (s - s_{5})(s - s_{6}), \qquad (5.12)$$

where

$$s_{5,6} = -\delta \pm \sqrt{\delta^2 - \omega_0^2 - \mu_r \frac{b^2}{K^2}}.$$
(5.13)

Substituting (5.12) into (5.11) allows the reflection coefficient in the Laplace domain to be rewritten as

$$\Gamma(s) = \frac{\mu_r \cos \theta \sqrt{s - s_1} \sqrt{s - s_2} - K \sqrt{s - s_5} \sqrt{s - s_6}}{\mu_r \cos \theta \sqrt{s - s_1} \sqrt{s - s_2} + K \sqrt{s - s_5} \sqrt{s - s_6}}.$$
(5.14)

5.2 Time-Domain Reflection Coefficient

Using the frequency-domain reflection coefficient found in Section 5.1, the timedomain reflection coefficient can be found using an inverse Laplace transform. In order to perform the inverse Laplace transform, the frequency-domain reflection coefficient may be rearranged into a more manageable form. Before this can be done however, it must be noted that as $s \longrightarrow \infty$, the reflection coefficient does not tend to zero. Instead it can be seen that

as
$$s \longrightarrow \infty$$
 $\Gamma(s) \longrightarrow \frac{\mu_r \cos \theta - K}{\mu_r \cos \theta + K}$. (5.15)

This term results in a delta function contribution in the final time-domain reflection coefficient. In order to perform the inverse Laplace transform, this term, defined as Γ_{∞} , needs to be subtracted from the total reflection coefficient. This leads to

$$\widetilde{\Gamma}(s) = \Gamma(s) - \Gamma_{\infty}$$

$$= \frac{\mu_r \cos\theta \sqrt{s - s_1} \sqrt{s - s_2} - K\sqrt{s - s_5} \sqrt{s - s_6}}{\mu_r \cos\theta \sqrt{s - s_1} \sqrt{s - s_2} + K\sqrt{s - s_5} \sqrt{s - s_6}} - \frac{\mu_r \cos\theta - K}{\mu_r \cos\theta + K}$$

$$= \frac{2K\mu_r \cos\theta \left[\sqrt{s - s_1} \sqrt{s - s_2} - \sqrt{s - s_5} \sqrt{s - s_6}\right]}{(\mu_r \cos\theta + K) (\mu_r \cos\theta \sqrt{s - s_1} \sqrt{s - s_2} + K\sqrt{s - s_5} \sqrt{s - s_6})}.$$
(5.16)

Rationalizing the denominator leads to

$$\widetilde{\Gamma}(s) = \begin{bmatrix} 2K\mu_r \cos\theta \left(\sqrt{s-s_1}\sqrt{s-s_2} - \sqrt{s-s_5}\sqrt{s-s_6}\right) \left(\mu_r \cos\theta\sqrt{s-s_1}\sqrt{s-s_2} - K\sqrt{s-s_5}\sqrt{s-s_6}\right) \end{bmatrix} / \left[(\mu_r \cos\theta + K) \left[\mu_r^2 \cos^2\theta (s-s_1)(s-s_2) - K^2 (s-s_5)(s-s_6)\right] \right]$$

$$= F_1 \frac{N}{D}, \qquad (5.17)$$

where

$$F_1 = \frac{2K\mu_r\cos\theta}{\mu_r\cos\theta + K}.$$
(5.18)

Expanding the terms in the denominator and examining them in further detail, it can be seen that

$$D = \mu_r^2 \cos^2 \theta (s^2 + 2\delta s + \omega_0^2) - K^2 (s^2 + 2\delta s + \omega_0^2 + \frac{\mu_r b^2}{K^2})$$

= $s^2 (\mu_r^2 \cos^2 \theta - K^2) + 2\delta s (\mu_r^2 \cos^2 \theta - K^2) + \omega_0^2 (\mu_r^2 \cos^2 \theta - K^2) - \mu_r b^2$
= $(\mu_r^2 \cos^2 \theta - K^2) \left(s^2 + 2\delta s + \omega_0^2 - \frac{\mu_r b^2}{\mu_r^2 \cos^2 \theta - K^2} \right)$
= $(\mu_r^2 \cos^2 \theta - K^2) \left(s^2 + 2\delta s + \gamma^2 \right),$ (5.19)

with the definition

$$\gamma^2 = \omega_0^2 - \frac{\mu_r b^2}{\mu_r^2 \cos^2 \theta - K^2}.$$
 (5.20)

At this point, it is convenient to define

$$s^{2} + 2\delta s + \gamma^{2} = (s - s_{C})(s - s_{D}), \qquad (5.21)$$

where

$$s_{C,D} = -\delta \pm \sqrt{\delta^2 - \gamma^2}$$
$$= -\delta \pm \lambda_C. \tag{5.22}$$

Substituting (5.21) into (5.19) allows the denominator to be written in its final form as

$$D = (\mu_r^2 \cos^2 \theta - K^2)(s - s_C)(s - s_D).$$
(5.23)

Expanding the numerator and examining it in further detail leads to

$$N = \mu_r \cos\theta \left[(s - s_1)(s - s_2) - \sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} \right] + K \left[(s - s_5)(s - s_6) - \sqrt{s - s_1}\sqrt{s - s_2}\sqrt{s - s_5}\sqrt{s - s_6} \right]$$
$$= \mu_r \cos\theta g_1(s) + K g_2(s). \tag{5.24}$$

Applying the following definition

$$F = \frac{2K\mu_r\cos\theta}{(\mu_r\cos\theta + K)^2(\mu_r\cos\theta - K)},\tag{5.25}$$

allows the Laplace domain reflection coefficient to be rewritten by substituting (5.23)and (5.24) into (5.17) as

$$\widetilde{\Gamma}(s) = F \frac{\mu_r \cos\theta g_1(s) + K g_2(s)}{(s - s_C)(s - s_D)}$$
$$= FC(s)G(s),$$
(5.26)

where it is defined that

$$C(s) = \frac{1}{(s - s_C)(s - s_D)},$$
(5.27a)

$$G(s) = \mu_r \cos\theta g_1(s) + Kg_2(s). \tag{5.27b}$$

5.2.1 Inversion of the G(s) Term

Both terms $g_1(s)$ and $g_2(s)$ in G(s) were inverted previously in Section 3.2.1. The solutions are given as

$$g_{1}(t) = e^{-\delta t} \left[-\lambda_{1}^{2} \lambda_{5}^{2} \hat{\mathbf{I}}_{1}(\lambda_{1} t) * \hat{\mathbf{I}}_{1}(\lambda_{5} t) + \lambda_{1}^{3} \hat{\mathbf{I}}_{2}(\lambda_{1} t) + \lambda_{5}^{3} \hat{\mathbf{I}}_{2}(\lambda_{5} t) \right] - \frac{\lambda_{1}^{2} - \lambda_{5}^{2}}{2} \delta(t),$$
(5.28)

$$g_{2}(t) = e^{-\delta t} \left[-\lambda_{1}^{2} \lambda_{5}^{2} \hat{\mathbf{I}}_{1}(\lambda_{1} t) * \hat{\mathbf{I}}_{1}(\lambda_{5} t) + \lambda_{1}^{3} \hat{\mathbf{I}}_{2}(\lambda_{1} t) + \lambda_{5}^{3} \hat{\mathbf{I}}_{2}(\lambda_{5} t) \right] + \frac{\lambda_{1}^{2} - \lambda_{5}^{2}}{2} \delta(t).$$
(5.29)

In these equations, λ_1 and λ_5 are defined from

$$s_{1,2} = -\delta \pm \lambda_1, \tag{5.30}$$

$$s_{5,6} = -\delta \pm \lambda_5, \tag{5.31}$$

and $\hat{I}_n(x)$ is defined in (3.51). The final expression for G(t) can then be given as

$$G(t) = (\mu_r \cos\theta + K)e^{-\delta t} \left[-\lambda_1^2 \lambda_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{I}}_1(\lambda_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \lambda_5^3 \hat{\mathbf{I}}_2(\lambda_5 t) \right] - \frac{\mu_r b^2}{2K^2} (\mu_r \cos\theta - K)\delta(t).$$
(5.32)

Just as in the optical TE case in Chapter 3, there are cases where λ_1 or λ_5 can be found to be imaginary and the modified Bessel functions in (5.32) can be replaced with ordinary Bessel functions. Case 1 occurs when $\omega_0^2 > \delta^2$. In this case both λ_1 and λ_5 are purely imaginary and defined as

$$-j\lambda_1 = \overline{\lambda}_1 = \sqrt{\omega_0^2 - \delta^2}, \qquad -j\lambda_5 = \overline{\lambda}_5 = \sqrt{\omega_0^2 + \frac{\mu_r b^2}{K^2} - \delta^2}.$$
 (5.33)

Then, using the identity given in (3.55) to replace modified Bessel functions with ordinary Bessel functions and the identity given in (4.32), (5.32) can be expressed as

$$G(t) = (\mu_r \cos\theta + K)e^{-\delta t} \left[-\overline{\lambda}_1^2 \overline{\lambda}_5^2 \hat{\mathbf{J}}_1(\overline{\lambda}_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) + \overline{\lambda}_1^3 \hat{\mathbf{J}}_2(\overline{\lambda}_1 t) + \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) \right] - \frac{\mu_r b^2}{2K^2} (\mu_r \cos\theta - K)\delta(t),$$
(5.34)

where $\hat{J}_n(x)$ was defined in (3.57).

Case 2 occurs when $\omega_0^2 + \mu_r b^2 / K^2 < \delta^2$. In this case, both λ_1 and λ_5 are purely real and the same expression from (5.32) can be used. Case 3 occurs when $-\mu_r b^2 / K^2 < \omega_0^2 - \delta^2 < 0$. In this case, λ_1 is purely real and λ_5 is purely imaginary. $\overline{\lambda}_5$ is defined as it was in (5.33) and the expression for G(t) can be written as

$$G(t) = (\mu_r \cos\theta + K)e^{-\delta t} \left[\lambda_1^2 \overline{\lambda}_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) \right] - \frac{\mu_r b^2}{2K^2} (\mu_r \cos\theta - K)\delta(t).$$
(5.35)

5.2.2 Inversion of the C(s) Term

Using partial fraction expansion, C(s) can be rearranged into

$$C(s) = \frac{1}{(s - s_C)(s - s_D)} = \frac{1}{2\lambda_C} \left(\frac{1}{s - s_C} - \frac{1}{s - s_D} \right).$$
(5.36)

As in previous cases, the values of s_C and s_D affect the inversion of C(s). If $\gamma^2 > 0$, then $Re\{s_{C,D}\} < 0$ and the inversion identity (3.27) can be used. Using this identity, C(t) is found to be

$$C(t) = \frac{e^{-\delta t}}{2\lambda_C} \left(e^{\lambda_C t} - e^{-\lambda_C t} \right) \mathbf{u}(t)$$

= $\frac{e^{-\delta t}}{\lambda_C} \sinh(\lambda_C t) \mathbf{u}(t).$ (5.37)

If $\gamma^2 < \delta^2$, λ_C is purely real and (5.37) can be used directly. If $\gamma^2 > \delta^2$, λ_C is purely imaginary and can be defined as

$$-j\lambda_C = \overline{\lambda}_C = \sqrt{\gamma^2 - \delta^2}.$$
 (5.38)

In this case, using the identity given in (4.32), (5.37) can be rewritten into

$$C(t) = \frac{e^{-\delta t}}{\overline{\lambda}_C} \sin(\overline{\lambda}_C t) \mathbf{u}(t).$$
(5.39)

If $\gamma^2 < 0$, λ_C is again purely real, but in this case, $Re\{s_c\} > 0$, which requires the identity given in (4.40) to be used. In this case, C(t) is given as

$$C(t) = -\frac{e^{-\delta t}}{2\lambda_C} \left(e^{\lambda_C t} \mathbf{u}(-t) + e^{-\lambda_C t} \mathbf{u}(t) \right)$$
$$= -\frac{e^{-\delta t}}{2\lambda_C} e^{-\lambda_C |t|}.$$
(5.40)

As in Chapter 4 for the TM optical case, there is a problem with causality in this term, however an interesting result can be observed by examining the γ^2 term. In order for $\gamma^2 < 0$ to occur, the following relationship must hold:

$$\omega_0^2 < \frac{\mu_r b^2}{\mu_r^2 \cos^2 \theta - K^2}.$$
 (5.41)

Examining the denominator on the right side of the equation in closer detail reveals that as long as $\mu_r < \epsilon_{\infty}$, the denominator is negative at any angle. Since this is not the optical case, it holds that $\epsilon_{\infty} > 1$. The Lorentz model is generally used for a dielectric material, so it is expected that $\mu_r < \epsilon_{\infty}$ will hold in general. This implies that the causality issue is not a concern in this case.

5.3 Numerical Results

In order to validate the expressions derived in the previous section, the time-domain reflection coefficient is evaluated numerically in Fortran, and then compared to the inverse FFT of the frequency-domain reflection coefficient given in (5.16). The Fortran code is included in Appendix C. The inverse FFT was done using WaveCalc.

The frequency-domain data was zero-padded up to the maximum limit allowed by WaveCalc, 32,768, before the inverse FFT was taken. Since the signal had already decayed to zero by this point, no windowing was necessary. A set of parameters corresponding to each of the three possible cases is used.

The first set of parameters chosen are: $\omega_0 = 4.0 \times 10^{11} s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_{\tau} = 1$. This choice of parameters corresponds to case 1. When computing the numerical results, for the frequency-domain data 4,096 frequency points were calculated with a step size of 400 MHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-4} ns. Using $\theta = 30^{\circ}$, (5.34) has been plotted in Figure 5.1 and compared to the inverse FFT. The results show excellent agreement. Since this function includes only standard Bessel functions, which are highly oscillatory, and no modified Bessel functions, which are not oscillatory, the waveform is highly oscillatory and only lightly damped.

The next choice of parameters is: $\omega_0 = 4.0 \times 10^{10} s^{-1}$, $b = 6.24 \times 10^{10} s^{-1}$, $\delta = 2.5 \times 10^{11} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$, which corresponds to case 2, (5.32). When computing the numerical results, for the frequency-domain data 32,768 frequency points were calculated with a step size of 4 MHz. In the time-domain, 8,192 points were calculated with a step size of 2×10^{-4} ns. The results are shown in Figure 5.2. Again, the closed-form expression and the inverse FFT compare well. For this choice of parameters $\omega_0^2 + \mu_r b^2/K^2 < \delta^2$, and the resulting waveform is overdamped, showing no oscillatory behavior and only a single negative peak. Since the expression for case 2 only involves modified Bessel functions, which do not have the oscillatory behavior of ordinary Bessel functions, this observed behavior is easily predicted from the mathematical form of the expression.

The final choice of parameters, which corresponds to case 3, is: $\omega_0 = 4.0 \times 10^9 \ s^{-1}$, $b = 6.24 \times 10^{11} \ s^{-1}$, $\delta = 2.5 \times 10^{10} \ s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_{\tau} = 1$, which corresponds to case 3, (5.35). When computing the numerical results, for the frequency-domain data 8,192 frequency points were calculated with a step size of 200 MHz. In the time-domain, 4,096 points were calculated with a step size of 1×10^{-4} ns. The analytic expression again matches the inverse FFT, as seen in Figure 5.3. As expected, since $\delta^2 > \omega_0^2$, but $\delta^2 < \omega_0^2 + \mu_r b^2/K^2$, there is more damping and less oscillation than with case 1, but more oscillation than with case 2. Here the expression for the reflection coefficient has a combination of ordinary and modified Bessel functions.


Figure 5.1. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{11} s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 1, Eq. (5.34).



Figure 5.2. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{10} s^{-1}$, $b = 6.24 \times 10^{10} s^{-1}$, $\delta = 2.5 \times 10^{11} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 2, Eq. (5.32).



Figure 5.3. Time-domain reflection coefficient with at an angle of $\theta = 30^{\circ}$ with parameter choices of $\omega_0 = 4.0 \times 10^9 s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 3, Eq. (5.35).

CHAPTER 6

TM PLANE WAVE REFLECTION FOR THE GENERAL CASE

In Chapter 4, the transient reflection of a TM plane-wave from a Lorentz-medium half-space is examined for a Lorentz-medium simplified to the optical case. In this chapter, the reflection coefficient will be examined for the most general case. As in the Chapter 4, a steady-state TM-polarized plane wave of frequency ω is obliquely incident on an interface separating free space (region 1) from a homogeneous Lorentz medium (region 2). The angle of incidence θ is measured from the normal to the interface. This geometry can be seen in Figure 2.3. As shown in Chapter 2, the reflection coefficient for a plane wave from a material half-space can be expressed as

$$\Gamma_{\parallel}(\omega) = \frac{Z_{\parallel}(\omega) - Z_0}{Z_{\parallel}(\omega) + Z_0}.$$
(6.1)

For a TM-polarized plane wave, the impedance of the incident wave is $\eta_0 \cos \theta$ and the wave impedance of the transmitted wave is given by

$$Z_{\parallel}(\omega) = \frac{k_z(\omega)\eta(\omega)}{k(\omega)}.$$
(6.2)

where the terms k_z, η , and k are defined in (3.3). The relative permittivity is the same as given in (5.3).

6.1 Laplace Domain Representation

The Laplace domain reflection coefficient for a TM-polarized plane wave can be written as

$$\Gamma(s) = \frac{k_z - \epsilon_r k_{z0}}{k_z + \epsilon_r k_{z0}}$$

$$= \frac{\sqrt{(k/k_0)^2 - \sin^2 \theta} - \epsilon_r \cos \theta}{\sqrt{(k/k_0)^2 - \sin^2 \theta} + \epsilon_r \cos \theta}$$

$$= \frac{\sqrt{\mu_r \epsilon_r - \sin^2 \theta} - \epsilon_r \cos \theta}{\sqrt{\mu_r \epsilon_r - \sin^2 \theta} + \epsilon_r \cos \theta}$$

$$= \left[[\mu_r \epsilon_{\infty} (s - s_3)(s - s_4)/[(s - s_1)(s - s_2)] - \sin^2 \theta]^{1/2} - \epsilon_{\infty} \cos \theta (s - s_3)(s - s_4)/[(s - s_1)(s - s_2)] \right] / \left[[\mu_r \epsilon_{\infty} (s - s_3)(s - s_4)/[(s - s_1)(s - s_2)] - \sin^2 \theta]^{1/2} + \epsilon_{\infty} \cos \theta (s - s_3)(s - s_4)/[(s - s_1)(s - s_2)] - \sin^2 \theta]^{1/2} + \epsilon_{\infty} \cos \theta (s - s_3)(s - s_4)/[(s - s_1)(s - s_2)] \right], \quad (6.3)$$

where $s_{1,2}$ are the same as defined in (3.9) and $s_{3,4}$ are the same as defined in (5.7). Multiplying the numerator and denominator by $\sqrt{(s-s_1)(s-s_2)}$ and expanding $(s-s_1)(s-s_2)$ and $(s-s_3)(s-s_4)$ leads to

$$\Gamma(s) = \left[\sqrt{s - s_1} \sqrt{s - s_2} [\mu_r \epsilon_{\infty} (s - s_3)(s - s_4) - \sin^2 \theta(s - s_1)(s - s_2)]^{1/2} - \epsilon_{\infty} (s - s_3)(s - s_4) \cos \theta \right] / \left[\sqrt{s - s_1} \sqrt{s - s_2} [\mu_r \epsilon_{\infty} (s - s_3)(s - s_4) - \sin^2 \theta(s - s_1)(s - s_2)]^{1/2} + \epsilon_{\infty} (s - s_3)(s - s_4) \cos \theta \right]$$

$$= \left[\sqrt{s - s_1} \sqrt{s - s_2} \left[(\mu_r \epsilon_{\infty} - \sin^2 \theta) s^2 + 2\delta s(\mu_r \epsilon_{\infty} - \sin^2 \theta) + \omega_0^2 (\mu_r \epsilon_{\infty} - \sin^2 \theta) + \mu_r b^2 \right]^{1/2} - \epsilon_{\infty} \cos \theta(s - s_3)(s - s_4) \right] / \left[\sqrt{s - s_1} \sqrt{s - s_2} \left[(\mu_r \epsilon_{\infty} - \sin^2 \theta) s^2 + 2\delta s(\mu_r \epsilon_{\infty} - \sin^2 \theta) + \omega_0^2 (\mu_r \epsilon_{\infty} - \sin^2 \theta) + \mu_r b^2 \right]^{1/2} + \epsilon_{\infty} \cos \theta(s - s_3)(s - s_4) \right] . \quad (6.4)$$

Substituting K^2 as defined in (5.10) allows (6.4) to be written as

$$\Gamma(s) = \frac{K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s^2+2\delta s+\omega_0^2+\mu_r b^2/K^2} - \epsilon_\infty \cos\theta(s-s_3)(s-s_4)}{K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s^2+2\delta s+\omega_0^2+\mu_r b^2/K^2} + \epsilon_\infty \cos\theta(s-s_3)(s-s_4)}.$$
(6.5)

Substituting (5.12) into (6.5) allows the final form of the reflection coefficient to be rewritten as

$$\Gamma(s) = \frac{K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6} - \epsilon_{\infty}\cos\theta(s-s_3)(s-s_4)}{K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6} + \epsilon_{\infty}\cos\theta(s-s_3)(s-s_4)}.$$
 (6.6)

6.2 Time-Domain Reflection Coefficient

Using the frequency-domain reflection coefficient found in Section 6.1, the timedomain reflection coefficient can be found using an inverse Laplace transform. In order to perform the inverse Laplace transform, the frequency-domain reflection coefficient may be rearranged into a more manageable form. Before this can be done however, it must be noted that as $s \longrightarrow \infty$, the reflection coefficient does not tend to zero. Instead it can be seen that

as
$$s \longrightarrow \infty$$
 $\Gamma(s) \longrightarrow \frac{K - \epsilon_{\infty} \cos \theta}{K + \epsilon_{\infty} \cos \theta}$, (6.7)

which produces a delta function in the final time-domain reflection coefficient. In order to perform the inverse Laplace transform, this term, defined as Γ_{∞} , needs to be subtracted from the total reflection coefficient. This leads to

$$\widetilde{\Gamma}(s) = \Gamma(s) - \Gamma_{\infty}$$

$$= \frac{K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_1}\sqrt{s-s_2} - \epsilon_{\infty}\cos\theta(s-s_3)(s-s_4)}{K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_1}\sqrt{s-s_2} + \epsilon_{\infty}\cos\theta(s-s_3)(s-s_4)} - \frac{K-\epsilon_{\infty}\cos\theta}{K+\epsilon_{\infty}\cos\theta}$$

$$=\frac{2K\epsilon_{\infty}\cos\theta\left[\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6}-(s-s_3)(s-s_4)\right]}{(K+\epsilon_{\infty}\cos\theta)\left[K\sqrt{s-s_1}\sqrt{s-s_2}\sqrt{s-s_5}\sqrt{s-s_6}+\epsilon_{\infty}\cos\theta(s-s_3)(s-s_4)\right]}$$
(6.8)

Rationalizing the denominator allows the denominator to be written as

$$D = (K + \epsilon_{\infty} \cos \theta) \left[K^{2}(s - s_{1})(s - s_{2})(s - s_{5})(s - s_{6}) - \epsilon_{\infty}^{2} \cos^{2} \theta(s - s_{3})^{2}(s - s_{4})^{2} \right],$$
(6.9)

and the numerator to be written as

$$N = 2K\epsilon_{\infty} \cos\theta \left[K(s-s_{1})(s-s_{2})(s-s_{5})(s-s_{6}) - (K+\epsilon_{\infty} \cos\theta)(s-s_{3})(s-s_{4})\sqrt{s-s_{1}}\sqrt{s-s_{2}}\sqrt{s-s_{5}}\sqrt{s-s_{6}} + \epsilon_{\infty} \cos\theta(s-s_{3})^{2}(s-s_{4})^{2} \right].$$
(6.10)

Using the definition

$$\gamma^2 = \frac{b^2(\mu_r - 2\epsilon_\infty \cos^2\theta)}{K^2 - \epsilon_\infty^2 \cos^2\theta},\tag{6.11}$$

the denominator term can be expanded and written as

$$D = (K + \epsilon_{\infty} \cos \theta)(K^{2} - \epsilon_{\infty}^{2} \cos \theta) \left[s^{4} + 4\delta s^{3} + (2\omega_{0}^{2} + 4\delta^{2} + \gamma^{2})s^{2} + (4\delta\omega_{0}^{2} + 2\delta\gamma^{2})s + \omega_{0}^{4} + \omega_{0}^{2}\gamma^{2} - \frac{b^{4}\cos^{2}\theta}{K^{2} - \epsilon_{\infty}^{2}\cos^{2}\theta} \right].$$
(6.12)

The next step is to factor the denominator term. This is accomplished by dividing the quartic function in the denominator by $s^2 + 2\delta s + \omega_0^2 + \gamma^2/2 + \chi$ using a long division technique. The remainder term is set equal to zero and solved for χ . This allows the denominator to be written as

$$D = (K + \epsilon_{\infty} \cos \theta)^{2} (K - \epsilon_{\infty} \cos \theta) \left(s^{2} + 2\delta s + \omega_{0}^{2} + \frac{\gamma^{2}}{2} - \chi\right) \times \left(s^{2} + 2\delta s + \omega_{0}^{2} + \frac{\gamma^{2}}{2} + \chi\right),$$
(6.13)

where χ is defined as

$$\chi = \frac{b^2 \sigma}{2(K^2 - \epsilon_\infty^2 \cos^2 \theta)},\tag{6.14}$$

and σ is defined as

$$\sigma^2 = \mu_r^2 + \sin^2(2\theta).$$
 (6.15)

It is then convenient to redefine the denominator as

$$D = (K + \epsilon_{\infty} \cos \theta)^2 (K - \epsilon_{\infty} \cos \theta) (s - s_E) (s - s_F) (s - s_G) (s - s_H), \quad (6.16)$$

where

$$(s - s_E)(s - s_F) = s^2 + 2\delta s + \omega_0^2 + \frac{\gamma^2}{2} - \chi, \qquad (6.17a)$$

$$(s - s_G)(s - s_H) = s^2 + 2\delta s + \omega_0^2 + \frac{\gamma^2}{2} + \chi.$$
 (6.17b)

The roots can then be found to be

$$s_{E,F} = -\delta \pm \sqrt{\delta^2 - \left(\omega_0^2 + \frac{\gamma^2}{2} - \chi\right)}$$

$$= -\delta \pm \lambda_E, \qquad (6.18a)$$

$$s_{G,H} = -\delta \pm \sqrt{\delta^2 - \left(\omega_0^2 + \frac{\gamma^2}{2} + \chi\right)}$$

$$= -\delta \pm \lambda_G. \qquad (6.18b)$$

The numerator also needs to be rearranged in order for the inverse Laplace transform to be taken. Noting that

$$(s - s_3)(s - s_4) = (s - s_1)(s - s_2) + \frac{b^2}{\epsilon_{\infty}},$$
(6.19)

it is possible to rewrite the numerator term as

$$N = 2K\epsilon_{\infty}\cos\theta(s-s_{1})(s-s_{2})\left[\epsilon_{\infty}\cos\theta[(s-s_{1})(s-s_{2})-\frac{\sqrt{s-s_{1}}\sqrt{s-s_{2}}\sqrt{s-s_{5}}\sqrt{s-s_{6}}] + K[(s-s_{5})(s-s_{6})-\frac{\sqrt{s-s_{1}}\sqrt{s-s_{2}}\sqrt{s-s_{5}}\sqrt{s-s_{6}}] - \frac{b^{2}}{\epsilon_{\infty}}(K+\epsilon_{\infty}\cos\theta)(s-s_{5})(s-s_{6})\times \left[\frac{1}{\sqrt{s-s_{1}}\sqrt{s-s_{2}}\sqrt{s-s_{5}}\sqrt{s-s_{6}}}\right] + \frac{b^{4}\cos\theta}{\epsilon_{\infty}}\frac{1}{(s-s_{1})(s-s_{2})} + 2b^{2}\cos\theta\right]$$
$$= 2K\epsilon_{\infty}\cos\theta(s-s_{1})(s-s_{2})\left[\epsilon_{\infty}\cos\theta g_{1}(s) + Kg_{2}(s) - \frac{b^{2}}{\epsilon_{\infty}}(K+\epsilon_{\infty}\cos\theta)g_{3}(s) + \frac{b^{4}\cos\theta}{\epsilon_{\infty}}g_{4}(s) + 2b^{2}\cos\theta\right]$$
$$= 2K\epsilon_{\infty}\cos\theta(s-s_{1})(s-s_{2})G(s). \tag{6.20}$$

The $g_n(s)$ terms are the same as in the previous cases. The reflection coefficient in the frequency domain can then be written as

$$\widetilde{\Gamma}(s) = \frac{2K\epsilon_{\infty}\cos\theta(s-s_1)(s-s_2)G(s)}{(K+\epsilon_{\infty}\cos\theta)^2(K-\epsilon_{\infty}\cos\theta)(s-s_E)(s-s_F)(s-s_G)(s-s_H)}.$$
(6.21)

Making the convenient substitutions

$$F_2 = \frac{2K\epsilon_{\infty}\cos\theta}{(K + \epsilon_{\infty}\cos\theta)^2(K - \epsilon_{\infty}\cos\theta)},$$
(6.22a)

$$C(s) = \frac{(s - s_1)(s - s_2)}{(s - s_E)(s - s_F)(s - s_G)(s - s_H)},$$
(6.22b)

allows (6.21) to be rewritten as

$$\widetilde{\Gamma}(s) = F_2 C(s) G(s). \tag{6.23}$$

The Laplace transform of both the C(s) and the G(s) term can be taken separately and the time-domain reflection coefficient is simply a convolution of those terms.

6.2.1 Inversion of the G(s) Term

As shown in (6.20), G(s) is given as

$$G(s) = \left[\epsilon_{\infty} \cos \theta g_1(s) + Kg_2(s) - \frac{b^2}{\epsilon_{\infty}} (K + \epsilon_{\infty} \cos \theta) g_3(s) + \frac{b^4 \cos \theta}{\epsilon_{\infty}} g_4(s) + 2b^2 \cos \theta\right]$$
(6.24)

All of the terms in G(s) are solved in previous sections. The inversion of the $g_1(s)$ and $g_2(s)$ terms is done in Section 3.2.1 and the inversion of the $g_3(s)$ and $g_4(s)$ is done in Section 4.2. These terms are given as

$$g_{1}(t) = e^{-\delta t} \left[-\lambda_{1}^{2} \lambda_{5}^{2} \hat{\mathbf{I}}_{1}(\lambda_{1}t) * \hat{\mathbf{I}}_{1}(\lambda_{5}t) + \lambda_{1}^{3} \hat{\mathbf{I}}_{2}(\lambda_{1}t) + \lambda_{5}^{3} \hat{\mathbf{I}}_{2}(\lambda_{5}t) \right] - \frac{\lambda_{1}^{2} - \lambda_{5}^{2}}{2} \delta(t),$$
(6.25a)

$$g_{2}(t) = e^{-\delta t} \left[-\lambda_{1}^{2} \lambda_{5}^{2} \hat{\mathbf{I}}_{1}(\lambda_{1} t) * \hat{\mathbf{I}}_{1}(\lambda_{5} t) + \lambda_{1}^{3} \hat{\mathbf{I}}_{2}(\lambda_{1} t) + \lambda_{5}^{3} \hat{\mathbf{I}}_{2}(\lambda_{5} t) \right] + \frac{\lambda_{1}^{2} - \lambda_{5}^{2}}{2} \delta(t),$$
(6.25b)

$$g_{3}(t) = e^{-\delta t} \left[-\lambda_{5}^{2} \left\{ \mathbf{I}_{0}(\lambda_{1}t)\mathbf{u}(t) \right\} * \hat{\mathbf{I}}_{1}(\lambda_{5}t) + \lambda_{1}\mathbf{I}_{1}(\lambda_{1}t)\mathbf{u}(t) \right] + \delta(t),$$
(6.25c)

$$g_4(t) = \frac{e^{-\delta t}}{\lambda_1} \sinh(\lambda_1 t) \mathbf{u}(t).$$
(6.25d)

In these equations, λ_1 and λ_5 are defined as in (5.30) and $\hat{I}_n(x)$ is defined as in (3.51). The final expression for G(t) can then be given as

$$G(t) = e^{-\delta t} \left\{ (K + \epsilon_{\infty} \cos \theta) \left[-\lambda_1^2 \lambda_5^2 \hat{\mathbf{I}}_1(\lambda_1 t) * \hat{\mathbf{I}}_1(\lambda_5 t) + \frac{b^2}{\epsilon_{\infty}} \lambda_5^2 \left\{ \mathbf{I}_0(\lambda_1 t) \mathbf{u}(t) \right\} * \hat{\mathbf{I}}_1(\lambda_5 t) - \mathbf{I}_0(\lambda_5 t) \right\} \right\}$$

$$\frac{b^2}{\epsilon_{\infty}}\lambda_1 \mathbf{I}_1(\lambda_1 t)\mathbf{u}(t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \lambda_5^3 \hat{\mathbf{I}}_2(\lambda_5 t) \Big] + \frac{b^4 \cos\theta}{\epsilon_{\infty}\lambda_1} \sinh(\lambda_1 t)\mathbf{u}(t) \Big\} + b^2 (K - \epsilon_{\infty}\cos\theta) \left(\frac{\mu_r \epsilon_{\infty} - 2K^2}{2K^2 \epsilon_{\infty}}\right) \delta(t).$$
(6.26)

Just as in the optical TM case in Chapter 4, there are cases where λ_1 or λ_5 can be found to be imaginary and the modified Bessel functions in (6.26) can be replaced with ordinary Bessel functions. Case 1 occurs when $\omega_0^2 > \delta^2$. In this case both λ_1 and λ_5 are purely imaginary and defined as in (5.33). Then, using the properties (3.55) and (4.32), it can be seen that (6.26) can be expressed as

$$G(t) = e^{-\delta t} \left\{ (K + \epsilon_{\infty} \cos \theta) \left[-\overline{\lambda}_{1}^{2} \overline{\lambda}_{5}^{2} \hat{J}_{1}(\overline{\lambda}_{1}t) * \hat{J}_{1}(\overline{\lambda}_{5}t) - \frac{b^{2}}{\epsilon_{\infty}} \overline{\lambda}_{5}^{2} \left\{ J_{0}(\overline{\lambda}_{1}t)u(t) \right\} * \hat{J}_{1}(\overline{\lambda}_{5}t) + \frac{b^{2}}{\epsilon_{\infty}} \overline{\lambda}_{1} J_{1}(\overline{\lambda}_{1}t)u(t) + \overline{\lambda}_{1}^{3} \hat{J}_{2}(\overline{\lambda}_{1}t) + \overline{\lambda}_{5}^{3} \hat{J}_{2}(\overline{\lambda}_{5}t) \right] + \frac{b^{4} \cos \theta}{\epsilon_{\infty} \overline{\lambda}_{1}} \sin(\overline{\lambda}_{1}t)u(t) \right\} + b^{2}(K - \epsilon_{\infty} \cos \theta) \left(\frac{\mu_{r} \epsilon_{\infty} - 2K^{2}}{2K^{2} \epsilon_{\infty}} \right) \delta(t),$$

$$(6.27)$$

where $\hat{J}_n(x)$ is defined in (3.57).

Case 2 occurs when $\omega_0^2 + \mu_r b^2/K^2 < \delta^2$. In this case, both λ_1 and λ_5 are purely real and the same expression from (6.26) can be used. Case 3 occurs when $-\mu_r b^2/K^2 < \omega_0^2 - \delta^2 < 0$. In this case, λ_1 is purely real and λ_5 is purely imaginary. $\overline{\lambda}_5$ is defined as in (5.30) and the expression for G(t) can be written as

$$G(t) = e^{-\delta t} \left\{ (K + \epsilon_{\infty} \cos \theta) \left[\lambda_1^2 \overline{\lambda}_5^2 \hat{\mathbf{I}}_1(\overline{\lambda}_1 t) * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) - \frac{b^2}{\epsilon_{\infty}} \overline{\lambda}_5^2 \left\{ \mathbf{I}_0(\lambda_1 t) \mathbf{u}(t) \right\} * \hat{\mathbf{J}}_1(\overline{\lambda}_5 t) - \frac{b^2}{\epsilon_{\infty}} \lambda_1 \mathbf{I}_1(\lambda_1 t) \mathbf{u}(t) + \lambda_1^3 \hat{\mathbf{I}}_2(\lambda_1 t) + \overline{\lambda}_5^3 \hat{\mathbf{J}}_2(\overline{\lambda}_5 t) \right] + \frac{b^4 \cos \theta}{\epsilon_{\infty} \lambda_1} \sinh(\lambda_1 t) \mathbf{u}(t) \right\} + b^2 (K - \epsilon_{\infty} \cos \theta) \left(\frac{\mu_r \epsilon_{\infty} - 2K^2}{2K^2 \epsilon_{\infty}} \right) \delta(t).$$

$$(6.28)$$

6.2.2 Inversion of the C(s) Term

As described in (6.22), C(s) is given in the Laplace domain as

$$C(s) = \frac{(s-s_1)(s-s_2)}{(s-s_E)(s-s_F)(s-s_G)(s-s_H)}.$$
(6.29)

Using partial fraction expansion, this term can be rewritten as

$$C(s) = \frac{\sigma - \mu_r + 2\epsilon_{\infty} \cos^2 \theta}{4\sigma \lambda_E} \left[\frac{1}{s - s_E} - \frac{1}{s - s_F} \right] + \frac{\sigma + \mu_r - 2\epsilon_{\infty} \cos^2 \theta}{4\sigma \lambda_G} \left[\frac{1}{s - s_G} - \frac{1}{s - s_H} \right]$$
$$= c_1(s) + c_2(s). \tag{6.30}$$

An inverse Laplace transform of each term in (6.30) can be taken separately. When inverting $c_1(s)$, if $\omega_0^2 + \gamma^2/2 - \chi > 0$ the standard transform used in (3.27) can be applied directly resulting in the expression

$$c_{1}(s) \longleftrightarrow c_{1}(t) = \frac{\sigma - \mu_{r} + 2\epsilon_{\infty} \cos^{2} \theta}{4\sigma\lambda_{E}} e^{-\delta t} \left[e^{\lambda_{E}t} - e^{-\lambda_{E}t} \right] \mathbf{u}(t)$$
$$= \frac{\sigma - \mu_{r} + 2\epsilon_{\infty} \cos^{2} \theta}{2\sigma\lambda_{E}} e^{-\delta t} \sinh(\lambda_{E}t)\mathbf{u}(t). \tag{6.31}$$

If $\omega_0^2 + \gamma^2/2 - \chi > \delta^2$, λ_E is purely imaginary and defined as

$$-j\lambda_E = \overline{\lambda}_E = \sqrt{\omega_0^2 + \frac{\gamma^2}{2} - \chi - \delta^2}.$$
 (6.32)

This allows (6.31) to be rewritten as

$$c_1(t) = \frac{\sigma - \mu_r + 2\epsilon_\infty \cos^2 \theta}{2\sigma \overline{\lambda}_E} e^{-\delta t} \sin(\overline{\lambda}_E t) \mathbf{u}(t).$$
(6.33)

If $\omega_0^2 + \gamma^2/2 - \chi < 0$ however, $R_e\{s_E\} > 0$. In this case the identity given in (4.40) must be used. This produces the result

$$c_{1}(t) = -\frac{\sigma - \mu_{r} + 2\epsilon_{\infty} \cos^{2}\theta}{4\sigma\lambda_{E}} e^{-\delta t} \left[e^{\lambda_{E}t} \mathbf{u}(-t) + e^{-\lambda_{E}t} \mathbf{u}(t) \right]$$
$$= -\frac{\sigma - \mu_{r} + 2\epsilon_{\infty} \cos^{2}\theta}{4\sigma\lambda_{E}} e^{-\delta t} e^{-\lambda_{E}|t|}, \tag{6.34}$$

which is non-causal. As argued in Chapter 4, this non-causality is due to the infinite nature of the problem and is not a physical phenomenon.

Taking the Laplace inversion of $c_2(s)$ can be done in much the same manner as for $c_1(s)$. If $\omega_0^2 + \gamma^2/2 + \chi > 0$ the standard transform used in (3.27) can be applied directly resulting in the expression

$$c_{2}(s) \longleftrightarrow c_{2}(t) = \frac{\sigma + \mu_{r} - 2\epsilon_{\infty} \cos^{2} \theta}{4\sigma \lambda_{G}} e^{-\delta t} \left[e^{\lambda_{G} t} - e^{-\lambda_{G} t} \right] \mathbf{u}(t)$$
$$= \frac{\sigma + \mu_{r} - 2\epsilon_{\infty} \cos^{2} \theta}{2\sigma \lambda_{G}} e^{-\delta t} \sinh(\lambda_{G} t) \mathbf{u}(t). \tag{6.35}$$

If $\omega_0^2 + \gamma^2/2 + \chi > \delta^2$, λ_G is purely imaginary and defined as

$$-j\lambda_G = \overline{\lambda}_G = \sqrt{\omega_0^2 + \frac{\gamma^2}{2} + \chi - \delta^2}.$$
(6.36)

This allows (6.35) to be rewritten as

$$c_2(t) = \frac{\sigma + \mu_r - 2\epsilon_\infty \cos^2 \theta}{2\sigma \overline{\lambda}_G} e^{-\delta t} \sin(\overline{\lambda}_G t) \mathbf{u}(t).$$
(6.37)

If $\omega_0^2 + \gamma^2/2 + \chi < 0$ however, $R_e\{s_G\} > 0$. In this case the identity given in (4.40) must again be used. This produces the result

$$c_2(t) = -\frac{\sigma + \mu_r - 2\epsilon_{\infty}\cos^2\theta}{4\sigma\lambda_G} e^{-\delta t} \left[e^{\lambda_G t} \mathbf{u}(-t) + e^{-\lambda_G t} \mathbf{u}(t) \right]$$

$$= -\frac{\sigma + \mu_r - 2\epsilon_{\infty}\cos^2\theta}{4\sigma\lambda_G} e^{-\delta t} e^{-\lambda_G|t|}, \qquad (6.38)$$

which is again non-causal. The same argument from earlier can be used to explain this non-causality.

Analyzing these two terms, it can be seen that in general, C(t) is causal whenever $\chi < -|\omega_0^2 + \gamma^2/2|$ and non-causal when $\chi > -|\omega_0^2 + \gamma^2/2|$.

6.3 Numerical Results

In order to validate the expressions derived in the previous section, the time-domain reflection coefficient is evaluated numerically in Fortran, and then compared to the inverse FFT of the frequency domain reflection coefficient given in (6.21). The Fortran code is included in Appendix D. The inverse FFT was done using WaveCalc. The frequency-domain data was zero-padded up to the maximum limit allowed by Wave-Calc, 32,768, before the inverse FFT was taken. Since the signal had already decayed to zero by this point, no windowing was necessary. A set of parameters corresponding to each of the three possible cases for G(t) is used. The angle is then adjusted for the case 1 parameters to produce results that contain a non-causal contribution. The number of points and step size for the results varied between the different cases.

The first set of parameters chosen are: $\omega_0 = 4.0 \times 10^{11} s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 1. When computing the numerical results, for the frequency-domain data 8,192 frequency points were calculated with a step size of 400 MHz. In the time-domain, 8,192 points were calculated with a step size of 1×10^{-4} ns. Using $\theta = 30^{\circ}$, (6.27) has been plotted in Figure 6.1 and compared to the inverse FFT. The results show excellent agreement. Since this function includes only standard Bessel functions, which are highly oscillatory, and no modified Bessel functions, which are not oscillatory, the waveform is highly oscillatory and only lightly damped.

The next choice of parameters is: $\omega_0 = 4.0 \times 10^{10} s^{-1}$, $b = 6.24 \times 10^{10} s^{-1}$, $\delta = 2.5 \times 10^{11} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$, which corresponds to case 2, (6.26). When computing the numerical results, for the frequency-domain data 32,768 frequency points were calculated with a step size of 4 MHz. In the time-domain, 8,192 points were calculated with a step size of 1×10^{-4} ns. The results are shown in Figure 6.2. Again, the closed-form expression and the inverse FFT compare well. For this choice of parameters $\omega_0^2 + \mu_r b^2/K^2 < \delta^2$, and the resulting waveform is overdamped, showing no oscillatory behavior and only a single negative peak. Since the expression for case 2 only involves modified Bessel functions, which do not have the oscillatory behavior of ordinary Bessel functions, this observed behavior is easily predicted from the mathematical form of the expression.

The next choice of parameters, which corresponds to case 3, is: $\omega_0 = 4.0 \times 10^9 \ s^{-1}$, $b = 6.24 \times 10^{11} \ s^{-1}$, $\delta = 2.5 \times 10^{10} \ s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$, which corresponds to case 3, (6.28). When computing the numerical results, for the frequency-domain data 32,768 frequency points were calculated with a step size of 400 MHz. In the time-domain, 8,192 points were calculated with a step size of 5×10^{-5} ns. The analytic expression again matches the inverse FFT, as seen in Figure 6.3. As expected, since $\delta > \omega_0$, but $\delta^2 < \omega_0^2 + \mu_r b^2/K^2$, there is more damping and less oscillation than with case 1, but more oscillation than with case 2. Here the expression for the reflection coefficient has a combination of ordinary and modified Bessel functions.

To examine the non-causal result which is possible for the C(t) term, the material parameters corresponding to case 1 are used again, but at an angle of 60°. This causes the $c_1(t)$ term in C(t) to be non-causal as shown in (6.34). When computing the numerical results, for the frequency-domain data 32,768 frequency points were calculated with a step size of 400 MHz. In the time-domain, 8,192 points were calculated with a step size of 5×10^{-5} ns with a starting time value of -1.024×10^{-1} ns. As seen in Figure 6.4, the expression again matches well with the inverse FFT for t > 0. For t < 0, non-causal term in the analytic expression is extremely small. Unfortunately, the inverse FFT does not have the necessary resolution to capture the small non-causal portion of the reflection coefficient, so it cannot be compared to the analytic expression.

In order to gain better insight into the non-causal term, the non-causal C(t) term is plotted in Figure 6.5. The non-causal part is much more significant in this C(t)than in the TM optical case. To investigate further, C(t) was convolved with G(t)minus the delta function term. This can be seen in Figure 6.6. Again, the non-causal portion has a significant contribution to this term. However, when C(t) is convolved with the delta function term, it can be seen in Figure 6.7 that the non-causal portion has the opposite sign of the term in Figure 6.6, and when those terms are added, the non-causal portion becomes extremely small in the final transient reflected field.



Figure 6.1. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{11} s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 1, Eq. (6.27).



Figure 6.2. Time-domain reflection coefficient with incidence angle $\theta = 30^{\circ}$ and material parameters $\omega_0 = 4.0 \times 10^{10} s^{-1}$, $b = 6.24 \times 10^{10} s^{-1}$, $\delta = 2.5 \times 10^{11} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 2, Eq. (6.26).



Figure 6.3. Time-domain reflection coefficient with at an angle of $\theta = 30^{\circ}$ with parameter choices of $\omega_0 = 4.0 \times 10^9 s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_r = 1$. This choice of parameters corresponds to case 3, Eq. (6.28).



Figure 6.4. Time-domain reflection coefficient with at an angle of $\theta = 60^{\circ}$ with parameter choices of $\omega_0 = 4.0 \times 10^{11} s^{-1}$, $b = 6.24 \times 10^{11} s^{-1}$, $\delta = 2.5 \times 10^{10} s^{-1}$, $\epsilon_{\infty} = 2$, $\mu_T = 1$. This choice of parameters corresponds to case 1, Eq. (6.27) with a non-causal term from Eq. (6.34).



Figure 6.5. Non-causal C(t) term for case 1 results.



Figure 6.6. Non-causal C(t) term convolved with G(t) minus the delta function term for case 1 results.



Figure 6.7. Non-causal C(t) term convolved with the delta function term for case 1 results.

CHAPTER 7

CONCLUSIONS

In this thesis an analytic solution for the transient reflection coefficient of plane waves from a Lorentz-medium half-space is formulated analytically. Using an inverse Laplace transform technique, the solution was found to be a combination of Bessel functions and convolutions of Bessel functions with a decaying exponential factor proportional to δ , the damping coefficient of the material.

Unlike previous work [10],[11] which represent the transient field as an infinite sum of fractional-order Bessel functions, the formulation in this thesis has no infinite sums and presents much more physical insight into the behavior of the transient field. Depending on field polarization, material properties, and angle of incidence, the expression for the transient field changes and gives a clearer view of the timedomain behavior. It is also clear that for certain angles there is a problem with causality that occurrs in the TM-polarized case. This non-causal function is due to the infinite nature of the problem and is not a physical phenomenon. It is, however, an interesting discovery.

7.1 Suggestions for Future Work

The Lorentz model is a single resonance model that is closely related to the permittivity of a cold plasma. A very similar reflection coefficient can be developed using plasma equations. Using this same method, developing the transient field reflection coefficient from a cold plasma half-space is a problem that is of some interest.

Transmission into dispersive material is also a topic of interest. It would be interesting to formulate the transient transmitted field using the same basic techniques outlined in this thesis for the reflected field. APPENDICES

APPENDIX A

FORTRAN CODE FOR OPTICAL TE CASE

program special_TE

implicit none

integer nsize

```
parameter(nsize = 10000)
```

```
real*8 BESSI,om0,delta,b,theta,rlam1,rlam5,dt,ct,t,pi
real*8 j1,j2,j1p,j2p,i1,i2,df,f,om,gammat(nsize)
real*8 j11h(nsize),j12h(nsize),j21h(nsize),j22h(nsize)
real*8 i11h(nsize),i12h(nsize),i21h(nsize),i22h(nsize)
real*8 j1j1(nsize),i111(nsize),i1j1(nsize),expon(nsize)
integer i,nt,nf
complex*16 z1,z2,s,zj,gamma,zz1,zz2,s1,s2,s5,s6
```

```
om0 = 4.d16
b = dsqrt(20.d32)
delta = 0.28d16
theta = 0.d0
pi = 4.d0*atan(1.d0)
ct = cos(theta*pi/180.d0)
zj=dcmplx(0.d0,1.d0)
```

```
df = 8d3
   nf = ((4095*2+1)*2+1)
   nt = 4096
   dt = 1.d-18
с
   zz1 = cdsqrt(dcmplx(delta*delta-om0*om0,0.d0))
   s1 = -delta+zz1
   s2 = -delta-zz1
   zz2 = cdsqrt(dcmplx(delta*delta-om0*om0-b*b/(ct*ct),0.d0))
    s5 = -delta+zz2
    s6 = -delta-zz2
    open (10,file='gamma.dat',status='unknown')
    do i=1,nf
       f = df * i
        om = 2.d0*pi*f*1.d9
        s = zj*om
        z1 = cdsqrt(s-s1)*cdsqrt(s-s2)
        z2 = cdsqrt(s-s5)*cdsqrt(s-s6)
        gamma = (z1-z2)/(z1+z2)
        write (10,*) f,real(gamma),aimag(gamma)
    end do
    close (10)
    do i=1,nt
        t = (i-1)*dt+.00001*dt
        expon(i) = exp(-delta*t)
```

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```

```
end do
   write(*,*) 'om^2 = ',om0*om0
   write(*,*) 'om^2+B^2 = ',om0*om0+b*b/(ct*ct)
   write(*,*) 'delta^2 = ',delta*delta
1 ------
1
  CASE 1
   om0^2 > delta^2
1
if((om0*om0).gt.(delta*delta)) then
      write(*,*) "CASE 1"
      rlam1 = dsqrt(om0*om0-delta*delta)
      rlam5 = dsqrt(om0*om0+(b*b/(ct*ct))-delta*delta)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
         call jbess(rlam1*t,2,j2,j2p)
         j21h(i) = j2/(rlam1*t)
         call jbess(rlam5*t,2,j2,j2p)
         j22h(i) = j2/(rlam5*t)
         call jbess(rlam1*t,1,j1,j1p)
         j11h(i) = j1/(rlam1*t)
         call jbess(rlam5*t,1,j1,j1p)
         j12h(i) = j1/(rlam5*t)
      end do
      call conv(j11h,j12h,nt,dt,j1j1)
      open(10,file='gammat.dat',status='unknown')
      do i=1,nt
```

```
gammat(i) = expon(i)*(2.d0*(rlam1**3)*j21h(i)+
2 2.d0*(rlam5**3)*j22h(i)-2.d0*rlam1*rlam1*rlam5*rlam5*
3 j1j1(i))
gammat(i) = -gammat(i)*ct*ct/(b*b)
write(10,*) ((i-1)*dt+.00001*dt)*1.d9,gammat(i)
end do
close(10)
!
CASE 2
! om0^2 + B^2 < delta^2
!
```

```
elseif((om0*om0+(b*b/(ct*ct))).lt.delta*delta) then
```

```
write(*,*) "CASE 2"
rlam1 = dsqrt(delta*delta-om0*om0)
rlam5 = dsqrt(-om0*om0-(b*b/(ct*ct))+delta*delta)
do i=1,nt
    t = (i-1)*dt+.00001*dt
    i2 = BESSI(2,rlam1*t)
    i21h(i) = i2/(rlam1*t)
    i2 = BESSI(2,rlam5*t)
    i22h(i) = i2/(rlam5*t)
    i1 = BESSI(1,rlam1*t)
    i11h(i) = i1/(rlam5*t)
    i12h(i) = i1/(rlam5*t)
```

end do

```
call conv(i11h,i12h,nt,dt,i1i1)
```

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```
open(10,file='gammat.dat',status='unknown')
      do i=1,nt
         gammat(i) = expon(i)*(2.d0*(rlam1**3)*i21h(i)+
   2
              2.d0*(rlam5**3)*i22h(i)-2.d0*rlam1*rlam1*rlam5*rlam5*
              i1i1(i))
   3
             gammat(i) = -gammat(i)*ct*ct/(b*b)
         write(10,*) ((i-1)*dt+.00001*dt)*1.d9,gammat(i)
      end do
      close(10)
   else
!
   CASE 3
   om0^2 + B^2 > delta^2 \& om0^2 < delta^2
write(*,*) "CASE 3"
      rlam1 = dsqrt(delta*delta-om0*om0)
      rlam5 = dsqrt(om0*om0+(b*b/(ct*ct))-delta*delta)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
         i2 = BESSI(2,rlam1*t)
         i21h(i) = i2/(rlam1*t)
         call jbess(rlam5*t,2,j2,j2p)
         j22h(i) = j2/(rlam5*t)
         i1 = BESSI(1,rlam1*t)
         i11h(i) = i1/(rlam1*t)
```

```
call jbess(rlam5*t,1,j1,j1p)
         j12h(i) = j1/(rlam5*t)
      end do
      call conv(i11h,j12h,nt,dt,i1j1)
      open(10,file='gammat.dat',status='unknown')
      do i=1,nt
         gammat(i) = expon(i)*(2.d0*(rlam1**3)*i21h(i)+
              2.d0*(rlam5**3)*j22h(i)+2.d0*rlam1*rlam1*rlam5*rlam5*
   2
   3
              i1j1(i))
             gammat(i) = -gammat(i)*ct*ct/(b*b)
         write(10,*) ((i-1)*dt+.00001*dt)*1.d9,gammat(i)
      end do
      close(10)
  endif
  end
subroutine conv(f,g,n,del,c)
   performs convolution of waveforms f and g using
    linear interpolation
  parameter (nsize=10000)
  2
             c16=0.166666666666666666660)
```

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```
implicit real*8 (a-h,o-z)
   real*8 f(nsize),g(nsize),c(nsize)
   c(1)=0.d0
   do k=2,n
    sum = 0.d0
    do l=1,k-1
      sum = sum + c13*f(l+1)*g(k-1)
    2
                + c13*f(l)*g(k-l+1)
                + c16*f(1)*g(k-1)
    3
                 + c16*f(l+1)*g(k-l+1)
    4
    end do
    c(k) = del*sum
   end do
   return
   end
FUNCTION BESSI(N,X)
    This subroutine calculates the first kind modified Bessel function
    of integer order N, for any REAL X. We use here the classical
    recursion formula, when X > N. For X < N, the Miller's algorithm
     is used to avoid overflows.
    REFERENCE:
    C.W.CLENSHAW, CHEBYSHEV SERIES FOR MATHEMATICAL FUNCTIONS,
```

ļ MATHEMATICAL TABLES, VOL.5, 1962.

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```
PARAMETER (IACC = 40, BIGNO = 1.D10, BIGNI = 1.D-10)
REAL *8 X, BESSI, BESSIO, BESSI1, TOX, BIM, BI, BIP
IF (N.EQ.O) THEN
BESSI = BESSIO(X)
RETURN
ENDIF
IF (N.EQ.1) THEN
BESSI = BESSI1(X)
RETURN
ENDIF
IF(X.EQ.O.DO) THEN
BESSI=0.DO
RETURN
ENDIF
TOX = 2.DO/X
BIP = 0.D0
BI = 1.D0
BESSI = 0.D0
M = 2*((N+INT(SQRT(FLOAT(IACC*N)))))
DO 12 J = M, 1, -1
BIM = BIP+DFLOAT(J)*TOX*BI
BIP = BI
BI = BIM
IF (ABS(BI).GT.BIGNO) THEN
BI = BI*BIGNI
BIP = BIP*BIGNI
```

!

```
BESSI = BESSI*BIGNI
     ENDIF
     IF (J.EQ.N) BESSI = BIP
  12 CONTINUE
     BESSI = BESSI*BESSIO(X)/BI
     RETURN
     END
! Auxiliary Bessel functions for N=0, N=1
     FUNCTION BESSIO(X)
     REAL *8 X, BESSIO, Y, P1, P2, P3, P4, P5, P6, P7,
         Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX
    *
     DATA P1, P2, P3, P4, P5, P6, P7/1. D0, 3.5156229D0, 3.0899424D0, 1.2067429D0
         ,0.2659732D0,0.360768D-1,0.45813D-2/
    *
     DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,0.1328592D-1,
         0.225319D-2,-0.157565D-2,0.916281D-2,-0.2057706D-1,
    *
         0.2635537D-1,-0.1647633D-1,0.392377D-2/
    *
     IF(ABS(X).LT.3.75D0) THEN
     Y = (X/3.75D0) * *2
     BESSI0=P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7))))))
     ELSE
     AX = ABS(X)
     Y=3.75D0/AX
     BX=EXP(AX)/SQRT(AX)
     AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9))))))))))
     BESSIO=AX*BX
     ENDIF
```

```
RETURN
    END
 _____
1
    FUNCTION BESSI1(X)
    REAL *8 X, BESSI1, Y, P1, P2, P3, P4, P5, P6, P7,
        Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX
    *
    DATA P1, P2, P3, P4, P5, P6, P7/0.5D0, 0.87890594D0, 0.51498869D0,
        0.15084934D0,0.2658733D-1,0.301532D-2,0.32411D-3/
    *
    DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,-0.3988024D-1,
        -0.362018D-2,0.163801D-2,-0.1031555D-1,0.2282967D-1,
        -0.2895312D-1,0.1787654D-1,-0.420059D-2/
    *
     IF(ABS(X).LT.3.75D0) THEN
    Y = (X/3.75D0) * * 2
    BESSI1=X*(P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7)))))))
     ELSE
     AX = ABS(X)
     Y=3.75D0/AX
     BX=EXP(AX)/SQRT(AX)
     AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9)))))))))
     BESSI1=AX*BX
     ENDIF
     RETURN
     END
```

subroutine jbess (x,n,bj,bjp)

```
c calculates jn and jn' for n positive or negative
С
     implicit real*8 (a-h,o-z)
с
   if (n .eq. 0) then
       bj = bessj(0,x)
       bjp = -bessj(1,x)
       return
     endif
С
     if (n .ge. 0) then
       m = n
      else
       m = -n
      endif
с
      if (x . eq. 0.d0) then
       bj = 0.d0
       bjp1 = bessj(m+1,x)
       bjm1 = bessj(m-1,x)
       bjp = (bjm1-bjp1)/2.d0
      else
        bj
            = bessj(m,x)
            = bessj(m+1,x)
        bj1
            = -bj1 + n*bj/x
        bjp
      endif
```

С

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```
с if (n .lt. 0) then = bj*(-1)**n bj bjp = bjp*(-1)**nendif с return end с с с FUNCTION BESSJO(X) implicit real*8 (a-h,o-z) REAL*8 Y, P1, P2, P3, P4, P5, Q1, Q2, Q3, Q4, Q5, R1, R2, R3, R4, R5, R6, S1,S2,S3,S4,S5,S6 * DATA P1, P2, P3, P4, P5/1.D0, -. 1098628627D-2, .2734510407D-4, -.2073370639D-5,.2093887211D-6/, Q1,Q2,Q3,Q4,Q5/-.1562499995D-* *1, .1430488765D-3, -.6911147651D-5,.7621095161D-6, -.934945152D-7/ * DATA R1, R2, R3, R4, R5, R6/57568490574.D0, -13362590354.D0, 651619640.7D *0, * -11214424.18D0,77392.33017D0,-184.9052456D0/, S1, S2, S3, S4, S5, S6/57568490411.D0, 1029532985.D0, * 9494680.718D0,59272.64853D0,267.8532712D0,1.D0/ IF(ABS(X).LT.8.)THEN Y=X**2 BESSJO=(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6))))))

```
/(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
*
ELSE
  AX = ABS(X)
  Z=8./AX
  Y=Z**2
  XX=AX-.785398164
  BESSJ0=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y
       *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
ENDIF
RETURN
END
FUNCTION BESSJ1(X)
implicit real*8 (a-h,o-z)
REAL*8 Y,P1,P2,P3,P4,P5,Q1,Q2,Q3,Q4,Q5,R1,R2,R3,R4,R5,R6,
     S1,S2,S3,S4,S5,S6
*
DATA R1,R2,R3,R4,R5,R6/72362614232.D0,-7895059235.D0,242396853.1D0
*,
     -2972611.439D0,15704.48260D0,-30.16036606D0/,
*
     S1, S2, S3, S4, S5, S6/144725228442.D0, 2300535178.D0,
     18583304.74D0,99447.43394D0,376.9991397D0,1.D0/
*
DATA P1, P2, P3, P4, P5/1.D0, .183105D-2, -.3516396496D-4, .2457520174D-5
*,
     -.240337019D-6/, Q1,Q2,Q3,Q4,Q5/.04687499995D0,-.2002690873D-3
*
*,
```

С

с

с

* .8449199096D-5,-.88228987D-6,.105787412D-6/

IF(ABS(X).LT.8.)THEN

Y=X**2

```
BESSJ1=X*(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6))))))
```

```
* /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
```

ELSE

AX = ABS(X)

Z=8./AX

Y=Z**2

XX=AX-2.356194491

BESSJ1=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y

```
* *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
```

```
* *SIGN(1.,X)
```

ENDIF

RETURN

END

```
С
```

```
с
```

```
с
```

```
FUNCTION BESSJ(N,X)
implicit real*8 (a-h,o-z)
PARAMETER (IACC=40,BIGN0=1.d10,BIGNI=1.d-10)
if (x .ge. 0.d0) then
ff = 1.d0
else
```

ff = (-1.d0) **n

end if

```
xx = abs(x)
if (n .eq. 0) then
    bessj = ff*bessj0(xx)
    return
endif
if (n .eq. 1) then
    bessj = ff*bessj1(xx)
    return
endif
TOX=2./Xx
IF(Xx.GT.FLOAT(N))THEN
BJM=BESSJ0(Xx)
BJ=BESSJ1(Xx)
DO 11 J=1,N-1
BJP=J*TOX*BJ-BJM
```

BJM=BJ

BJ=BJP

11 CONTINUE

BESSJ=ff*BJ

ELSE

M=2*((N+INT(SQRT(FLOAT(IACC*N))))/2)
BESSJ=0.
JSUM=0
SUM=0.
BJP=0.
BJ=1.

DO 12 J=M,1,-1

BJM=J*TOX*BJ-BJP

BJP=BJ

BJ=BJM

IF(ABS(BJ).GT.BIGNO)THEN

BJ=BJ*BIGNI

BJP=BJP*BIGNI

BESSJ=BESSJ*BIGNI

SUM=SUM*BIGNI

ENDIF

IF(JSUM.NE.O)SUM=SUM+BJ

JSUM=1-JSUM

IF(J.EQ.N)BESSJ=BJP

12 CONTINUE

SUM=2.*SUM-BJ

BESSJ=ff*BESSJ/SUM

ENDIF

RETURN

END

APPENDIX B

FORTRAN CODE FOR OPTICAL TM CASE

program special_TM

implicit none

integer nsize

parameter(nsize = 10000)

```
real*8 BESSI,om0,delta,b,theta,dt,ct,tt,t,pi,df,f,om,YY
real*8 rlam1,rlam5,rlame,expon(nsize),gams,temp,term1,term2
real*8 i01(nsize),i11(nsize),i15(nsize),i21(nsize),i25(nsize)
real*8 i11h(nsize),i15h(nsize),i21h(nsize),i25h(nsize),i0i2(nsize)
real*8 i111(nsize),i2i2(nsize),i0i1(nsize),i0i0(nsize),i05(nsize)
real*8 c3ft(nsize),c3f_t(nsize),f_t(nsize),temp2(nsize)
real*8 c3(nsize),ft(nsize),gammat(nsize)
real*8 c3shift(nsize),ftshift(nsize),f_tshift(nsize)
integer i,nt,nf,c3case3,shift
complex*16 z1,z2,s,zj,gamma,zz1,zz2,s1,s2,s5,s6,zze,se,sf,num
```

```
om0 = 4.d16
b = dsqrt(20.d32)
delta = 0.28d16
theta = 30.d0
pi = 4.d0*atan(1.d0)
```

```
ct = cos(theta*pi/180.d0)
   tt = tan(theta*pi/180.d0)
   z_j=dcmplx(0.d0,1.d0)
   gams = b*b/(tt*tt-1)
   c3case3 = 0
   shift = 4
   df = 8d3
   nf = 4096 * 2 * 2 * 2
   nt = 4096
   dt = 1.d-18
с
   zz1 = cdsqrt(dcmplx(delta*delta-om0*om0,0.d0))
   s1 = -delta+zz1
    s2 = -delta-zz1
   zz2 = cdsqrt(dcmplx(delta*delta-om0*om0-b*b/(ct*ct),0.d0))
   s5 = -delta+zz2
   s6 = -delta-zz2
   zze = cdsqrt(dcmplx(delta*delta-om0*om0+gams,0.d0))
   se = -delta+zze
   sf = -delta-zze
Frequency Domain Reflection Coefficient (gamma.dat)
!
open (10,file='gamma.dat',status='unknown')
   do i=1,nf
      f = df * i
      om = 2.d0*pi*f*1.d9
```

```
s = zj*om
      z1 = cdsqrt(s-s1)*cdsqrt(s-s2)*cdsqrt(s-s5)*cdsqrt(s-s6)
      z2 = (s-s1)*(s-s2)+b*b
      gamma = (z1-z2)/(z1+z2)
      write (10,*) f,real(gamma),aimag(gamma)
   end do
   close (10)
  do i=1,nt
      t = (i-1)*dt+.00001*dt
      expon(i) = exp(-delta*t)
   end do
Calculate C Term
! ------
   if((om0*om0).gt.(delta*delta+gams)) then
      write(*,*) "C term 1"
      rlame = dsqrt(om0*om0-delta*delta-gams)
      do i=1.nt
         t = (i-1)*dt+.00001*dt
         c3(i) = expon(i)*sin(rlame*t)/rlame
      end do
   elseif((om0*om0).gt.(gams)) then
      write(*,*) "C term 2"
      rlame = dsqrt(delta*delta-om0*om0+gams)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
```

I.

```
c3(i) = expon(i)*sinh(rlame*t)/rlame
     end do
  else
     write(*,*) "C term 3"
     rlame = dsqrt(delta*delta-om0*om0+gams)
     c3case3 = 1
     rlame = dsqrt(delta*delta-om0*om0+gams)
     do i=1,nt/shift
        t = (i-1-nt/shift)*dt+.00001*dt
        c3(i) = -exp((-delta+rlame)*t)/(2.d0*rlame)
     end do
     do i=nt/shift+1,nt
        t = (i-1-nt/shift)*dt+.00001*dt
        c3(i) = -exp(-(delta+rlame)*t)/(2.d0*rlame)
     end do
  endif
Calculate F Term
1
Case 1: om0^2>delta^2
I.
if((om0*om0).gt.(delta*delta)) then
     write(*,*) "CASE 1"
     rlam1 = dsqrt(om0*om0-delta*delta)
     rlam5 = dsqrt(om0*om0+(b*b/(ct*ct))-delta*delta)
     do i=1,nt
        t = (i-1)*dt+.00001*dt
```

```
call jbess(rlam1*t,0,i01(i),temp)
           call jbess(rlam1*t,1,i11(i),temp)
           call jbess(rlam5*t,1,i15(i),temp)
           call jbess(rlam1*t,2,i21(i),temp)
           call jbess(rlam5*t,2,i25(i),temp)
           i11h(i) = i11(i)/t
           i15h(i) = i15(i)/t
           i21h(i) = i21(i)/t
           i25h(i) = i25(i)/t
       end do
       call conv(i11h, i15h, nt, dt, i1i1)
       call conv(i01,i15h,nt,dt,i0i1)
       do i=1,nt
           t = (i-1)*dt+.00001*dt
           ft(i) = 2.d0*expon(i)*(-rlam1*rlam5*i1i1(i)+rlam1*rlam1*
                 i21h(i)+rlam5*rlam5*i25h(i)-b*b*rlam5*i0i1(i)+
    2
    3
                 b*b*rlam1*i11(i)+b*b*b*bisin(rlam1*t)/(2.d0*rlam1))
       end do
Case 2: om0<sup>2</sup><delta<sup>2</sup>-b<sup>2</sup>/ct<sup>2</sup>
1
   elseif((om0*om0).lt.(delta*delta-(b*b/(ct*ct)))) then
       write(*,*) "CASE 2"
       rlam1 = dsqrt(delta*delta-om0*om0)
       rlam5 = dsqrt(-om0*om0-(b*b/(ct*ct))+delta*delta)
       do i=1,nt
           t = (i-1)*dt+.00001*dt
```

```
i01(i) = BESSI(0,rlam1*t)
         i11(i) = BESSI(1,rlam1*t)
         i15(i) = BESSI(1,rlam5*t)
         i21(i) = BESSI(2,rlam1*t)
         i25(i) = BESSI(2,rlam5*t)
         i11h(i) = i11(i)/t
         i15h(i) = i15(i)/t
         i21h(i) = i21(i)/t
         i25h(i) = i25(i)/t
      end do
      call conv(i11h,i15h,nt,dt,i1i1)
      call conv(i01,i15h,nt,dt,i0i1)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
         ft(i) = 2.d0*expon(i)*(-rlam1*rlam5*i1i1(i)+rlam1*rlam1*
   2
              i21h(i)+rlam5*rlam5*i25h(i)+b*b*rlam5*i0i1(i)-
   3
              b*b*rlam1*i11(i)+b*b*b*sinh(rlam1*t)/(2.d0*rlam1))
      end do
Case 3: om0^2>delta^2-b^2/ct^2 and om0^2<delta^2
else
      write(*,*) "CASE 3"
      rlam1 = dsqrt(delta*delta-om0*om0)
      rlam5 = dsqrt(om0*om0+(b*b/(ct*ct))-delta*delta)
      do i=1,nt
```

t = (i-1)*dt+.00001*dt

!

```
i01(i) = BESSI(0,rlam1*t)
         i11(i) = BESSI(1,rlam1*t)
         call jbess(rlam5*t,1,i15(i),temp)
         i21(i) = BESSI(2,rlam1*t)
         call jbess(rlam5*t,2,i25(i),temp)
         i11h(i) = i11(i)/t
         i15h(i) = i15(i)/t
         i21h(i) = i21(i)/t
         i25h(i) = i25(i)/t
      end do
      call conv(i11h, i15h, nt, dt, i1i1)
      call conv(i01,i15h,nt,dt,i0i1)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
         ft(i) = 2.d0*expon(i)*(rlam1*rlam5*i1i1(i)+rlam1*rlam1*
   2
              i21h(i)+rlam5*rlam5*i25h(i)-b*b*rlam5*i0i1(i)-
   3
              b*b*rlam1*i11(i)+b*b*b*sinh(rlam1*t)/(2.d0*rlam1))
      end do
   endif
Time Domain Reflection Coefficient (gammat.dat)
term2 = b*b*(tt*tt-1)
   if (theta.eq.45.d0) then
      call conv(ft,ft,nt,dt,f_t)
      do i=1,nt
         gammat(i) = -f_t(i)/(b*b*b*b)
```

```
end do
elseif (c3case3.eq.0) then
    call conv(c3,ft,nt,dt,c3ft)
    do i=1,nt
        gammat(i) = (ft(i)+gams*c3ft(i))/term2
        temp2(i) = gammat(i)
    end do
else
    do i=1,(nt/shift)
        ftshift(i) = 0
    end do
   do i=(nt/shift+1),nt
        ftshift(i) = ft(i-nt/shift)
    end do
    call conv(c3,ftshift,nt,dt,c3ft)
    do i=1,(nt/shift)
        f_tshift(i) = 0
    end do
    do i=(nt/shift+1),nt
        f_tshift(i) = ftshift(i-nt/shift)
    end do
    do i=1,nt
        gammat(i) = (f_tshift(i)+gams*c3ft(i))/term2
    end do
endif
open(10,file='gammat.dat',status='unknown')
do i=1,nt
```

```
if (c3case3.eq.0) then
         write(10,*) ((i-1)*dt+.00001*dt)*1.d9,gammat(i)
      else
         write(10,*) ((i-1-2*nt/(shift))*dt+.00001*dt)*1.d9,
    2
              gammat(i)
      endif
   end do
   close(10)
   end
subroutine conv(f,g,n,del,c)
ļ
!
    performs convolution of waveforms f and g using
1
    linear interpolation
ţ.
   parameter (nsize=10000)
   2
             c16=0.16666666666666666660)
   implicit real*8 (a-h,o-z)
   real*8 f(nsize),g(nsize),c(nsize)
   c(1)=0.d0
   do k=2,n
    sum = 0.d0
    do l=1,k-1
      sum = sum + c13*f(1+1)*g(k-1)
    2
               + c13*f(l)*g(k-l+1)
```

```
111
```

```
3 + c16*f(l)*g(k-l)
4 + c16*f(l+1)*g(k-l+1)
end do
c(k) = del*sum
end do
return
end
```

```
1 ------
     FUNCTION BESSI(N,X)
!
!
     This subroutine calculates the first kind modified Bessel function
!
     of integer order N, for any REAL X. We use here the classical
!
     recursion formula, when X > N. For X < N, the Miller's algorithm
     is used to avoid overflows.
Ţ
ļ
     REFERENCE:
I.
     C.W.CLENSHAW, CHEBYSHEV SERIES FOR MATHEMATICAL FUNCTIONS,
Ţ
     MATHEMATICAL TABLES, VOL.5, 1962.
!
     PARAMETER (IACC = 40, BIGNO = 1.D10, BIGNI = 1.D-10)
     REAL *8 X, BESSI, BESSIO, BESSI1, TOX, BIM, BI, BIP
     IF (N.EQ.O) THEN
     BESSI = BESSIO(X)
     RETURN
     ENDIF
     IF (N.EQ.1) THEN
```

BESSI = BESSI1(X)RETURN ENDIF IF(X.EQ.O.DO) THEN BESSI=0.DO RETURN ENDIF TOX = 2.DO/XBIP = 0.D0BI = 1.D0BESSI = 0.D0M = 2*((N+INT(SQRT(FLOAT(IACC*N))))) DO 12 J = M, 1, -1BIM = BIP+DFLOAT(J)*TOX*BI BIP = BIBI = BIM IF (ABS(BI).GT.BIGNO) THEN BI = BI*BIGNI BIP = BIP*BIGNI BESSI = BESSI*BIGNI ENDIF IF (J.EQ.N) BESSI = BIP 12 CONTINUE BESSI = BESSI*BESSIO(X)/BI RETURN END

```
! Auxiliary Bessel functions for N=0, N=1
```

FUNCTION BESSIO(X)

REAL *8 X, BESSIO, Y, P1, P2, P3, P4, P5, P6, P7,

k Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX

DATA P1, P2, P3, P4, P5, P6, P7/1. D0, 3.5156229D0, 3.0899424D0, 1.2067429D0

* ,0.2659732D0,0.360768D-1,0.45813D-2/

DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,0.1328592D-1,

- * 0.225319D-2,-0.157565D-2,0.916281D-2,-0.2057706D-1,
- * 0.2635537D-1,-0.1647633D-1,0.392377D-2/

IF(ABS(X).LT.3.75D0) THEN

Y=(X/3.75D0)**2

BESSIO=P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7))))))

ELSE

AX = ABS(X)

Y=3.75D0/AX

BX=EXP(AX)/SQRT(AX)

```
AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9))))))))
```

BESSIO=AX*BX

ENDIF

RETURN

```
END
```

! _____

FUNCTION BESSI1(X)

REAL *8 X, BESSI1, Y, P1, P2, P3, P4, P5, P6, P7,

* Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX

DATA P1, P2, P3, P4, P5, P6, P7/0.5D0, 0.87890594D0, 0.51498869D0,

* 0.15084934D0,0.2658733D-1,0.301532D-2,0.32411D-3/

DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,-0.3988024D-1,

- * -0.362018D-2,0.163801D-2,-0.1031555D-1,0.2282967D-1,
- * -0.2895312D-1,0.1787654D-1,-0.420059D-2/

IF(ABS(X).LT.3.75D0) THEN

Y=(X/3.75D0)**2

BESSI1=X*(P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7)))))))

ELSE

AX = ABS(X)

Y=3.75D0/AX

BX=EXP(AX)/SQRT(AX)

```
AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9))))))))
```

BESSI1=AX*BX

ENDIF

RETURN

END

! -----

```
subroutine jbess (x,n,bj,bjp)
c
c
c calculates jn and jn' for n positive or negative
c
implicit real*8 (a-h,o-z)
c
if (n .eq. 0) then
bj = bessj(0,x)
bjp = -bessj(1,x)
```

```
return
     endif
с
     if (n .ge. 0) then
       m = n
     else
       m = -n
      endif
с
      if (x .eq. 0.d0) then
        bj = 0.d0
       bjp1 = bessj(m+1,x)
       bjm1 = bessj(m-1,x)
        bjp = (bjm1-bjp1)/2.d0
      else
        bj
             = bessj(m,x)
            = bessj(m+1,x)
        bj1
             = -bj1 + n*bj/x
        bjp
      endif
с
      if (n .lt. 0) then
        bj
             = bj*(-1)**n
             = bjp*(-1)**n
        bjp
      endif
с
      return
      end
```

```
С
с
с
      FUNCTION BESSJO(X)
      implicit real*8 (a-h,o-z)
      REAL*8 Y,P1,P2,P3,P4,P5,Q1,Q2,Q3,Q4,Q5,R1,R2,R3,R4,R5,R6,
          S1,S2,S3,S4,S5,S6
      DATA P1,P2,P3,P4,P5/1.D0,-.1098628627D-2,.2734510407D-4,
          -.2073370639D-5,.2093887211D-6/, Q1,Q2,Q3,Q4,Q5/-.1562499995D-
     *1,
          .1430488765D-3, -. 6911147651D-5, .7621095161D-6, -. 934945152D-7/
     *
      DATA R1,R2,R3,R4,R5,R6/57568490574.D0,-13362590354.D0,651619640.7D
     *0,
          -11214424.18D0,77392.33017D0,-184.9052456D0/,
     *
     *
          S1, S2, S3, S4, S5, S6/57568490411.D0, 1029532985.D0,
     *
          9494680.718D0,59272.64853D0,267.8532712D0,1.D0/
      IF (ABS(X).LT.8.) THEN
        Y=X**2
        BESSJO=(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6))))))
            /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
     *
      ELSE
        AX = ABS(X)
        Z=8./AX
        Y=Z**2
        XX=AX-.785398164
        BESSJ0=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y
            *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
```

```
ENDIF
      RETURN
      END
С
с
с
      FUNCTION BESSJ1(X)
      implicit real*8 (a-h,o-z)
      REAL*8 Y,P1,P2,P3,P4,P5,Q1,Q2,Q3,Q4,Q5,R1,R2,R3,R4,R5,R6,
          S1, S2, S3, S4, S5, S6
      DATA R1, R2, R3, R4, R5, R6/72362614232.D0, -7895059235.D0, 242396853.1D0
     *,
          -2972611.439D0,15704.48260D0,-30.16036606D0/,
     *
          S1, S2, S3, S4, S5, S6/144725228442.D0, 2300535178.D0,
     *
          18583304.74D0,99447.43394D0,376.9991397D0,1.D0/
     *
      DATA P1, P2, P3, P4, P5/1.D0, .183105D-2, -.3516396496D-4, .2457520174D-5
     *,
          -.240337019D-6/, Q1,Q2,Q3,Q4,Q5/.04687499995D0,-.2002690873D-3
     *
     *,
          .8449199096D-5, -.88228987D-6, .105787412D-6/
     *
      IF(ABS(X).LT.8.)THEN
        Y=X**2
        BESSJ1=X*(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6)))))
     *
            /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
      ELSE
        AX = ABS(X)
```

Z=8./AX

```
Y=Z**2
```

с

С

С

```
XX=AX-2.356194491
```

BESSJ1=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y

```
* *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
```

```
* *SIGN(1.,X)
```

```
ENDIF
 RETURN
 END
 FUNCTION BESSJ(N,X)
  implicit real*8 (a-h,o-z)
 PARAMETER (IACC=40,BIGNO=1.d10,BIGNI=1.d-10)
 if (x .ge. 0.d0) then
 ff = 1.d0
else
 ff = (-1.d0) * * n
end if
xx = abs(x)
if (n .eq. 0) then
    bessj = ff*bessj0(xx)
    return
  endif
  if (n .eq. 1) then
    bessj = ff*bessj1(xx)
```

return

endif

TOX=2./Xx

IF(Xx.GT.FLOAT(N))THEN

BJM=BESSJO(Xx)

BJ=BESSJ1(Xx)

DO 11 J=1,N-1

BJP=J*TOX*BJ-BJM

BJM=BJ

BJ=BJP

11 CONTINUE

BESSJ=ff*BJ

ELSE

M=2*((N+INT(SQRT(FLOAT(IACC*N))))/2)
BESSJ=0.
JSUM=0
SUM=0.
BJP=0.
BJP=0.
BJ=1.
D0 12 J=M,1,-1
BJM=J*TOX*BJ-BJP
BJP=BJ
BJP=BJ
BJ=BJM
IF(ABS(BJ).GT.BIGN0)THEN
BJ=BJ*BIGNI
BJP=BJP*BIGNI
BSJ=BESSJ*BIGNI
SUM=SUM*BIGNI

ENDIF

IF(JSUM.NE.O)SUM=SUM+BJ

JSUM=1-JSUM

IF(J.EQ.N)BESSJ=BJP

12 CONTINUE

SUM=2.*SUM-BJ

BESSJ=ff*BESSJ/SUM

ENDIF

RETURN

END

APPENDIX C

FORTRAN CODE FOR GENERAL TE CASE

```
program general_TE
```

```
implicit none
```

integer nsize

```
parameter(nsize = 50000)
```

```
real*8 BESSI,om0,delta,b,theta,dt,ct,tt,t,pi,df,f,om,YY
  real*8 rmur,epsinf,st,rkap,f1,f2
  real*8 rlam1,rlam5,rlama,expon(nsize),gams,temp
  real*8 i11h(nsize),i15h(nsize),i15(nsize),i11(nsize)
  real*8 i21h(nsize),i25h(nsize),i1i1(nsize)
  real*8 c3ft(nsize),c3shift(nsize),ftshift(nsize)
  real*8 c3(nsize),ft(nsize),gammat(nsize)
   integer i,nt,nf,c3case3,shift
  complex*16 z1,z2,s,zj,gamma,zz1,zz2,s1,s2,s5,s6
Material Parameters
1
! ____________
  rmur = 1.d0
  epsinf = 2.d0
  om0 = 4.d11
  b = 6.24d11
```

```
delta = 2.5d10
theta = 60.d0
pi = 4.d0*atan(1.d0)
ct = cos(theta*pi/180.d0)
st = sin(theta*pi/180.d0)
tt = tan(theta*pi/180.d0)
z_j=dcmplx(0.d0,1.d0)
c3case3 = 0
shift = 8
rkap = dsqrt(rmur*epsinf-st*st)
gams = om0*om0-(rmur*b*b)/(rmur*rmur*ct*ct-rkap*rkap)
f1 = 2.d0*rkap*rmur*ct/(rmur*ct+rkap)
f2 = f1/(rmur*rmur*ct*ct-rkap*rkap)
df = 0.4d0
nf = 4095 * 2
nt = 4096 * 2
dt = 2.d-13
write(*,*) om0*om0
write(*,*) delta*delta-rmur*b*b/(rkap*rkap)
zz1 = cdsqrt(dcmplx(delta*delta-om0*om0,0.d0))
s1 = -delta+zz1
s2 = -delta-zz1
zz2 = cdsqrt(dcmplx(delta*delta-om0*om0-rmur*b*b/(rkap*rkap),0.d0))
s5 = -delta+zz2
s6 = -delta-zz2
```

С

```
Frequency Domain Reflection Coefficient (gamma.dat)
1
open (10,file='gamma.dat',status='unknown')
  do i=1,nf
     f = df * i
     om = 2.d0*pi*f*1.d9
     s = zj * om
     z1 = rmur*ct*cdsqrt(s-s1)*cdsqrt(s-s2)
     z2 = rkap*cdsqrt(s-s5)*cdsqrt(s-s6)
     gamma = (z1-z2)/(z1+z2)-(rmur*ct-rkap)/(rmur*ct+rkap)
     write (10,*) f,real(gamma),aimag(gamma)
  end do
  close (10)
  do i=1,nt
     t = (i-1)*dt+.00001*dt
     expon(i) = exp(-delta*t)
  end do
Calculate C Term
L
if(gams.gt.(delta*delta)) then
     write(*,*) "C term 1"
     rlama = dsqrt(gams-delta*delta)
     do i=1,nt
```

```
t = (i-1)*dt+.00001*dt
c3(i) = expon(i)*sin(rlama*t)/rlama
end do
elseif(0.gt.gams) then
write(*,*) "C term 3"
rlama = dsqrt(delta*delta-gams)
c3case3 = 1
do i=1,nt/shift
t = (i-1-nt/shift)*dt+.00001*dt
c3(i) = -exp((-delta+rlama)*t)/(2.d0*rlama)
end do
do i=nt/shift+1,nt
t = (i-1-nt/shift)*dt+.00001*dt
c3(i) = -exp(-(delta+rlama)*t)/(2.d0*rlama)
end do
```

```
else
```

```
write(*,*) "C term 2"
rlama = dsqrt(delta*delta-gams)
do i=1,nt
    t = (i-1)*dt+.00001*dt
    c3(i) = expon(i)*sinh(rlama*t)/rlama
end do
```

```
endif
```

```
! ------
```

! Calculate G Term

```
Case 1: om0<sup>2</sup>>delta<sup>2</sup>
if((om0*om0).gt.(delta*delta)) then
     write(*,*) "CASE 1"
     rlam1 = dsqrt(om0*om0-delta*delta)
     rlam5 = dsqrt(om0*om0+(rmur*b*b/(rkap*rkap))-delta*delta)
     do i=1,nt
         t = (i-1)*dt+.00001*dt
         call jbess(rlam1*t,1,i11h(i),temp)
         call jbess(rlam5*t,1,i15(i),temp)
         call jbess(rlam1*t,2,i21h(i),temp)
         call jbess(rlam5*t,2,i25h(i),temp)
         i11h(i) = i11h(i)/t
         i15h(i) = i15(i)/t
         i21h(i) = i21h(i)/t
         i25h(i) = i25h(i)/t
      end do
      call conv(i11h,i15h,nt,dt,i1i1)
      do i=1,nt
         ft(i) = expon(i)*(rmur*ct+rkap)*(-rlam1*rlam5*i1i1(i)+
   2
             rlam1*rlam1*i21h(i)+rlam5*rlam5*i25h(i))
      end do
 Case 2: om0<sup>2</sup><delta<sup>2</sup>-rmur*b<sup>2</sup>/rkap<sup>2</sup>
I.
elseif((om0*om0).lt.(delta*delta-(rmur*b*b/(rkap*rkap)))) then
```

```
126
```

```
write(*,*) "CASE 2"
      rlam1 = dsqrt(delta*delta-om0*om0)
      rlam5 = dsqrt(delta*delta-om0*om0-rmur*b*b/(rkap*rkap))
      do i=1.nt
         t = (i-1)*dt+.00001*dt
         i11(i) = BESSI(1,rlam1*t)
         i15(i) = BESSI(1,rlam5*t)
         i21h(i) = BESSI(2,rlam1*t)
         i25h(i) = BESSI(2,rlam5*t)
         i11h(i) = i11(i)/t
         i15h(i) = i15(i)/t
         i21h(i) = i21h(i)/t
         i25h(i) = i25h(i)/t
      end do
      call conv(i11h,i15h,nt,dt,i1i1)
      do i=1,nt
         ft(i) = expon(i)*(rmur*ct+rkap)*(-rlam1*rlam5*i1i1(i)+
   2
              rlam1*rlam1*i21h(i)+rlam5*rlam5*i25h(i))
      end do
Case 3: om0^2>delta^2-rmur*b^2/rkap^2 and om0^2<delta^2
1
else
      write(*,*) "CASE 3"
      rlam1 = dsqrt(delta*delta-om0*om0)
      rlam5 = dsqrt(om0*om0+(rmur*b*b/(rkap*rkap))-delta*delta)
      do i=1,nt
```

```
t = (i-1)*dt+.00001*dt
         i11h(i) = BESSI(1,rlam1*t)
         call jbess(rlam5*t,1,i15(i),temp)
         i21h(i) = BESSI(2,rlam1*t)
         call jbess(rlam5*t,2,i25h(i),temp)
         i11h(i) = i11h(i)/t
         i15h(i) = i15(i)/t
         i21h(i) = i21h(i)/t
         i25h(i) = i25h(i)/t
      end do
      call conv(i11h,i15h,nt,dt,i1i1)
      do i=1,nt
         ft(i) = expon(i)*(rmur*ct+rkap)*(rlam1*rlam5*i1i1(i)+
   2
              rlam1*rlam1*i21h(i)+rlam5*rlam5*i25h(i))
      end do
   endif
| ______
   Time Domain Reflection Coefficient (gammat.dat)
1
YY = (rmur*b*b)*(rkap-rmur*ct)/(2.d0*rkap*rkap)
   if (ct.eq.rkap/rmur) then
      write(*,*) 'Special Denom'
      do i=1,nt
         gammat(i) = -f1*ft(i)/(rmur*b*b)
      end do
   elseif (c3case3.eq.0) then
      call conv(c3,ft,nt,dt,c3ft)
```

```
128
```

```
do i=1,nt
        gammat(i) = f2*(c3ft(i)+YY*c3(i))
    end do
else
    write(*,*) 'non-causal'
    do i=1,(nt/shift)
        ftshift(i) = 0
    end do
    do i=(nt/shift+1),nt
        ftshift(i) = ft(i-nt/shift)
    end do
    call conv(c3,ftshift,nt,dt,c3ft)
    do i=1,(nt/shift+1)
        c3shift(i) = 0
    end do
    do i=(nt/shift+2),nt
        c3shift(i) = c3(i-nt/shift-1)
    end do
    do i=1,nt
        gammat(i) = f2*(c3ft(i)+YY*c3shift(i))
    end do
endif
open(10,file='gammat.dat',status='unknown')
do i=1,nt
    if (c3case3.eq.0) then
```

```
write(10,*) ((i-1)*dt+.00001*dt)*1.d9,gammat(i)
```

```
else
         write(10,*) ((i-1-2*nt/(shift))*dt+.00001*dt)*1.d9,gammat(i)
      endif
   end do
   close(10)
   end
            subroutine conv(f,g,n,del,c)
ļ
ļ
    performs convolution of waveforms f and g using
!
    linear interpolation
ļ
   parameter (nsize=10000)
   2
              c16=0.166666666666666666660)
   implicit real*8 (a-h,o-z)
   real*8 f(nsize),g(nsize),c(nsize)
   c(1)=0.d0
   do k=2,n
    sum = 0.d0
    do l=1,k-1
      sum = sum + c13*f(1+1)*g(k-1)
    2
                + c13*f(l)*g(k-l+1)
                + c16*f(l)*g(k-l)
    3
                + c16*f(l+1)*g(k-l+1)
    4
```

```
end do
c(k) = del*sum
end do
return
end
```

```
1 ---
     FUNCTION BESSI(N,X)
ļ
!
     This subroutine calculates the first kind modified Bessel function
1
     of integer order N, for any REAL X. We use here the classical
1
     recursion formula, when X > N. For X < N, the Miller's algorithm
ļ
     is used to avoid overflows.
1
     REFERENCE:
1
     C.W.CLENSHAW, CHEBYSHEV SERIES FOR MATHEMATICAL FUNCTIONS,
!
     MATHEMATICAL TABLES, VOL.5, 1962.
Ţ
     PARAMETER (IACC = 40, BIGNO = 1.D10, BIGNI = 1.D-10)
     REAL *8 X, BESSI, BESSIO, BESSI1, TOX, BIM, BI, BIP
     IF (N.EQ.O) THEN
     BESSI = BESSIO(X)
     RETURN
     ENDIF
     IF (N.EQ.1) THEN
     BESSI = BESSI1(X)
     RETURN
```

```
ENDIF
    IF(X.EQ.O.DO) THEN
    BESSI=0.DO
    RETURN
    ENDIF
    TOX = 2.DO/X
    BIP = 0.D0
    BI = 1.DO
    BESSI = 0.D0
    M = 2*((N+INT(SQRT(FLOAT(IACC*N)))))
    DO 12 J = M, 1, -1
    BIM = BIP+DFLOAT(J)*TOX*BI
    BIP = BI
    BI = BIM
    IF (ABS(BI).GT.BIGNO) THEN
    BI = BI*BIGNI
    BIP = BIP*BIGNI
    BESSI = BESSI*BIGNI
    ENDIF
    IF (J.EQ.N) BESSI = BIP
  12 CONTINUE
    BESSI = BESSI*BESSIO(X)/BI
    RETURN
    END
! Auxiliary Bessel functions for N=0, N=1
```

```
FUNCTION BESSIO(X)
```

REAL *8 X, BESSIO, Y, P1, P2, P3, P4, P5, P6, P7,

* Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX

DATA P1, P2, P3, P4, P5, P6, P7/1. D0, 3.5156229D0, 3.0899424D0, 1.2067429D0

* ,0.2659732D0,0.360768D-1,0.45813D-2/

DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,0.1328592D-1,

- * 0.225319D-2,-0.157565D-2,0.916281D-2,-0.2057706D-1,
- * 0.2635537D-1,-0.1647633D-1,0.392377D-2/

IF(ABS(X).LT.3.75D0) THEN

Y=(X/3.75D0)**2

```
BESSIO=P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7))))))
```

ELSE

AX = ABS(X)

Y=3.75D0/AX

BX=EXP(AX)/SQRT(AX)

AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9)))))))))

BESSIO=AX*BX

ENDIF

RETURN

END

FUNCTION BESSI1(X)

REAL *8 X, BESSI1, Y, P1, P2, P3, P4, P5, P6, P7,

* Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX

DATA P1,P2,P3,P4,P5,P6,P7/0.5D0,0.87890594D0,0.51498869D0,

- * 0.15084934D0,0.2658733D-1,0.301532D-2,0.32411D-3/
 DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,-0.3988024D-1,
- * -0.362018D-2,0.163801D-2,-0.1031555D-1,0.2282967D-1,
```
* -0.2895312D-1,0.1787654D-1,-0.420059D-2/
IF(ABS(X).LT.3.75D0) THEN
Y=(X/3.75D0)**2
BESSI1=X*(P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7)))))
ELSE
AX=ABS(X)
Y=3.75D0/AX
BX=EXP(AX)/SQRT(AX)
AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9))))))
BESSI1=AX*BX
ENDIF
RETURN
END
```

```
! ------
```

```
subroutine jbess (x,n,bj,bjp)
c
c
c calculates jn and jn' for n positive or negative
c
implicit real*8 (a-h,o-z)
c
if (n .eq. 0) then
bj = bessj(0,x)
bjp = -bessj(1,x)
return
endif
```

с if (n .ge. 0) then m = nelse m = -nendif с if (x . eq. 0.d0) then bj = 0.d0bjp1 = bessj(m+1,x)bjm1 = bessj(m-1,x) bjp = (bjm1-bjp1)/2.d0else = bessj(m,x) bj = bessj(m+1,x) bj1 = -bj1 + n*bj/x bjp endif с if (n .lt. 0) then bj = bj*(-1)**n = bjp*(-1)**n bjp endifс return endС

С

с

```
FUNCTION BESSJO(X)
```

implicit real*8 (a-h,o-z)

REAL*8 Y,P1,P2,P3,P4,P5,Q1,Q2,Q3,Q4,Q5,R1,R2,R3,R4,R5,R6,

* \$1,\$2,\$3,\$4,\$5,\$6

DATA P1,P2,P3,P4,P5/1.D0,-.1098628627D-2,.2734510407D-4,

* -.2073370639D-5,.2093887211D-6/, Q1,Q2,Q3,Q4,Q5/-.1562499995D-*1,

* .1430488765D-3, -.6911147651D-5,.7621095161D-6, -.934945152D-7/
 DATA R1,R2,R3,R4,R5,R6/57568490574.D0, -13362590354.D0,651619640.7D
 *0,

- * -11214424.18D0,77392.33017D0,-184.9052456D0/,
- * S1,S2,S3,S4,S5,S6/57568490411.D0,1029532985.D0,
- * 9494680.718D0,59272.64853D0,267.8532712D0,1.D0/

IF(ABS(X).LT.8.)THEN

Y=X**2

BESSJO=(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6)))))

* /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))

ELSE

AX = ABS(X)

Z=8./AX

Y=Z**2

XX=AX-.785398164

```
BESSJ0=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y
```

```
* *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
```

ENDIF

RETURN

```
END
С
с
с
      FUNCTION BESSJ1(X)
      implicit real*8 (a-h,o-z)
      REAL*8 Y, P1, P2, P3, P4, P5, Q1, Q2, Q3, Q4, Q5, R1, R2, R3, R4, R5, R6,
          S1,S2,S3,S4,S5,S6
      DATA R1,R2,R3,R4,R5,R6/72362614232.D0,-7895059235.D0,242396853.1D0
     *,
     *
          -2972611.439D0,15704.48260D0,-30.16036606D0/,
          S1, S2, S3, S4, S5, S6/144725228442.D0, 2300535178.D0,
     *
          18583304.74D0,99447.43394D0,376.9991397D0,1.D0/
     *
      DATA P1, P2, P3, P4, P5/1.D0, .183105D-2, -.3516396496D-4, .2457520174D-5
     *,
          -.240337019D-6/, Q1,Q2,Q3,Q4,Q5/.04687499995D0,-.2002690873D-3
     *
     *,
           .8449199096D-5, -.88228987D-6, .105787412D-6/
     *
      IF(ABS(X).LT.8.)THEN
        Y=X**2
        BESSJ1=X*(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6))))))
            /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
     *
      ELSE
        AX = ABS(X)
        Z=8./AX
```

Y=Z**2

XX=AX-2.356194491

```
BESSJ1=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y
            *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
     *
            *SIGN(1.,X)
     *
     ENDIF
     RETURN
     END
с
с
с
      FUNCTION BESSJ(N,X)
      implicit real*8 (a-h,o-z)
      PARAMETER (IACC=40,BIGNO=1.d10,BIGNI=1.d-10)
      if (x .ge. 0.d0) then
      ff = 1.d0
    else
     ff = (-1.d0) * * n
    end if
    xx = abs(x)
    if (n .eq. 0) then
        bessj = ff*bessj0(xx)
        return
      endif
      if (n .eq. 1) then
        bessj = ff*bessj1(xx)
        return
      endif
      TOX=2./Xx
```

IF(Xx.GT.FLOAT(N))THEN

BJM=BESSJO(Xx)

BJ=BESSJ1(Xx)

DO 11 J=1,N-1

BJP=J*TOX*BJ-BJM

BJM=BJ

BJ=BJP

11 CONTINUE

BESSJ=ff*BJ

ELSE

M=2*((N+INT(SQRT(FLOAT(IACC*N))))/2)
BESSJ=0.
JSUM=0
SUM=0.
BJP=0.
BJ=1.
D0 12 J=M,1,-1
BJM=J*TOX*BJ-BJP
BJP=BJ
BJ=BJM
IF(ABS(BJ).GT.BIGNO)THEN
BJ=BJ*BIGNI
BJP=BJP*BIGNI
BESSJ=BESSJ*BIGNI

SUM=SUM*BIGNI

ENDIF

IF(JSUM.NE.O)SUM=SUM+BJ

JSUM=1-JSUM

IF(J.EQ.N)BESSJ=BJP

12 CONTINUE

SUM=2.*SUM-BJ

BESSJ=ff*BESSJ/SUM

ENDIF

RETURN

END

APPENDIX D

FORTRAN CODE FOR GENERAL TM CASE

program general_TM

implicit none

integer nsize

parameter(nsize = 50000)

```
real*8 BESSI,om0,delta,b,theta,dt,ct,st,tt,t,pi,df,f,om,YY
  real*8 rmur,epsinf,rkap,f1,sigma,chi
  real*8 rlam1,rlam5,rlamc,rlame,expon(nsize),gams,temp
  real*8 i11h(nsize),i15h(nsize),i15(nsize),i11(nsize)
  real*8 i21h(nsize),i25h(nsize),i1i1(nsize),i01(nsize)
  real*8 c3ft(nsize),c3shift(nsize),ftshift(nsize)
  real*8 c3(nsize),ft(nsize),gammat(nsize),i0i1(nsize)
  real*8 c1(nsize),c2(nsize),ta(nsize),scale
   integer i,nt,nf,c1nc,c2nc,shift,c3case3
   complex*16 z1,z2,s,zj,gamma,zz1,zz2,s1,s2,s5,s6
Material Parameters
| ______
  rmur = 1.d0
   epsinf = 2.d0
```

```
om0 = 4.d11
```

1

b = 6.24d11
delta = 2.5d10
theta = 60.d0

```
pi = 4.d0*atan(1.d0)
ct = cos(theta*pi/180.d0)
st = sin(theta*pi/180.d0)
tt = tan(theta*pi/180.d0)
zj = dcmplx(0.d0,1.d0)
c1nc = 0
c2nc = 0
c3case3 = 0
scale = 1.d-20
```

```
rkap = dsqrt(rmur*epsinf-st*st)
gams = b*b*(rmur-2.d0*epsinf*ct*ct)/(rkap*rkap-epsinf*epsinf*ct*ct)
sigma = dsqrt(rmur*rmur-sin(2.d0*theta*pi/180.d0)*
2 sin(2.d0*theta*pi/180.d0))
chi = (b*b*sigma)/(2.d0*(rkap*rkap-epsinf*epsinf*ct*ct))
shift = 8
YY = b*b*(rkap-epsinf*ct)*(rmur*epsinf-2.d0*rkap*rkap)/
2 (2.d0*rkap*rkap*epsinf)
f1 = (2.d0*rkap*rkap*epsinf*ct)/((rkap+epsinf*ct)*(rkap+epsinf*ct)*
2 (rkap-epsinf*ct))
df = 0.4d0
nf = 4095*8
```

```
nt = 4096 * 2
   dt = 1d - 13
С
   zz1 = cdsqrt(dcmplx(delta*delta-om0*om0,0.d0))
   s1 = -delta+zz1
   s2 = -delta-zz1
   zz2 = cdsqrt(dcmplx(delta*delta-om0*om0-rmur*b*b/(rkap*rkap),0.d0))
   s5 = -delta+zz2
   s6 = -delta-zz2
| -----
                                             _____
    Frequency Domain Reflection Coefficient (gamma.dat)
1 ------
   open (10,file='gamma.dat',status='unknown')
   do i=1,nf
      f = df * i
      om = 2.d0*pi*f*1.d9
      s = zj * om
      z1 = cdsqrt(s-s1)*cdsqrt(s-s2)*cdsqrt(s-s5)*cdsqrt(s-s6)
      z2 = epsinf*ct*((s-s1)*(s-s2)+b*b/epsinf)
       gamma = (rkap*z1-z2)/(rkap*z1+z2)-(rkap-epsinf*ct)/(rkap+epsinf*ct)
       write (10,*) f,real(gamma),aimag(gamma)
   end do
   close (10)
   do i=1,nt
       t = (i-1)*dt+.00001*dt
```

```
expon(i) = exp(-delta*t)
   end do
Calculate C1 Term
1
 _____
   if(om0*om0+(gams/2.d0)-chi.gt.(delta*delta)) then
      write(*,*) "C1 term 1"
      rlamc = dsqrt(om0*om0+(gams/2.d0)-chi-delta*delta)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
          c1(i) = (sigma-rmur+2.d0*epsinf*ct*ct)*expon(i)*
    2
               sin(rlamc*t)/(2.d0*sigma*rlamc)
      end do
   elseif(om0*om0+(gams/2.d0)-chi.lt.0) then
      write(*,*) "C1 term 3"
      rlamc = dsqrt(-om0*om0-(gams/2.d0)+chi+delta*delta)
      clnc = 1
      c3case3 = 1
      do i=1.nt/shift
          t = (i-1-nt/shift)*dt+.00001*dt
          c1(i) = -(sigma-rmur+2.d0*epsinf*ct*ct)*
               exp((-delta+rlamc)*t)/(4.d0*sigma*rlamc)
    2
      end do
      do i=nt/shift+1,nt
          t = (i-1-nt/shift)*dt+.00001*dt
          c1(i) = -(sigma-rmur+2.d0*epsinf*ct*ct)*
```

end do

else

2

```
write(*,*) "C1 term 2"
rlamc = dsqrt(-om0*om0-(gams/2.d0)+chi+delta*delta)
do i=1,nt
    t = (i-1)*dt+.00001*dt
    c1(i) = (sigma-rmur+2.d0*epsinf*ct*ct)*expon(i)*
    sinh(rlamc*t)/(2.d0*sigma*rlamc)
end do
```

 ${\tt endif}$

```
_____
Ł
   Calculate C2 Term
1 ------
  if(om0*om0+(gams/2.d0)+chi.gt.(delta*delta)) then
     write(*,*) "C2 term 1"
     rlame = dsqrt(om0*om0+(gams/2.d0)+chi-delta*delta)
     do i=1,nt
         t = (i-1)*dt+.00001*dt
         c2(i) = (sigma+rmur-2.d0*epsinf*ct*ct)*expon(i)*
   2
             sin(rlame*t)/(2.d0*sigma*rlame)
      end do
  elseif(om0*om0+(gams/2.d0)+chi.lt.0) then
     write(*,*) "C2 term 3"
     rlame = dsqrt(-om0*om0-(gams/2.d0)-chi+delta*delta)
```

```
c2nc = 1
c3case3 = 1
do i=1,nt/shift
    t = (i-1-nt/shift)*dt+.00001*dt
    c2(i) = -(sigma+rmur-2.d0*epsinf*ct*ct)*
2         exp((-delta+rlame)*t)/(4.d0*sigma*rlame)
end do
do i=nt/shift+1,nt
    t = (i-1-nt/shift)*dt+.00001*dt
    c2(i) = -(sigma+rmur-2.d0*epsinf*ct*ct)*
2         exp(-(delta+rlame)*t)/(4.d0*sigma*rlame)
end do
```

```
else
```

```
write(*,*) "C2 term 2"
rlame = dsqrt(-om0*om0-(gams/2.d0)-chi+delta*delta)
do i=1,nt
    t = (i-1)*dt+.00001*dt
    c2(i) = (sigma+rmur-2.d0*epsinf*ct*ct)*expon(i)*
        sinh(rlame*t)/(2.d0*sigma*rlame)
```

end do

endif

2

```
! -----
! Shift and add C terms
! -----
if (c3case3.ne.0) then
```

```
if (c1nc.eq.0) then
       write(*,*) 'shift c1'
       ta = c1;
       do i=1,(nt/shift)
           c1(i) = 0
       end do
       do i=(nt/shift+1),nt
           c1(i) = ta(i-nt/shift)
       end do
   endif
   if (c2nc.eq.0) then
       write(*,*) 'shift c2'
       ta = c2;
       do i=1,(nt/shift)
           c2(i) = 0
        end do
        do i=(nt/shift+1),nt
            c2(i) = ta(i-nt/shift)
        end do
    endif
endif
do i=1,nt
    c3(i) = c1(i)+c2(i)
```

end do

```
Calculate F Term
1
| ______
   Case 1: om0<sup>2</sup>>delta<sup>2</sup>
I.
1 ------
   if((om0*om0).gt.(delta*delta)) then
      write(*,*) "CASE 1"
      rlam1 = dsqrt(om0*om0-delta*delta)
      rlam5 = dsqrt(om0*om0+(rmur*b*b/(rkap*rkap))-delta*delta)
      do i=1.nt
         t = (i-1)*dt+.00001*dt
         call jbess(rlam1*t,0,i01(i),temp)
         call jbess(rlam1*t,1,i11(i),temp)
         call jbess(rlam5*t,1,i15h(i),temp)
         call jbess(rlam1*t,2,i21h(i),temp)
         call jbess(rlam5*t,2,i25h(i),temp)
         i11h(i) = i11(i)/t
         i15h(i) = i15h(i)/t
         i21h(i) = i21h(i)/t
         i25h(i) = i25h(i)/t
      end do
      call conv(i01,i15h,nt,dt,i0i1)
      call conv(i11h,i15h,nt,dt,i1i1)
      do i=1,nt
         t = (i-1)*dt+.00001*dt
         ft(i) = expon(i)*((epsinf*ct+rkap)*(-rlam1*rlam5*i1i1(i)-
    2
              (b*b/epsinf)*rlam5*i0i1(i)+(b*b/epsinf)*rlam1*i11(i)+
```

```
3
               rlam1*rlam1*i21h(i)+rlam5*rlam5*i25h(i))+
               (b*b*b*b*ct/(epsinf*rlam1))*sin(rlam1*t))
    4
      end do
1
    Case 2: om0<sup>2</sup><delta<sup>2</sup>-rmur*b<sup>2</sup>/rkap<sup>2</sup>
elseif((om0*om0).lt.(delta*delta-(rmur*b*b/(rkap*rkap)))) then
      write(*,*) "CASE 2"
      rlam1 = dsqrt(delta*delta-om0*om0)
      rlam5 = dsqrt(delta*delta-om0*om0-rmur*b*b/(rkap*rkap))
      do i=1,nt
          t = (i-1)*dt+.00001*dt
          i01(i) = BESSI(0,rlam1*t)
          i11(i) = BESSI(1,rlam1*t)
          i15h(i) = BESSI(1,rlam5*t)
          i21h(i) = BESSI(2,rlam1*t)
          i25h(i) = BESSI(2,rlam5*t)
          i11h(i) = i11(i)/t
          i15h(i) = i15h(i)/t
          i21h(i) = i21h(i)/t
          i25h(i) = i25h(i)/t
       end do
       call conv(i01,i15h,nt,dt,i0i1)
       call conv(i11h,i15h,nt,dt,i1i1)
       do i=1,nt
          t = (i-1)*dt+.00001*dt
          ft(i) = expon(i)*((epsinf*ct+rkap)*(-rlam1*rlam5*i1i1(i)+
```

```
2
               (b*b/epsinf)*rlam5*i0i1(i)-(b*b/epsinf)*rlam1*i11(i)+
              rlam1*rlam1*i21h(i)+rlam5*rlam5*i25h(i))+
    3
    4
               (b*b*b*ct/(epsinf*rlam1))*sinh(rlam1*t))
      end do
Case 3: om0^2>delta^2-rmur*b^2/rkap^2 and om0^2<delta^2
!
else
      write(*,*) "CASE 3"
      rlam1 = dsqrt(delta*delta-om0*om0)
      rlam5 = dsqrt(om0*om0+(rmur*b*b/(rkap*rkap))-delta*delta)
      do i=1,nt
          t = (i-1)*dt+.00001*dt
          i01(i) = BESSI(0,rlam1*t)
          i11(i) = BESSI(1,rlam1*t)
          call jbess(rlam5*t,1,i15h(i),temp)
          i21h(i) = BESSI(2,rlam1*t)
          call jbess(rlam5*t,2,i25h(i),temp)
          i11h(i) = i11(i)/t
          i15h(i) = i15h(i)/t
          i21h(i) = i21h(i)/t
          i25h(i) = i25h(i)/t
      end do
      call conv(i01,i15h,nt,dt,i0i1)
      call conv(i11h, i15h, nt, dt, i1i1)
      do i=1,nt
          t = (i-1)*dt+.00001*dt
```

```
ft(i) = expon(i)*((epsinf*ct+rkap)*(rlam1*rlam5*i1i1(i)-
   2
              (b*b/epsinf)*rlam5*i0i1(i)-(b*b/epsinf)*rlam1*i11(i)+
   3
              rlam1*rlam1*i21h(i)+rlam5*rlam5*i25h(i))+
   4
              (b*b*b*ct/(epsinf*rlam1))*sinh(rlam1*t))
      end do
   endif
L
   Time Domain Reflection Coefficient (gammat.dat)
if (c3case3.eq.0) then
      call conv(c3,ft,nt,dt,c3ft)
      do i=1,nt
         gammat(i) = f1*(c3ft(i)+YY*c3(i))
      end do
   else
      write(*,*) 'non-causal'
      do i=1,(nt/shift)
         ftshift(i) = 0
      end do
      do i=(nt/shift+1),nt
         ftshift(i) = ft(i-nt/shift)
      end do
      call conv(c3,ftshift,nt,dt,c3ft)
      do i=1,(nt/shift+1)
         c3shift(i) = 0
      end do
      do i=(nt/shift+2),nt
```

```
c3shift(i) = c3(i-nt/shift-1)
      end do
      do i=1,nt
          gammat(i) = f1*(c3ft(i)+YY*c3shift(i))
      end do
   endif
   open(10,file='gammat.dat',status='unknown')
   do i=1,nt
      if (c3case3.eq.0) then
          write(10,*) ((i-1)*dt+.00001*dt)*1.d9,gammat(i)
      else
          write(10,*) ((i-1-2*nt/(shift))*dt+.00001*dt)*1.d9,gammat(i)
      endif
   end do
   close(10)
   end
subroutine conv(f,g,n,del,c)
    performs convolution of waveforms f and g using
     linear interpolation
   parameter (nsize=10000)
   parameter (c13=0.333333333333333333333333,
```

!

ļ

!

ļ

```
2
             c16=0.1666666666666666666660)
implicit real*8 (a-h,o-z)
real*8 f(nsize),g(nsize),c(nsize)
c(1)=0.d0
do k=2,n
  sum = 0.d0
  do l=1,k-1
    sum = sum + c13*f(1+1)*g(k-1)
 2
               + c13*f(1)*g(k-l+1)
                + c16*f(l)*g(k-l)
 3
 4
                + c16*f(l+1)*g(k-l+1)
  end do
  c(k) = del*sum
end do
return
end
```

```
FUNCTION BESSI(N,X)
This subroutine calculates the first kind modified Bessel function
of integer order N, for any REAL X. We use here the classical
recursion formula, when X > N. For X < N, the Miller's algorithm
is used to avoid overflows.
REFERENCE:
REFERENCE:
C.W.CLENSHAW, CHEBYSHEV SERIES FOR MATHEMATICAL FUNCTIONS,</pre>
```

! MATHEMATICAL TABLES, VOL.5, 1962.

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```
PARAMETER (IACC = 40, BIGNO = 1.D10, BIGNI = 1.D-10)
REAL *8 X, BESSI, BESSIO, BESSI1, TOX, BIM, BI, BIP
IF (N.EQ.O) THEN
BESSI = BESSIO(X)
RETURN
ENDIF
IF (N.EQ.1) THEN
BESSI = BESSI1(X)
                      .
RETURN
ENDIF
IF(X.EQ.O.DO) THEN
BESSI=0.DO
RETURN
ENDIF
TOX = 2.DO/X
BIP = 0.D0
BI = 1.DO
BESSI = 0.D0
M = 2*((N+INT(SQRT(FLOAT(IACC*N)))))
DO 12 J = M, 1, -1
BIM = BIP+DFLOAT(J)*TOX*BI
BIP = BI
BI = BIM
IF (ABS(BI).GT.BIGNO) THEN
BI = BI*BIGNI
```

```
BIP = BIP*BIGNI
     BESSI = BESSI*BIGNI
     ENDIF
     IF (J.EQ.N) BESSI = BIP
  12 CONTINUE
     BESSI = BESSI * BESSIO(X) / BI
     RETURN
     END
| -----
          _____
                                       ! Auxiliary Bessel functions for N=0, N=1
     FUNCTION BESSIO(X)
     REAL *8 X, BESSIO, Y, P1, P2, P3, P4, P5, P6, P7,
    *
         Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX
     DATA P1, P2, P3, P4, P5, P6, P7/1. D0, 3.5156229D0, 3.0899424D0, 1.2067429D0
         ,0.2659732D0,0.360768D-1,0.45813D-2/
    *
     DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,0.1328592D-1,
         0.225319D-2,-0.157565D-2,0.916281D-2,-0.2057706D-1,
     *
         0.2635537D-1,-0.1647633D-1,0.392377D-2/
    *
     IF(ABS(X).LT.3.75D0) THEN
     Y = (X/3.75D0) * * 2
     BESSI0=P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7))))))
     ELSE
     AX = ABS(X)
     Y=3.75D0/AX
     BX=EXP(AX)/SQRT(AX)
     AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9)))))))))
     BESSIO=AX*BX
```

```
ENDIF
```

RETURN

END

FUNCTION BESSI1(X)

REAL *8 X,BESSI1,Y,P1,P2,P3,P4,P5,P6,P7,

* Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9,AX,BX

DATA P1, P2, P3, P4, P5, P6, P7/0.5D0, 0.87890594D0, 0.51498869D0,

* 0.15084934D0,0.2658733D-1,0.301532D-2,0.32411D-3/

DATA Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8,Q9/0.39894228D0,-0.3988024D-1,

- * -0.362018D-2,0.163801D-2,-0.1031555D-1,0.2282967D-1,
- * -0.2895312D-1,0.1787654D-1,-0.420059D-2/

IF(ABS(X).LT.3.75D0) THEN

```
Y = (X/3.75D0) * * 2
```

```
BESSI1=X*(P1+Y*(P2+Y*(P3+Y*(P4+Y*(P5+Y*(P6+Y*P7)))))))
```

ELSE

AX = ABS(X)

Y=3.75D0/AX

BX=EXP(AX)/SQRT(AX)

```
AX=Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*(Q5+Y*(Q6+Y*(Q7+Y*(Q8+Y*Q9)))))))))
```

BESSI1=AX*BX

ENDIF

RETURN

END

1 ------

```
subroutine jbess (x,n,bj,bjp)
с
c calculates jn and jn' for n positive or negative
с
     implicit real*8 (a-h,o-z)
с
    if (n .eq. 0) then
       bj = bessj(0,x)
       bjp = -bessj(1,x)
       return
      endif
с
      if (n .ge. 0) then
       m = n
      else
       m = -n
      endif
с
      if (x . eq. 0.d0) then
        bj = 0.d0
       bjp1 = bessj(m+1,x)
        bjm1 = bessj(m-1,x)
        bjp = (bjm1-bjp1)/2.d0
      else
             = bessj(m,x)
        bj
        bj1 = bessj(m+1,x)
        bjp = -bj1 + n*bj/x
```

```
endif
с
      if (n .lt. 0) then
        bj = bj*(-1)**n
        bjp = bjp*(-1)**n
      endif
с
      return
      end
с
с
С
      FUNCTION BESSJO(X)
      implicit real*8 (a-h,o-z)
      REAL*8 Y,P1,P2,P3,P4,P5,Q1,Q2,Q3,Q4,Q5,R1,R2,R3,R4,R5,R6,
          S1,S2,S3,S4,S5,S6
     *
      DATA P1,P2,P3,P4,P5/1.D0,-.1098628627D-2,.2734510407D-4,
          -.2073370639D-5,.2093887211D-6/, Q1,Q2,Q3,Q4,Q5/-.1562499995D-
     *
     *1,
          .1430488765D-3, -.6911147651D-5, .7621095161D-6, -.934945152D-7/
     *
      DATA R1, R2, R3, R4, R5, R6/57568490574. D0, -13362590354. D0, 651619640.7D
     *0,
          -11214424.18D0,77392.33017D0,-184.9052456D0/,
     *
          S1,S2,S3,S4,S5,S6/57568490411.D0,1029532985.D0,
     *
          9494680.718D0,59272.64853D0,267.8532712D0,1.D0/
     *
      IF(ABS(X).LT.8.)THEN
        Y=X**2
```

```
158
```

```
BESSJO=(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6)))))
       /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
*
ELSE
  AX = ABS(X)
  Z=8./AX
  Y=Z**2
  XX=AX-.785398164
  BESSJ0=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y
       *P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
*
ENDIF
RETURN
END
FUNCTION BESSJ1(X)
 implicit real*8 (a-h,o-z)
REAL*8 Y,P1,P2,P3,P4,P5,Q1,Q2,Q3,Q4,Q5,R1,R2,R3,R4,R5,R6,
     S1,S2,S3,S4,S5,S6
*
DATA R1, R2, R3, R4, R5, R6/72362614232.D0, -7895059235.D0, 242396853.1D0
*,
     -2972611.439D0,15704.48260D0,-30.16036606D0/,
*
     S1,S2,S3,S4,S5,S6/144725228442.D0,2300535178.D0,
*
     18583304.74D0,99447.43394D0,376.9991397D0,1.D0/
DATA P1, P2, P3, P4, P5/1.D0, .183105D-2, -.3516396496D-4, .2457520174D-5
*,
```

с

с

с

* -.240337019D-6/, Q1,Q2,Q3,Q4,Q5/.04687499995D0,-.2002690873D-3

```
*,
```

```
* .8449199096D-5,-.88228987D-6,.105787412D-6/
```

```
IF(ABS(X).LT.8.)THEN
```

Y=X**2

```
BESSJ1=X*(R1+Y*(R2+Y*(R3+Y*(R4+Y*(R5+Y*R6)))))
```

```
* /(S1+Y*(S2+Y*(S3+Y*(S4+Y*(S5+Y*S6)))))
```

ELSE

AX = ABS(X)

Z=8./AX

Y=Z**2

XX=AX-2.356194491

```
BESSJ1=SQRT(.636619772/AX)*(COS(XX)*(P1+Y*(P2+Y*(P3+Y*(P4+Y
```

```
*P5))))-Z*SIN(XX)*(Q1+Y*(Q2+Y*(Q3+Y*(Q4+Y*Q5)))))
```

```
* *SIGN(1.,X)
```

ENDIF

RETURN

END

*

c c

с

```
FUNCTION BESSJ(N,X)
implicit real*8 (a-h,o-z)
PARAMETER (IACC=40,BIGN0=1.d10,BIGNI=1.d-10)
if (x .ge. 0.d0) then
ff = 1.d0
else
ff = (-1.d0)**n
```

```
end if
xx = abs(x)
if (n .eq. 0) then
    bessj = ff*bessj0(xx)
    return
  endif
  if (n .eq. 1) then
    bessj = ff*bessj1(xx)
    return
  endif
  TOX=2./Xx
  IF(Xx.GT.FLOAT(N))THEN
    BJM=BESSJO(Xx)
    BJ=BESSJ1(Xx)
    DO 11 J=1,N-1
      BJP=J*TOX*BJ-BJM
      BJM=BJ
      BJ=BJP
    CONTINUE
    BESSJ=ff*BJ
  ELSE
    M=2*((N+INT(SQRT(FLOAT(IACC*N))))/2)
    BESSJ=0.
```

JSUM=0

11

SUM=0.

BJP=0.

BJ=1.

DO 12 J=M,1,-1

BJM=J*TOX*BJ-BJP

BJP=BJ

BJ=BJM

IF(ABS(BJ).GT.BIGNO)THEN

BJ=BJ*BIGNI

BJP=BJP*BIGNI

BESSJ=BESSJ*BIGNI

SUM=SUM*BIGNI

ENDIF

IF(JSUM.NE.O)SUM=SUM+BJ

JSUM=1-JSUM

IF(J.EQ.N)BESSJ=BJP

12 CONTINUE

SUM=2.*SUM-BJ

BESSJ=ff*BESSJ/SUM

ENDIF

RETURN

END

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.

BIBLIOGRAPHY

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